

# bq25703A I2C Multi-Chemistry Battery Buck-Boost Charge Controller With System Power Monitor and Processor Hot Monitor

## 1 Features

- Charge 1- to 4-Cell Battery From Wide Range of Input Sources
  - 3.5-V to 24-V Input Operating Voltage
  - Supports USB2.0, USB 3.0, USB 3.1 (Type C), and USB\_PD Input Current Settings
  - Seamless Transition Between Buck and Boost Operation
  - Input Current and Voltage Regulation (IDPM and VDPM) Against Source Overload
- Power/Current Monitor for CPU Throttling
  - Comprehensive PROCHOT Profile, IMVP8 Compliant
  - Input and Battery Current Monitor
  - System Power Monitor, IMVP8 Compliant
- Narrow-VDC (NVDC) Power Path Management
  - Instant-On With No Battery or Deeply Discharged Battery
  - Battery Supplements System When Adapter is Fully-Loaded
  - Ideal Diode Operation in Supplement Mode
- Power Up USB Port From Battery (USB OTG)
  - Output 4.48-V to 20.8-V Compatible With USB PD
  - Output Current Limit up to 6.35 A
- 800-kHz or 1.2-MHz Programmable Switching Frequency for 1- $\mu$ H to 2.2- $\mu$ H Low Profile Inductor
- Host Control Interface for Flexible System Configuration
  - I2C (bq25703A) Port for Optimal System Performance and Status Reporting
  - Hardware Pin to Set Input Current Limit Without EC Control
- High Accuracy Regulation and Monitor
  - $\pm 0.5\%$  Charge Voltage Regulation
  - $\pm 2\%$  Input/Charge Current Regulation
  - $\pm 2\%$  Input/Charge Current Monitor
  - $\pm 5\%$  Power Monitor
- Safety
  - Thermal Shutdown
  - Input, System, Battery Overvoltage Protection
  - MOSFET Inductor Overcurrent Protection
- Low Battery Quiescent Current

- Input Current Optimizer (ICO) to Extract Max Input Power
- Charge Any Battery Chemistry: Li+, LiFePO<sub>4</sub>, NiCd, NiMH, Lead Acid
- Package: 32-Pin 4 x 4 WQFN

## 2 Applications

- Drones, Bluetooth Speakers, IP Cameras, Detachable, and Tablet PCs and Power Bank
- Industrial and Medical Equipment
- Portable Equipment With Rechargeable Batteries

## 3 Description

The bq25703A is a synchronous NVDC battery buck-boost charge controller, offering low component count, high efficiency solution for space-constraint, multi-chemistry battery charging applications.

The NVDC-1 configuration allows the system to be regulated at battery voltage, but not drop below system minimum voltage. The system keeps operating even when the battery is completely discharged or removed. When load power exceeds input source rating, the battery goes into supplement mode and prevents the input source from being overloaded.

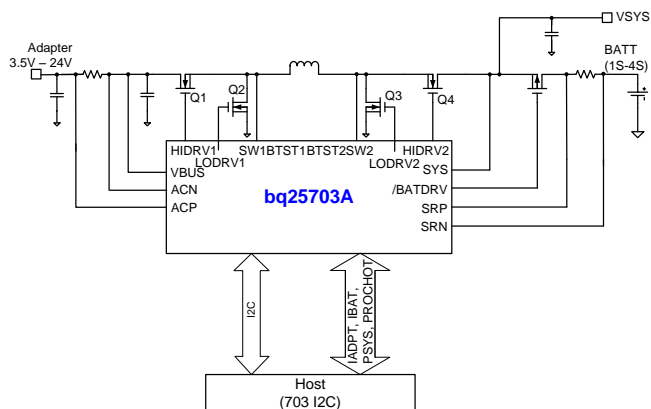
The bq25703A charges battery from a wide range of input sources including USB adapter, high voltage USB PD sources and traditional adapters.

### Device Information (1)

PART NUMBER	PACKAGE	BODY SIZE (NOM)
bq25703A	WQFN (32)	4.00 mm x 4.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

### Application Diagram



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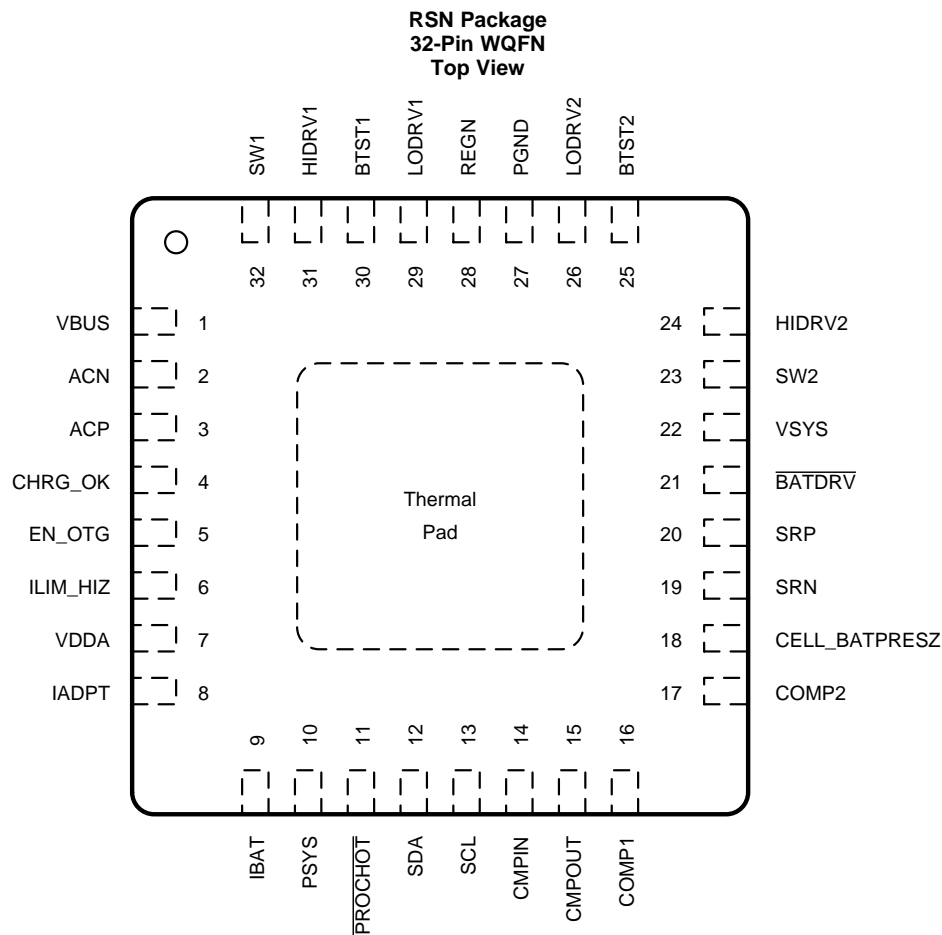
## 5 Description (Continued)

During power up, the charger sets converter to buck, boost or buck-boost configuration based on input source and battery conditions. The charger automatically transits among buck, boost and buck-boost configuration without host control.

In the absence of an input source, the bq25703A supports On-the-Go (OTG) function from 1- to 4-cell battery to generate 4.48 V to 20.8 V on VBUS. During OTG mode, the charger regulates output voltage and output current.

The bq25703A monitors adapter current, battery current and system power. The flexibly programmed PROCHOT output goes directly to CPU for throttle back when needed.

## 6 Pin Configuration and Functions



### Pin Functions

PIN		I/O	DESCRIPTION
NAME	NUMBER		
ACN	2	PWR	Input current sense resistor negative input. The leakage on ACP and ACN are matched. The series resistors on the ACP and ACN pins are placed between sense resistor and filter cap. Refer to <a href="#">Application and Implementation</a> for ACP/ACN filter design.
ACP	3	PWR	Input current sense resistor positive input. The leakage on ACP and ACN are matched. The series resistors on the ACP and ACN pins are placed between sense resistor and filter cap. Refer to <a href="#">Application and Implementation</a> for ACP/ACN filter design.
$\overline{\text{BATDRV}}$	21	O	P-channel battery FET (BATFET) gate driver output. It is shorted to VSYS to turn off the BATFET. It goes 10 V below VSYS to fully turn on BATFET. BATFET is in linear mode to regulate VSYS at minimum system voltage when battery is depleted. BATFET is fully on during fast charge and supplement mode.
BTST1	30	PWR	Buck mode high side power MOSFET driver power supply. Connect a 0.047- $\mu\text{F}$ capacitor between SW1 and BTST1. The bootstrap diode between REGN and BTST1 is integrated.
BTST2	25	PWR	Boost mode high side power MOSFET driver power supply. Connect a 0.047- $\mu\text{F}$ capacitor between SW2 and BTST2. The bootstrap diode between REGN and BTST2 is integrated.
CELL_BATPRESZ	18	I	Battery cell selection pin for 1–4 cell battery setting. CELL_BATPRESZ pin is biased from VDDA. CELL_BATPRESZ pin also sets SYSOVP threshold to 5 V for 1-cell, 12 V for 2-cell and 18.5 V for 3-cell. CELL_BATPRESZ pin is pulled below $V_{\text{CELL\_BATPRESZ\_FALL}}$ to indicate battery removal. The device exits LEARN mode, and disables charge. REG0x05/04() goes back to default.

**Pin Functions (continued)**

PIN		I/O	DESCRIPTION
NAME	NUMBER		
CHRG_OK	4	O	Open drain active high indicator to inform the system good power source is connected to the charger input. Connect to the pullup rail via 10-kΩ resistor. When VBUS rises above 3.5V or falls below 24.5V, CHRG_OK is HIGH after 50ms deglitch time. When VBUS is falls below 3.2 V or rises above 26 V, CHRG_OK is LOW.
CMPIN	14	I	Input of independent comparator. The independent comparator compares the voltage sensed on CMPIN pin to internal reference, and its output is on CMPOUT pin. Internal reference, output polarity and deglitch time is selectable by I2C. With polarity HIGH (REG0x30[6] = 1), place a resistor between CMPIN and CMPOUT to program hysteresis. With polarity LOW (REG0x30[6] = 0), the internal hysteresis is 100 mV. If the independent comparator is not in use, tie CMPIN to ground.
CMPOUT	15	I	Open-drain output of independent comparator. Place pullup resistor from CMPOUT to pullup supply rail. Internal reference, output polarity and deglitch time are selectable by I2C.
COMP2	17	I	Buck boost converter compensation pin 2. Refer to bq25700 EVM schematic for COMP2 pin RC network.
COMP1	16	I	Buck boost converter compensation pin 1. Refer to bq25700 EVM schematic for COMP1 pin RC network.
EN_OTG	5	I	Active HIGH to enable OTG mode. When EN_OTG pin is HIGH and REG0x35[4] is HIGH, OTG can be enabled, refer to <i>USB On-The-Go (OTG)</i> for details of how to enable OTG function
HIDRV1	31	O	Buck mode high side power MOSFET (Q1) driver. Connect to high side n-channel MOSFET gate.
HIDRV2	24	O	Boost mode high side power MOSFET(Q4) driver. Connect to high side n-channel MOSFET gate.
IADPT	8	O	Buffered adapter current output. $V_{(IADP)} = 20 \text{ or } 40 \times (V_{(ACP)} - V_{(ACN)})$ . With ratio selectable in REG0x00[4]. Place a resistor from the IADPT pin to ground corresponding to inductor in use. For 2.2 μH, the resistor is 137 kΩ. Place 100-pF or less ceramic decoupling capacitor from IADPT pin to ground. IADPT output voltage is clamped below 3.3 V.
IBAT	9	O	Buffered battery current selected by I2C. $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRP)} - V_{(SRN)})$ for charge current, or $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRN)} - V_{(SRP)})$ for discharge current, with ratio selectable in REG0x00[3]. Place 100-pF or less ceramic decoupling capacitor from IBAT pin to ground. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V.
ILIM_HIZ	6	I	Input current limit input. Program ILIM_HIZ voltage by connecting a resistor divider from supply rail to ILIM_HIZ pin to ground. The pin voltage is calculated as: $V_{(ILIM\_HIZ)} = 1 \text{ V} + 40 \times \text{IDPM} \times \text{RAC}$ , in which IDPM is the target input current. The input current limit used by the charger is the lower setting of ILIM_HIZ pin and REG0x0F() and REG0x0E(). When the pin voltage is below 0.4 V, the device enters Hi-Z mode with low quiescent current. When the pin voltage is above 0.8 V, the device is out of Hi-Z mode.
LODRV1	29	O	Buck mode low side power MOSFET (Q2) driver. Connect to low side n-channel MOSFET gate.
LODRV2	26	O	Boost mode low side power MOSFET (Q3) driver. Connect to low side n-channel MOSFET gate.
PGND	27	GND	Device power ground.
$\overline{\text{PROCHOT}}$	11	O	Active low open drain output of processor hot indicator. It monitors adapter input current, battery discharge current, and system voltage. After any event in the PROCHOT profile is triggered, a minimum 10-ms pulse is asserted. The pulse width is adjustable in REG0x36[5:2].
PSYS	10	O	Current mode system power monitor. The output current is proportional to the total power from the adapter and battery. The gain is selectable through I2C. Place resistor from PSYS to ground to generate output voltage. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V. Place a capacitor in parallel with resistor for filtering.
REGN	28	PWR	6-V linear regulator output supplied from VBUS or VSYS. The LDO is active when VBUS above $V_{VBUS\_CONVEN}$ . Connect a 2.2- or 3.3-μF ceramic capacitor from REGN to power ground. REGN pin output is for power stage gate drive.
SCL	13	I	I2C clock input. Connect to clock line from the host controller or smart battery. Connect a 10-kΩ pullup resistor according to I2C specifications.
SDA	12	I/O	I2C open-drain data I/O. Connect to data line from the host controller or smart battery. Connect a 10-kΩ pullup resistor according to I2C specifications.

**Pin Functions (continued)**

PIN		I/O	DESCRIPTION
NAME	NUMBER		
SRN	19	PWR	Charge current sense resistor negative input. SRN pin is for battery voltage sensing as well. Connect SRN pin with optional 0.1- $\mu$ F ceramic capacitor to GND for common-mode filtering. Connect a 0.1- $\mu$ F ceramic capacitor from SRP to SRN to provide differential mode filtering. The leakage current on SRP and SRN are matched. For reverse battery plug-in protection, 10- $\Omega$ series resistors are placed on SRP and SRN.
SRP	20	PWR	Charge current sense resistor positive input. Connect 0.1- $\mu$ F ceramic capacitor from SRP to SRN to provide differential mode filtering. The leakage current on SRP and SRN are matched. For reverse battery plug-in protection, 10- $\Omega$ series resistors are placed on SRP and SRN. Connect SRP pin with optional 0.1- $\mu$ F ceramic capacitor to GND for common-mode filtering.
SW1	32	PWR	Buck mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.
SW2	23	PWR	Boost mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.
VBUS	1	PWR	Charger input voltage. An input low pass filter of 1 $\Omega$ and 0.47 $\mu$ F (minimum) is recommended.
VDDA	7	PWR	Internal reference bias pin. Connect a 10- $\Omega$ resistor from REGN to VDDA and a 1- $\mu$ F ceramic capacitor from VDDA to power ground.
VSYS	22	PWR	Charger system voltage sensing. The system voltage regulation limit is programmed in REG0x05/04() and REG0X0D/0C().
Thermal pad	–	–	Exposed pad beneath the IC. Analog ground and power ground star-connected near the IC's ground. Always solder thermal pad to the board, and have vias on the thermal pad plane connecting to power ground planes. It also serves as a thermal pad to dissipate the heat.

## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)(2)</sup>

		MIN	MAX	UNIT
Voltage	SRN, SRP, ACN, ACP, VBUS, VSYS, $\overline{\text{BATDRV}}$	-0.3	30	V
	SW1, SW2	-2.0	30	
	BTST1, BTST2, HIDRV1, HIDRV2	-0.3	36	
	LODRV1, LODRV2 (2% duty cycle)	-4.0	7	
	HIDRV1, HIDRV2 (2% duty cycle)	-4.0	36	
	SW1, SW2 (2% duty cycle)	-4.0	30	
	SDA, SCL, REGN, CHRГ_OK, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT, EN_OTG	-0.3	7	
	$\overline{\text{PROCHOT}}$	-0.3	5.5	
	IADPT, IBAT, PSYS	-0.3	3.6	
Differential voltage	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	-0.3	7	V
	SRP-SRN, ACP-ACN	-0.5	0.5	
Junction temperature range, T <sub>J</sub>		-40	155	°C
Storage temperature, T <sub>stg</sub>		-40	155	°C

- Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- All voltages are with respect to GND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages.

### 7.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	

- JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Voltage	ACN, ACP, VBUS	0	24	V
	SRN, SRP, VSYS, $\overline{\text{BATDRV}}$	0	19.2	
	SW1, SW2	-2	24	
	BTST1, BTST2, HIDRV1, HIDRV2	0	30	
	SDA, SCL, REGN, CHRГ_OK, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT	0	6.5	
	$\overline{\text{PROCHOT}}$	0	5.3	
	IADPT, IBAT, PSYS	0	3.3	
Differential voltage	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	0	6.5	V
	SRP-SRN, ACP-ACN	-0.35	0.35	
Junction temperature, T <sub>J</sub>		-40	125	°C
Operating free-air temperature, T <sub>A</sub>		-40	85	°C

## 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		bq25703A	
		RSN (WQFN)	
		32 PINS	
Symbol	Description	Value	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	37.2	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	26.1	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	7.8	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	0.3	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	7.8	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	2.3	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 7.5 Electrical Characteristics

over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{INPUT\_OP}$	Input voltage operating range	3.5		26	V
<b>REGULATION ACCURACY</b>					
<b>MAX SYSTEM VOLTAGE REGULATION</b>					
$V_{SYSMAX\_RNG}$	System voltage regulation, measured on $V_{SYS}$	1.024		19.2	V
$V_{SYSMAX\_ACC}$	System voltage regulation accuracy (charge disable)	REG0x05/04() = 0x41A0H (16.800 V)	$V_{SRN} + 160$ mV		V
			-2%	2%	
		REG0x05/04() = 0x3130H (12.592 V)	$V_{SRN} + 160$ mV		V
			-2%	2%	
	REG0x05/04() = 0x20D0H (8.400 V)	$V_{SRN} + 160$ mV		V	
		-3%	3%		
	REG0x05/04() = 0x1060H (4.192 V)	$V_{SRN} + 160$ mV		V	
		-3%	3%		
<b>MINIMUM SYSTEM VOLTAGE REGULATION</b>					
$V_{SYSMIN\_RNG}$	System voltage regulation, measured on $V_{SYS}$	1.024		19.2	V
$V_{SYSMIN\_REG\_ACC}$	Minimum system voltage regulation accuracy (charge enable, VBAT below REG0x0D/0C() setting)	REG0x0D/0C() = 0x3000H	12.288		V
			-2%	2%	
		REG0x0D/0C() = 0x2400H	9.216		V
			-2%	2%	
	REG0x0D/0C() = 0x1800H	6.144		V	
		-3%	3%		
	REG0x0D/0C() = 0x0E00H	3.584		V	
		-3%	4%		
<b>CHARGE VOLTAGE REGULATION</b>					
$V_{BAT\_RNG}$	Battery voltage regulation	1.024		19.2	V
$V_{BAT\_REG\_ACC}$	Battery voltage regulation accuracy (charge enable) (0°C to 85°C)	REG0x05/04() = 0x41A0H	16.8		V
			-0.5%	0.5%	
		REG0x05/04() = 0x3130H	12.592		V
			-0.5%	0.5%	
	REG0x05/04() = 0x20D0H	8.4		V	
		-0.6%	0.6%		
	REG0x05/04() = 0x1060H	4.192		V	
		-1.1%	1.2%		



## Electrical Characteristics (continued)

over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>CHARGE CURRENT REGULATION IN FAST CHARGE</b>							
$V_{\text{IREG\_CHG\_RNG}}$	Charge current regulation differential voltage range	$V_{\text{IREG\_CHG}} = V_{\text{SRP}} - V_{\text{SRN}}$	0		81.28	mV	
$I_{\text{CHRG\_REG\_ACC}}$	Charge current regulation accuracy 10-m $\Omega$ current sensing resistor, VBAT above 0x0D/0C() setting (0°C to 85°C)	REG0x03/02() = 0x1000H		4096		mA	
			-3%		2%		
		REG0x03/02() = 0x0800H		2048		3%	mA
			-4%				
		REG0x03/02() = 0x0400H		1024		6%	mA
				512		mA	
			-12%		12%		
<b>CHARGE CURRENT REGULATION IN LDO MODE</b>							
$I_{\text{CLAMP}}$	Pre-charge current clamp	CELL 2s-4s		384		mA	
		CELL 1 s, $V_{\text{SRN}} < 3\text{ V}$		384		mA	
		CELL 1 s, $3\text{ V} < V_{\text{SRN}} < V_{\text{SYSMIN}}$		2		A	
$I_{\text{PRECHRG\_REG\_ACC}}$	Pre-charge current regulation accuracy with 10- $\Omega$ SRP/SRN series resistor, VBAT below REG0x0D/0C() setting (0°C to 85°C)	REG0x03/02() = 0x0180H		384		mA	
		2S-4S	-15%		15%		
		1S	-25%		25%		
		REG0x03/02() = 0x0100H		256		mA	
		2S-4S	-20%		20%		
		1S	-35%		35%		
		REG0x03/02() = 0x00C0H		192		mA	
		2S-4S	-25%		25%		
		1S	-50%		50%		
				128		mA	
			-30%		30%		
$I_{\text{LEAK\_SRP\_SRN}}$	SRP, SRN leakage current mismatch (0°C to 85°C)		-12		10	$\mu\text{A}$	
<b>INPUT CURRENT REGULATION</b>							
$V_{\text{IREG\_DPM\_RNG}}$	Input current regulation differential voltage range	$V_{\text{IREG\_DPM}} = V_{\text{ACP}} - V_{\text{ACN}}$	0.5		64	mV	
$I_{\text{DPM\_REG\_ACC}}$	Input current regulation accuracy (-40°C to 105°C) with 10- $\Omega$ ACP/ACN series resistor	REG0x0F/0E() = 0x4FFFH		3820		4000	mA
		REG0x0F/0E() = 0x3BFFH		2830		3000	mA
		REG0x0F/0E() = 0x1DFFH		1350		1500	mA
		REG0x0F/0E() = 0x09FFH		340		500	mA
$I_{\text{LEAK\_ACP\_ACN}}$	ACP, ACN leakage current mismatch		-16		10	$\mu\text{A}$	
$V_{\text{IREG\_DPM\_RNG\_ILIM}}$	Voltage Range for input current regulation		1		4	V	
$I_{\text{DPM\_REG\_ACC\_ILIM}}$	Input Current Regulation Accuracy on ILIM_HIZ pin $V_{\text{ILIM\_HIZ}} = 1\text{ V} + 40 \times I_{\text{DPM}} \times R_{\text{AC}}$ , with 10- $\Omega$ ACP/ACN series resistor	$V_{\text{ILIM\_HIZ}} = 2.6\text{ V}$		3800	4000	4200	mA
		$V_{\text{ILIM\_HIZ}} = 2.2\text{ V}$		2800	3000	3200	mA
		$V_{\text{ILIM\_HIZ}} = 1.6\text{ V}$		1300	1500	1700	mA
		$V_{\text{ILIM\_HIZ}} = 1.2\text{ V}$		300	500	700	mA
$I_{\text{LEAK\_ILIM}}$	$I_{\text{LIM\_HIZ}}$ pin leakage		-1		1	$\mu\text{A}$	
<b>INPUT VOLTAGE REGULATION</b>							
$V_{\text{IREG\_DPM\_RNG}}$	Input voltage regulation range	Voltage on VBUS	3.2		19.52	V	

## Electrical Characteristics (continued)

 over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
$V_{\text{DPM\_REG\_ACC}}$	Input voltage regulation accuracy	REG0x07/06()=0x3C80H		18688	mV	
			-2%	2%		
		REG0x07/06()=0x1E00H		10880	mV	
			-2.5%	2.5%		
		REG0x07/06()=0x0500H		4480	mV	
		-3%	5%			
<b>OTG CURRENT REGULATION</b>						
$V_{\text{IOTG\_REG\_RNG}}$	Input current regulation differential voltage range	$V_{\text{IREG\_DPM}} = V_{\text{ACP}} - V_{\text{ACN}}$	0	81.28	mV	
$I_{\text{OTG\_ACC}}$	Input current regulation accuracy with 50-mA LSB, with 10- $\Omega$ ACP/ACN series resistor	REG0x09/08() = 0x3C00H	2800	3000	3200	mA
		REG0x09/08() = 0x1E00H	1300	1500	1700	mA
		REG0x09/08() = 0x0A00H	300	500	700	mA
<b>OTG VOLTAGE REGULATION</b>						
$V_{\text{IREG\_DPM\_RNG}}$	Input voltage regulation range	Voltage on VBUS	4.48	20.8	V	
$V_{\text{OTG\_REG\_ACC}}$	OTG voltage regulation accuracy	REG0x0B/0A()=0x3CC0H		20.032	V	
			-2%	2%		
		REG0x0B/0A()=0x1D80H		12.032	V	
			-2%	2%		
		REG0x0B/0A()=0x0240H		5.056	V	
		-3%	3%			
<b>REFERENCE AND BUFFER</b>						
<b>REGN REGULATOR</b>						
$V_{\text{REGN\_REG}}$	REGN regulator voltage (0 mA–60 mA)	$V_{\text{VBUS}} = 10\text{ V}$	5.7	6	6.3	V
$V_{\text{DROPOUT}}$	REGN voltage in drop out mode	$V_{\text{VBUS}} = 5\text{ V}$ , $I_{\text{LOAD}} = 20\text{ mA}$	3.8	4.3	4.6	V
$I_{\text{REGN\_LIM\_Charging}}$	REGN current limit when converter is enabled	$V_{\text{VBUS}} = 10\text{ V}$ , force $V_{\text{REGN}} = 4\text{ V}$	50	65		mA
$C_{\text{REGN}}$	REGN output capacitor required for stability	$I_{\text{LOAD}} = 100\text{ }\mu\text{A}$ to 50 mA	2.2			$\mu\text{F}$
$C_{\text{VDDA}}$	REGN output capacitor required for stability	$I_{\text{LOAD}} = 100\text{ }\mu\text{A}$ to 50 mA	1			$\mu\text{F}$
<b>QUIESCENT CURRENT</b>						
$I_{\text{BAT\_BATFET\_ON}}$	System powered by battery. BATFET on. $I_{\text{SRN}} + I_{\text{SRP}} + I_{\text{SW2}} + I_{\text{BTST2}} + I_{\text{SW1}} + I_{\text{BTST1}} + I_{\text{ACP}} + I_{\text{ACN}} + I_{\text{VBUS}} + I_{\text{VSY}} + I_{\text{VDDA}}$	$V_{\text{BAT}} = 18\text{ V}$ , REG0x01[7] = 1, in low power mode		22	45	$\mu\text{A}$
		$V_{\text{BAT}} = 18\text{ V}$ , REG0x01[7] = 0, REG0x31[6:5] = 01, REGN off		105	175	$\mu\text{A}$
		$V_{\text{BAT}} = 18\text{ V}$ , REG0x01[7] = 0, REG0x31[6:5] = 10, REGN off		60	90	$\mu\text{A}$
		$V_{\text{BAT}} = 18\text{ V}$ , REG0x01[7] = 0, REG0x31[4] = 0, REGN on, EN_PSYS		860	1150	$\mu\text{A}$
		$V_{\text{BAT}} = 18\text{ V}$ , REG0x01[7] = 0, REG0x = 1, REGN on		960	1250	$\mu\text{A}$
$I_{\text{AC\_SW\_LIGHT\_buck}}$	Input current during PFM in buck mode, no load, $I_{\text{VBUS}} + I_{\text{ACP}} + I_{\text{ACN}} + I_{\text{VSY}} + I_{\text{SRP}} + I_{\text{SRN}} + I_{\text{SW1}} + I_{\text{BTST}} + I_{\text{SW2}} + I_{\text{BTST2}}$	$V_{\text{IN}} = 20\text{ V}$ , $V_{\text{BAT}} = 12.6\text{ V}$ , 3 s, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.2		mA

## Electrical Characteristics (continued)

over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
$I_{AC\_SW\_LIGHT\_boost}$	Input current during PFM in boost mode, no load, $I_{VBUS} + I_{ACP} + I_{ACN} + I_{VSY} + I_{SRP} + I_{SRN} + I_{SW1} + I_{BTST2} + I_{SW2} + I_{BTST2}$	$V_{IN} = 5\text{ V}$ , $V_{BAT} = 8.4\text{ V}$ , 2 s, $REG0x01[2] = 0$ ; MOSFET $Q_g = 4\text{ nC}$	2.7		mA		
$I_{AC\_SW\_LIGHT\_buckboost}$	Input current during PFM in buck boost mode, no load, $I_{VBUS} + I_{ACP} + I_{ACN} + I_{VSY} + I_{SRP} + I_{SRN} + I_{SW1} + I_{BTST1} + I_{SW2} + I_{BTST2}$	$V_{IN} = 12\text{ V}$ , $V_{BAT} = 12\text{ V}$ , $REG0x01[2] = 0$ ; MOSFET $Q_g = 4\text{ nC}$	2.4		mA		
$I_{OTG\_STANDBY}$	Quiescent current during PFM in OTG mode $I_{VBUS} + I_{ACP} + I_{ACN} + I_{VSY} + I_{SRP} + I_{SRN} + I_{SW1} + I_{BTST2} + I_{SW2} + I_{BTST2}$	$V_{BAT} = 8.4\text{ V}$ , $V_{BUS} = 5\text{ V}$ , 800-kHz switching frequency, MOSFET $Q_g = 4\text{ nC}$	3		mA		
		$V_{BAT} = 8.4\text{ V}$ , $V_{BUS} = 12\text{ V}$ , 800-kHz switching frequency, MOSFET $Q_g = 4\text{ nC}$	4.2				
		$V_{BAT} = 8.4\text{ V}$ , $V_{BUS} = 20\text{ V}$ , 800-kHz switching frequency, MOSFET $Q_g = 4\text{ nC}$	6.2				
$V_{ACP/N\_OP}$	Input common mode range	Voltage on ACP/ACN		3.8	26	V	
$V_{IADPT\_CLAMP}$	$I_{ADPT}$ output clamp voltage			3.1	3.2	3.3	V
$I_{IADPT}$	$I_{ADPT}$ output current				1	mA	
$A_{IADPT}$	Input current sensing gain	$V_{(IADPT)} / V_{(ACP-ACN)}$ , $REG0x00[4] = 0$	20		V/V		
		$V_{(IADPT)} / V_{(ACP-ACN)}$ , $REG0x00[4] = 1$	40		V/V		
$V_{IADPT\_ACC}$	Input current monitor accuracy	$V_{(ACP-ACN)} = 40.96\text{ mV}$	-2%		2%		
		$V_{(ACP-ACN)} = 20.48\text{ mV}$	-3%		3%		
		$V_{(ACP-ACN)} = 10.24\text{ mV}$	-6%		6%		
		$V_{(ACP-ACN)} = 5.12\text{ mV}$	-10%		10%		
$C_{IADPT\_MAX}$	Maximum output load capacitance				100	pF	
$V_{SRP/N\_OP}$	Battery common mode range	Voltage on SRP/SRN		2.5	18	V	
$V_{IBAT\_CLAMP}$	IBAT output clamp voltage			3.05	3.2	3.3	V
$I_{IBAT}$	IBAT output current				1	mA	
$A_{IBAT}$	Charge and discharge current sensing gain on IBAT pin	$V_{(IBAT)} / V_{(SRN-SRP)}$ , $REG0x00[3] = 0$ ,		8	V/V		
		$V_{(IBAT)} / V_{(SRN-SRP)}$ , $REG0x00[3] = 1$ ,		16	V/V		
$I_{IBAT\_CHG\_ACC}$	Charge and discharge current monitor accuracy on IBAT pin	$V_{(SRN-SRP)} = 40.96\text{ mV}$	-2%		2%		
		$V_{(SRN-SRP)} = 20.48\text{ mV}$	-3%		4%		
		$V_{(SRN-SRP)} = 10.24\text{ mV}$	-6%		6%		
		$V_{(SRN-SRP)} = 5.12\text{ mV}$	-12%		12%		
$C_{IBAT\_MAX}$	Maximum output load capacitance				100	pF	
<b>SYSTEM POWER SENSE AMPLIFIER</b>							
$V_{PSYS}$	PSYS output voltage range			0	3.3	V	
$I_{PSYS}$	PSYS output current			0	160	$\mu\text{A}$	
$A_{PSYS}$	PSYS system gain	$V_{(PSYS)} / (P_{(IN)} + P_{(BAT)})$ , $REG0x31[1] = 1$		1		$\mu\text{A/W}$	

**Electrical Characteristics (continued)**

 over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>PSYS_ACC</sub>	PSYS gain accuracy (REG0x31[1] = 1)	Adapter only with system power = 19.5 V / 45 W, T <sub>A</sub> = 0 to 85°C	-5%		5%	
		Adapter only with system power = 19.5 V / 45 W, T <sub>A</sub> = -40 to 125°C	-7%		6%	
		Battery only with system power = 11 V / 44 W, T <sub>A</sub> = 0 to 85°C	-5%		5%	
		Battery only with system power = 11 V / 44 W, T <sub>A</sub> = -40 to 125°C	-6%		6%	
V <sub>PSYS_CLAMP</sub>	PSYS clamp voltage		3		3.3	V
<b>COMPARATOR</b>						
<b>VBUS UNDER VOLTAGE LOCKOUT COMPARATOR</b>						
V <sub>VBUS_UVLOZ</sub>	VBUS undervoltage rising threshold	VBUS rising	2.34	2.55	2.77	V
V <sub>VBUS_UVLO</sub>	VBUS undervoltage falling threshold	VBUS falling	2.2	2.4	2.6	V
V <sub>VBUS_UVLO_HYST</sub>	VBUS undervoltage hysteresis			150		mV
V <sub>VBUS_CONVEN</sub>	VBUS converter enable rising threshold	VBUS rising	3.2	3.5	3.9	V
V <sub>VBUS_CONVENZ</sub>	VBUS converter enable falling threshold	VBUS falling	2.9	3.2	3.5	V
V <sub>VBUS_CONVEN_HYST</sub>	VBUS converter enable hysteresis			400		mV
<b>BATTERY UNDER VOLTAGE LOCKOUT COMPARATOR</b>						
V <sub>VBAT_UVLOZ</sub>	VBAT undervoltage rising threshold	VSRN rising	2.35	2.55	2.75	V
V <sub>VBAT_UVLO</sub>	VBAT undervoltage falling threshold	VSRN falling	2.2	2.4	2.6	V
V <sub>VBAT_UVLO_HYST</sub>	VBAT undervoltage hysteresis			150		mV
V <sub>VBAT_OTGEN</sub>	VBAT OTG enable rising threshold	VSRN rising	3.3	3.55	3.75	V
V <sub>VBAT_OTGENZ</sub>	VBAT OTG enable falling threshold	VSRN falling	3	3.2	3.4	V
V <sub>VBAT_OTGEN_HYST</sub>	VBAT OTG enable hysteresis			350		mV
<b>VBUS UNDER VOLTAGE COMPARATOR (OTG MODE)</b>						
V <sub>VBUS_OTG_UV</sub>	VBUS undervoltage falling threshold	As percentage of REG0x07/06()		85.0%		
t <sub>VBUS_OTG_UV</sub>	VBUS undervoltage deglitch time			7		ms
<b>VBUS OVER VOLTAGE COMPARATOR (OTG MODE)</b>						
V <sub>VBUS_OTG_OV</sub>	VBUS overvoltage rising threshold	As percentage of REG0x07/06()		105%		
t <sub>VBUS_OTG_OV</sub>	VBUS Over-Voltage Deglitch Time			10		ms
V <sub>BAT_SYSMIN_RISE</sub>	LDO mode to fast charge mode threshold, VSRN rising	as percentage of 0x0D/0C()	98%	100%	102%	
V <sub>BAT_SYSMIN_FALL</sub>	LDO mode to fast charge mode threshold, VSRN falling	as percentage of 0x0D/0C()		97.5%		

## Electrical Characteristics (continued)

over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{BAT\_SYSMIN\_HYST}}$	Fast charge mode to LDO mode threshold hysteresis	as percentage of 0x0D/0C()		2.5%		
<b>BATTERY LOWV COMPARATOR (Pre-charge to Fast Charge Threshld for 1S)</b>						
$V_{\text{BATLV\_FALL}}$	BATLOWV falling threshold	1 s		2.80		V
$V_{\text{BATLV\_RISE}}$	BATLOWV rising threshold			3.00		V
$V_{\text{BATLV\_RHYST}}$	BATLOWV hysteresis			200		mV
<b>INPUT OVER-VOLTAGE COMPARATOR (ACOV)</b>						
$V_{\text{ACOV\_RISE}}$	VBUS overvoltage rising threshold	VBUS rising	25	26	27	V
$V_{\text{ACOV\_FALL}}$	VBUS overvoltage falling threshold	VBUS falling	24	24.5	25	V
$V_{\text{ACOV\_HYST}}$	VBUS overvoltage hysteresis			1.5		V
$t_{\text{ACOV\_RISE\_DEG}}$	VBUS overvoltage rising deglitch	VBUS rising to stop converter		100		$\mu\text{s}$
$t_{\text{ACOV\_FALL\_DEG}}$	VBUS overvoltage falling deglitch	VBUS falling to start converter		1		ms
<b>INPUT OVER CURRENT COMPARATOR (ACOC)</b>						
$V_{\text{ACOC}}$	ACP to ACN rising threshold, w.r.t. ILIM2 in REG0x37[7:3]	Voltage across input sense resistor rising, Reg0x32[2] = 1	195%	210%	225%	
$V_{\text{ACOC\_FLOOR}}$	Measure between ACP and ACN	Set IDPM to minimum	44	50	56	mV
$V_{\text{ACOC\_CEILING}}$	Measure between ACP and ACN	Set IDPM to maximum	172	180	188	mV
$t_{\text{ACOC\_DEG\_RISE}}$	Rising deglitch time	Deglitch time to trigger ACOC		250		$\mu\text{s}$
$t_{\text{ACOC\_RELAX}}$	Relax time	Relax time before converter starts again		250		ms
<b>SYSTEM OVER-VOLTAGE COMPARATOR (SYSOVP)</b>						
$V_{\text{SYSOVP\_RISE}}$	System overvoltage rising threshold to turn off converter	1 s	4.85	5	5.1	V
		2 s	11.7	12	12.2	
		3 s	19	19.5	20	
		4 s	19	19.5	20	
$V_{\text{SYSOVP\_FALL}}$	System overvoltage falling threshold	1 s		4.8		V
		2 s		11.5		
		3 s		19		
		4 s		19		
$I_{\text{SYSOVP}}$	Discharge current when SYSOVP stop switching was triggered	on SYS		20		mA
<b>BAT OVER-VOLTAGE COMPARATOR (BATOVP)</b>						
$V_{\text{BATOVP\_RISE}}$	Overvoltage rising threshold as percentage of $V_{\text{BAT\_REG}}$ in REG0x05/04()	1 s, 4.2 V	102.5%	104%	106%	
		2 s - 4 s	102.5%	104%	105%	
$V_{\text{BATOVP\_FALL}}$	Overvoltage falling threshold as percentage of $V_{\text{BAT\_REG}}$ in REG0x05/04()	1 s	100%	102%	104%	
		2 s - 4 s	100%	102%	103%	
$V_{\text{BATOVP\_HYST}}$	Overvoltage hysteresis as percentage of $V_{\text{BAT\_REG}}$ in REG0x05/04()	1 s		2%		
		2 s - 4 s		2%		
$I_{\text{BATOVP}}$	Discharge current during BATOVP	on SRP and SRN		20		mA

**Electrical Characteristics (continued)**

 over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{BATOVP\_RISE}}$	Overvoltage rising deglitch to turn off BATDRV to disable charge			20		ms
<b>CONVERTER OVER-CURRENT COMPARATOR (Q2)</b>						
VOCP_limit_Q2	Converter Over-Current Limit	Reg0x32[5]=1		150		mV
		Reg0x32[5]=0		210		
VOCP_limit_SYSSH ORT_Q2	System Short or SRN<2.5 V	Reg0x32[5]=1		45		mV
		Reg0x32[5]=0		60		
<b>CONVERTER OVER-CURRENT COMPARATOR (ACX)</b>						
VOCP_limit_Q3	Converter Over-Current Limit	Reg0x32[4]=1		150		mV
		Reg0x32[4]=0		280		
VOCP_limit_SYSSH ORT_Q3	System Short or SRN<2.5 V	Reg0x32[4]=1		90		mV
		Reg0x32[4]=0		150		
<b>THERMAL SHUTDOWN COMPARATOR</b>						
$T_{\text{SHUT\_RISE}}$	Thermal shutdown rising temperature	Temperature increasing		155		$^\circ\text{C}$
$T_{\text{SHUT\_FALL}}$	Thermal shutdown falling temperature	Temperature reducing		135		$^\circ\text{C}$
$T_{\text{SHUT\_HYS}}$	Thermal shutdown hysteresis			20		$^\circ\text{C}$
$t_{\text{SHUT\_RDEG}}$	Thermal shutdown rising deglitch			100		$\mu\text{s}$
$t_{\text{SHUT\_FHYS}}$	Thermal shutdown falling deglitch			12		ms
<b>VSYS PROCHOT COMPARATOR</b>						
$V_{\text{SYS\_PROCHOT}}$	$V_{\text{SYS}}$ threshold falling threshold	Reg0x36[7:6] = 00, 1 s		2.85		V
		Reg0x36[7:6] = 00, 2–4 s		5.75		V
		Reg0x36[7:6] = 01, 1 s	2.95	3.1	3.25	V
		Reg0x36[7:6] = 01, 2–4 s	5.8	5.95	6.1	V
		Reg0x36[7:6] = 10, 1 s		3.3		V
		Reg0x36[7:6] = 10, 2–4 s		6.25		V
		Reg0x36[7:6] = 11, 1 s		3.5		V
		Reg0x36[7:6] = 11, 2–4 s		6.5		V
$t_{\text{SYS\_PRO\_RISE\_DEG}}$	$V_{\text{SYS}}$ rising deglitch for throttling			8		$\mu\text{s}$
<b>ICRIT PROCHOT COMPARATOR</b>						
$V_{\text{ICRIT\_PRO}}$	Input current rising threshold for throttling as 10% above ILIM2 (REG0x37[7:3])	Reg0x37[7:3] = 00000	105%	110%	116%	
		Reg0x37[7:3] = 01001	142%	150%	156%	
<b>INOM PROCHOT COMPARATOR</b>						
$V_{\text{INOM\_PRO}}$	INOM rising threshold as 10% above IIN (REG0x0F/0E())		105%	110%	116%	
<b>IDCHG PROCHOT COMPARATOR</b>						
$V_{\text{IDCHG\_PRO}}$	IDCHG threshold for throttling for IDSCHG of 6 A	Reg0x39[7:2] = 001100		6272		mA
			95%		102%	
<b>INDEPENDENT COMPARATOR</b>						
$V_{\text{INDEP\_CMP}}$	Independent comparator threshold	Reg0x30[7] = 1, CMPIN falling	1.17	1.2	1.23	V
		Reg0x30[7] = 0, CMPIN falling	2.27	2.3	2.33	V

## Electrical Characteristics (continued)

over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{INDEP\_CMP\_HYS}}$	Independent comparator hysteresis	Reg0x06[6] = 0, CMPIN falling		100		mV
<b>POWER MOSFET DRIVER</b>						
<b>PWM OSCILLATOR AND RAMP</b>						
$F_{\text{SW}}$	PWM switching frequency	Reg0x01[1] = 0	1020	1200	1380	kHz
		Reg0x01[1] = 1	680	800	920	kHz
<b>BATFET GATE DRIVER (BATDRV)</b>						
$V_{\text{BATDRV\_ON}}$	Gate drive voltage on BATFET		8.5	10	11.5	V
$V_{\text{BATDRV\_DIODE}}$	Drain-source voltage on BATFET during ideal diode operation			30		mV
$R_{\text{BATDRV\_ON}}$	Measured by sourcing 10- $\mu\text{A}$ current to BATDRV		3	4	6	k $\Omega$
$R_{\text{BATDRV\_OFF}}$	Measured by sinking 10- $\mu\text{A}$ current from BATDRV			1.2	2.1	k $\Omega$
<b>PWM HIGH SIDE DRIVER (HIDRV Q1)</b>						
$R_{\text{DS\_HI\_ON\_Q1}}$	High side driver (HSD) turnon resistance	$V_{\text{BTST1}} - V_{\text{SW1}} = 5\text{ V}$		6		$\Omega$
$R_{\text{DS\_HI\_OFF\_Q1}}$	High side driver turnoff resistance	$V_{\text{BTST1}} - V_{\text{SW1}} = 5\text{ V}$		1.3	2.2	$\Omega$
$V_{\text{BTST1\_REFRESH}}$	Bootstrap refresh comparator falling threshold voltage	$V_{\text{BTST1}} - V_{\text{SW1}}$ when low side refresh pulse is requested	3.2	3.7	4.6	V
<b>PWM HIGH SIDE DRIVER (HIDRV Q4)</b>						
$R_{\text{DS\_HI\_ON\_Q4}}$	High side driver (HSD) turnon resistance	$V_{\text{BTST2}} - V_{\text{SW2}} = 5\text{ V}$		6		$\Omega$
$R_{\text{DS\_HI\_OFF\_Q4}}$	High side driver turnoff resistance	$V_{\text{BTST2}} - V_{\text{SW2}} = 5\text{ V}$		1.5	2.4	$\Omega$
$V_{\text{BTST2\_REFRESH}}$	Bootstrap refresh comparator falling threshold voltage	$V_{\text{BTST2}} - V_{\text{SW2}}$ when low side refresh pulse is requested	3.3	3.7	4.6	V
<b>PWM LOW SIDE DRIVER (LODRV Q2)</b>						
$R_{\text{DS\_LO\_ON\_Q2}}$	Low side driver (LSD) turnon resistance	$V_{\text{BTST1}} - V_{\text{SW1}} = 5.5\text{ V}$		6		$\Omega$
$R_{\text{DS\_LO\_OFF\_Q2}}$	Low side driver turnoff resistance	$V_{\text{BTST1}} - V_{\text{SW1}} = 5.5\text{ V}$		1.7	2.6	$\Omega$
<b>PWM LOW SIDE DRIVER (LODRV Q3)</b>						
$R_{\text{DS\_LO\_ON\_Q3}}$	Low side driver (LSD) turnon resistance	$V_{\text{BTST2}} - V_{\text{SW2}} = 5.5\text{ V}$		7.6		$\Omega$
$R_{\text{DS\_LO\_OFF\_Q3}}$	Low side driver turnoff resistance	$V_{\text{BTST2}} - V_{\text{SW2}} = 5.5\text{ V}$		2.9	4.6	$\Omega$
<b>INTERNAL SOFT START During Charge Enable</b>						
SSSTEP_DAC	Soft Start Step Size			64		mA
SSSTEP_DAC	Soft Start Step Time			8		$\mu\text{s}$
<b>INTEGRATED BTST DIODE (D1)</b>						
$V_{\text{F\_D1}}$	Forward bias voltage	$I_{\text{F}} = 20\text{ mA}$ at $25^\circ\text{C}$		0.8		V
$V_{\text{R\_D1}}$	Reverse breakdown voltage	$I_{\text{R}} = 2\text{ }\mu\text{A}$ at $25^\circ\text{C}$			20	V
<b>INTEGRATED BTST DIODE (D2)</b>						
$V_{\text{F\_D2}}$	Forward bias voltage	$I_{\text{F}} = 20\text{ mA}$ at $25^\circ\text{C}$		0.8		V
$V_{\text{R\_D2}}$	Reverse breakdown voltage	$I_{\text{R}} = 2\text{ }\mu\text{A}$ at $25^\circ\text{C}$			20	V
<b>PWM DRIVERS TIMING</b>						

## Electrical Characteristics (continued)

 over  $T_J = -40$  to  $125^\circ\text{C}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INTERFACE</b>						
<b>LOGIC INPUT (SDA, SCL, EN_OTG)</b>						
$V_{IN\_LO}$	Input low threshold	I2C			0.4	V
$V_{IN\_HI}$	Input high threshold	I2C	1.3			V
<b>LOGIC OUTPUT OPEN DRAIN (SDA, CHRG_OK, CMPOUT)</b>						
$V_{OUT\_LO}$	Output saturation voltage	5-mA drain current			0.4	V
$V_{OUT\_LEAK}$	Leakage current	$V = 7\text{ V}$	-1		1	mA
<b>LOGIC OUTPUT OPEN DRAIN SDA</b>						
$V_{OUT\_LO\_SDA}$	Output Saturation Voltage	5 mA drain current			0.4	V
$V_{OUT\_LEAK\_SDA}$	Leakage Current	$V = 7\text{ V}$	-1		1	mA
<b>LOGIC OUTPUT OPEN DRAIN CHRG_OK</b>						
$V_{OUT\_LO\_CHRG\_OK}$	Output Saturation Voltage	5 mA drain current			0.4	V
$V_{OUT\_LEAK\_CHRG\_OK}$	Leakage Current	$V = 7\text{ V}$	-1		1	mA
<b>LOGIC OUTPUT OPEN DRAIN CMPOUT</b>						
$V_{OUT\_LO\_CMPOUT}$	Output Saturation Voltage	5 mA drain current			0.4	V
$V_{OUT\_LEAK\_CMPOUT}$	Leakage Current	$V = 7\text{ V}$	-1		1	mA
<b>LOGIC OUTPUT OPEN DRAIN (PROCHOT)</b>						
$V_{OUT\_LO\_PROCHOT}$	Output saturation voltage	50- $\Omega$ pullup to 1.05 V / 5-mA load			300	mV
$V_{OUT\_LEAK\_PROCHOT}$	Leakage current	$V = 5.5\text{ V}$	-1		1	mA
<b>ANALOG INPUT (ILIM_HIZ)</b>						
$V_{HIZ\_LO}$	Voltage to get out of HIZ mode	ILIM_HIZ pin rising	0.8			V
$V_{HIZ\_HIGH}$	Voltage to enable HIZ mode	ILIM_HIZ pin falling			0.4	V
<b>ANALOG INPUT (CELL_BATPRESZ)</b>						
$V_{CELL\_4S}$	4S	REGN = 6 V, as percentage of REGN	68.4%	75%		
$V_{CELL\_3S}$	3S	REGN = 6 V, as percentage of REGN	51.7%	55%	65%	
$V_{CELL\_2S}$	2S	REGN = 6 V, as percentage of REGN	35%	40%	49.1%	
$V_{CELL\_1S}$	1S	REGN = 6 V, as percentage of REGN	18.4%	25%	31.6%	
$V_{CELL\_BATPRESZ\_RISE}$	Battery is present		18%			
$V_{CELL\_BATPRESZ\_FALL}$	Battery is removed	CELL_BATPRESZ falling			15%	
<b>ANALOG INPUT (COMP1, COMP2)</b>						
$I_{LEAK\_COMP1}$	COMP1 Leakage		-120		120	nA
$I_{LEAK\_COMP2}$	COMP2 Leakage		-120		120	nA

## 7.6 Timing Requirements

		MIN	TYP	MAX	UNIT
<b>I2C TIMING CHARACTERISTICS</b>					
$t_r$	SCLK/SDATA rise time			1	$\mu\text{s}$
$t_f$	SCLK/SDATA fall time			300	ns
$t_{W(H)}$	SCLK pulse width high		4	50	$\mu\text{s}$
$t_{W(L)}$	SCLK Pulse Width Low		4.7		$\mu\text{s}$
$t_{SU(STA)}$	Setup time for START condition		4.7		$\mu\text{s}$
$t_{H(STA)}$	START condition hold time after which first clock pulse is generated		4		$\mu\text{s}$

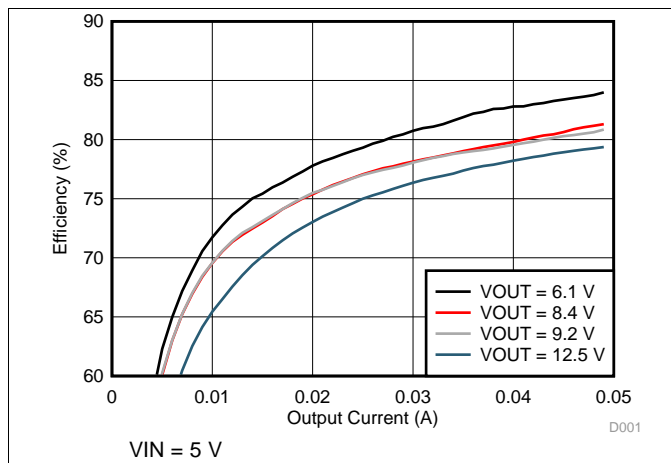


**Timing Requirements (continued)**

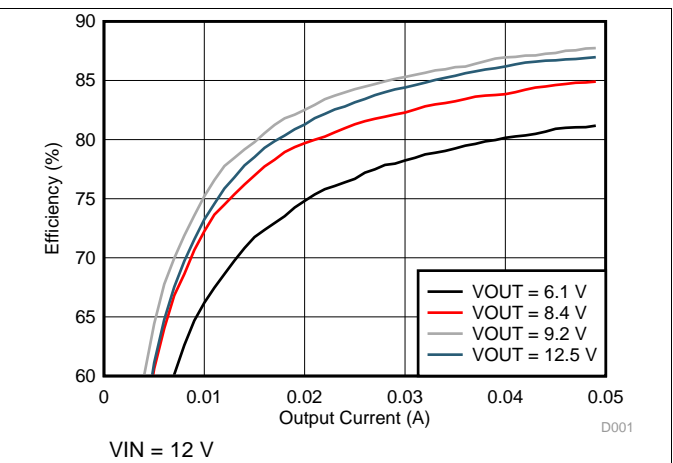
		MIN	TYP	MAX	UNIT
$t_{SU(DAT)}$	Data setup time	250			ns
$t_{H(DTA)}$	Data hold time	300			ns
$t_{SU(STOP)}$	Setup time for STOP condition	4			$\mu$ s
$t_{(BUF)}$	Bus free time between START and STOP condition	4.7			$\mu$ s
$F_{S(CL)}$	Clock Frequency	100		400	KHz
<b>HOST COMMUNICATION FAILURE</b>					
$t_{BOOT}$	Deglitch for watchdog reset signal	10			ms
$t_{WDI}$	Watchdog timeout period, ChargeOption() bit [6:5] = 01 <sup>(1)</sup>	35	44	53	s
	Watchdog timeout period, ChargeOption() bit [6:5] = 10 <sup>(1)</sup>	70	88	105	s
	Watchdog timeout period, ChargeOption() bit [6:5] = 11 <sup>(1)</sup> (default)	140	175	210	s

(1) User can adjust threshold via SMBus ChargeOption() REG0x01/00.

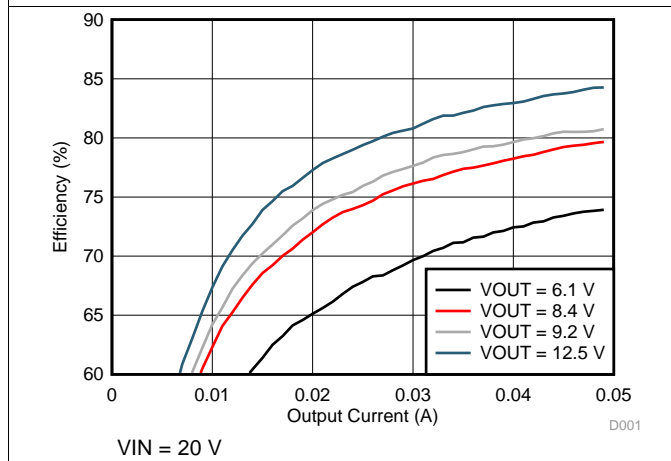
**7.7 Typical Characteristics**



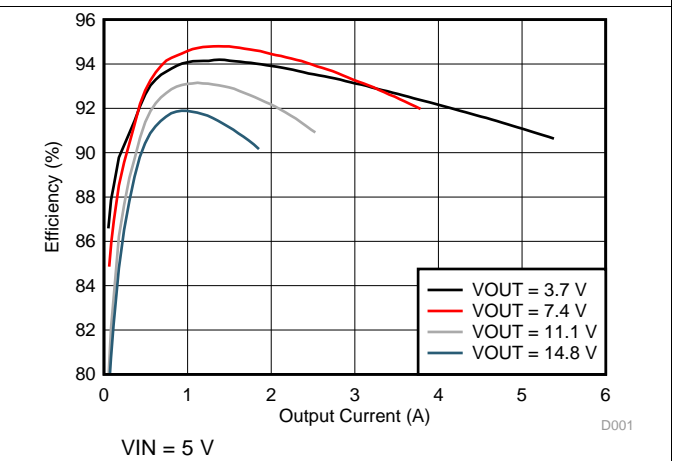
**Figure 1. Light Load Efficiency**



**Figure 2. Light Load Efficiency**

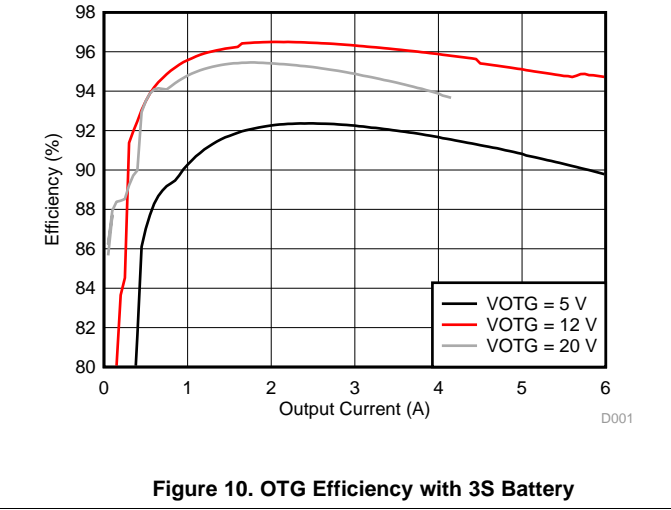
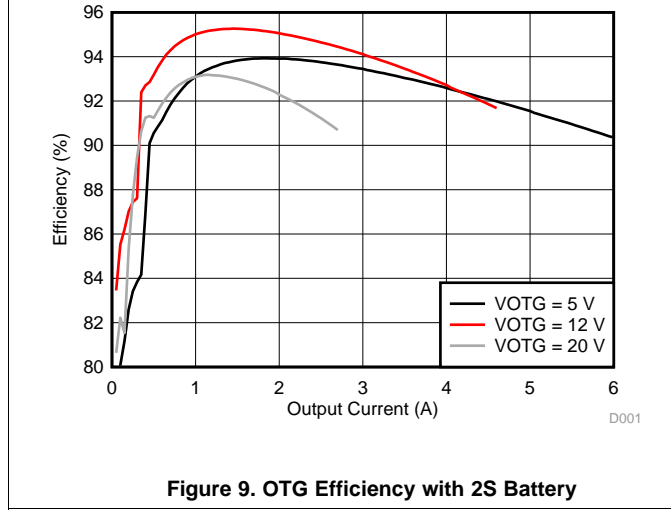
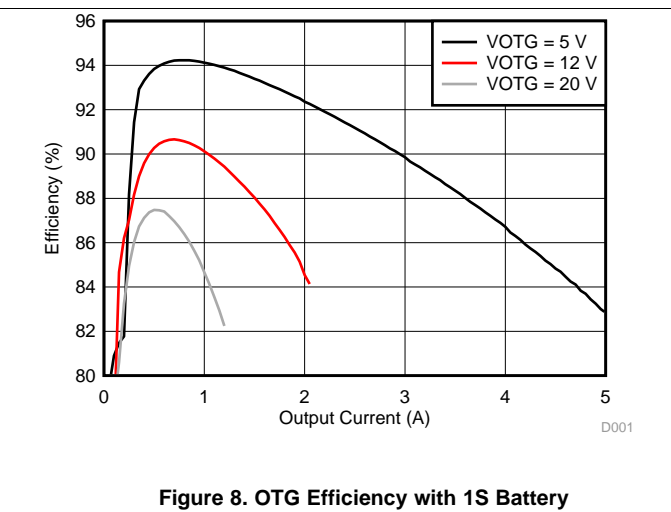
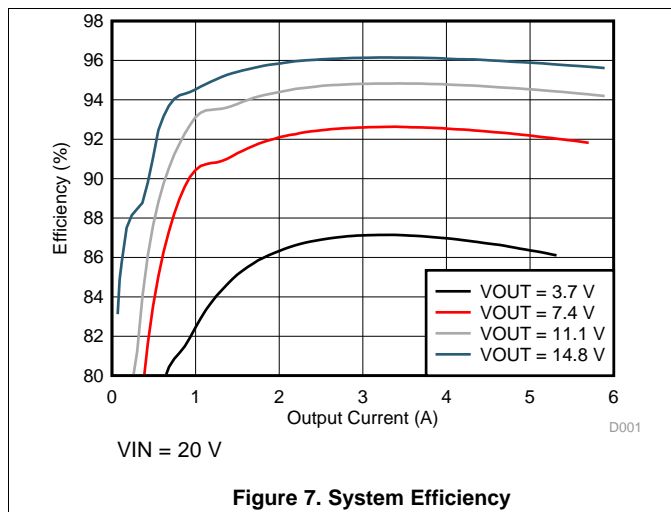
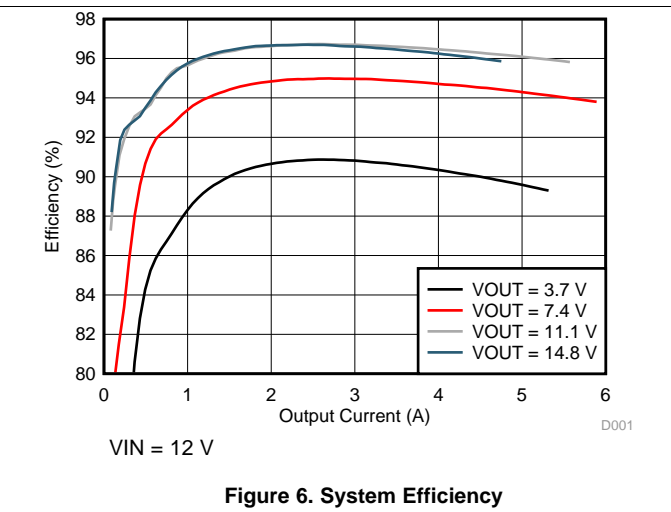
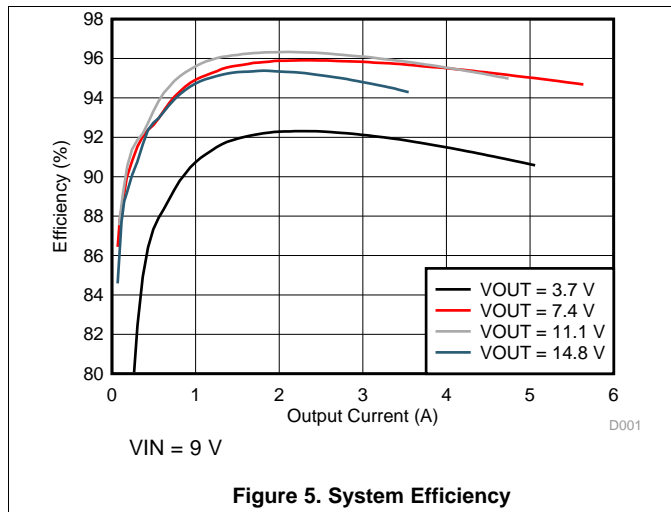


**Figure 3. Light Load Efficiency**

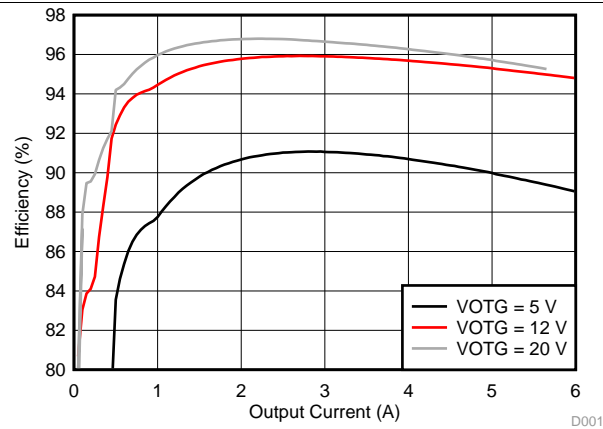


**Figure 4. System Efficiency**

Typical Characteristics (continued)



**Typical Characteristics (continued)**



**Figure 11. OTG Efficiency with 4S Battery**

## 8 Detailed Description

### 8.1 Overview

The bq25703A is a buck boost NVDC (narrow voltage DC) charge controller for multi-chemistry portable applications such as notebook, detachable, ultrabook, tablet and other mobile devices with rechargeable batteries. It provides seamless transition between converter operation modes (buck, boost, or buck boost), fast transient response, and high light load efficiency.

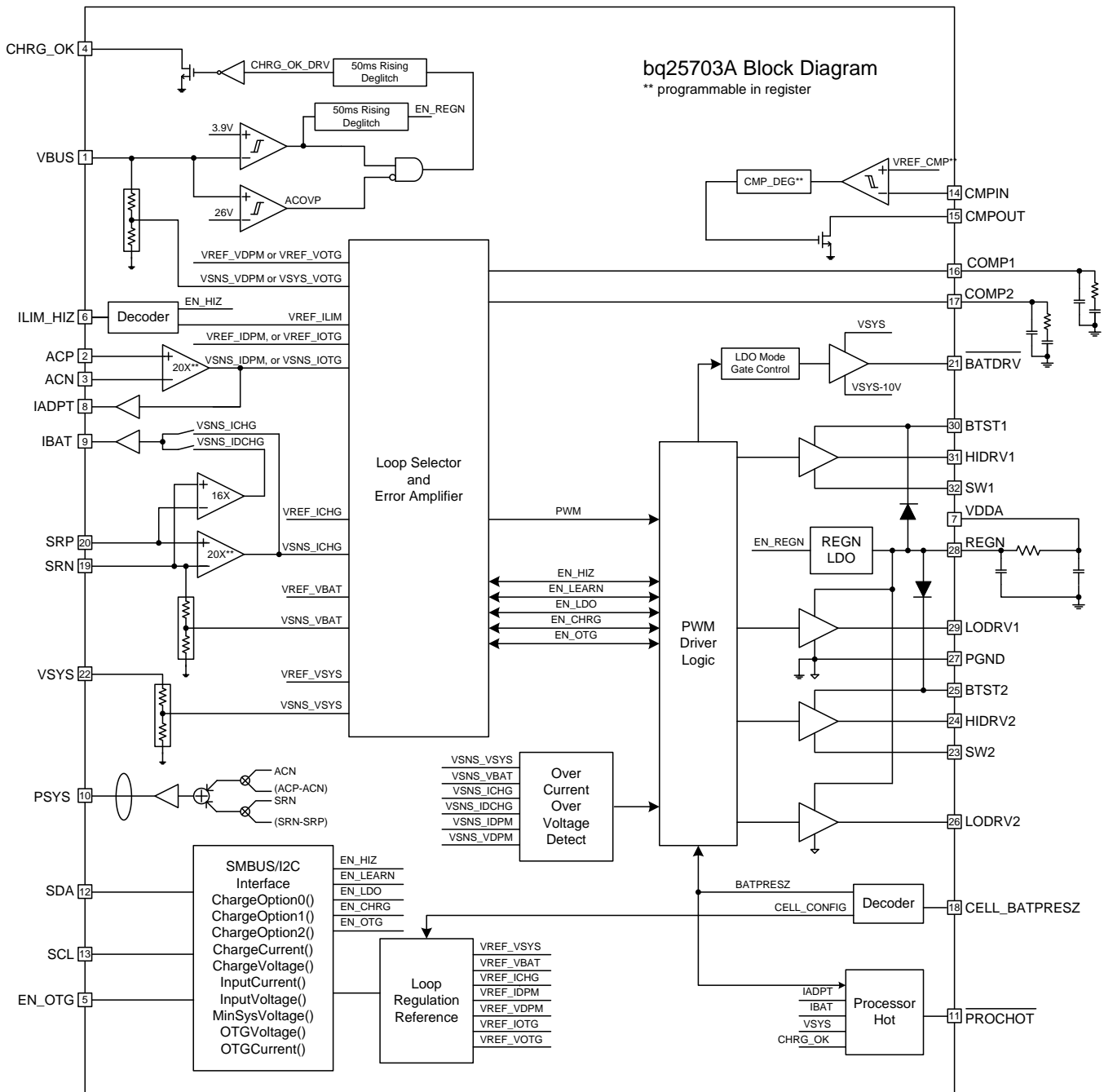
The bq25703A supports wide range of power sources, including USB PD ports, legacy USB ports, traditional AC-DC adapters, etc. It takes input voltage from 3.5 V to 24 V, and charges battery of 1-4 series. It also supports USB On-The-Go (OTG) to provide 4.48V to 20.8V output at USB port.

The bq25703A features Dynamic Power Management (DPM) to limit the input power and avoid AC adapter overloading. During battery charging, as the system power increases, the charging current will reduce to maintain total input current below adapter rating. If system power demand temporarily exceeds adapter rating, the bq25703A supports NVDC architecture to allow battery discharge energy to supplement system power. For details, refer to [System Voltage Regulation](#) section.

In order to be compliant with Intel IMVP8 compliant system, the bq25703A includes PSYS function to monitor the total platform power from adapter and battery. Besides PSYS, it provides both an independent input current buffer (IADPT) and a battery current buffer (IBAT) with highly accurate current sense amplifiers. If the platform power exceeds the available power from adapter and battery, a PROCHOT signal is asserted to CPU so that the CPU optimizes its performance to the power available to the system.

The I2C controls input current, charge current and charge voltage registers with high resolution, high accuracy regulation limits. It also sets the PROCHOT timing and threshold profile to meet system requirements.

## 8.2 Functional Block Diagram



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## 8.3 Feature Description

### 8.3.1 Power-Up from Battery Without DC Source

If only battery is present and the voltage is above  $V_{VBAT\_UVLOZ}$ , the BATFET turns on and connects battery to system. By default, the charger is in low power mode ( $REG0x01[7] = 1$ ) with lowest quiescent current. The LDO stays off. When device moves to performance mode ( $REG0x01[7] = 0$ ), The host enables IBAT buffer through I2C to monitor discharge current. For PSYS,  $\overline{PROCHOT}$  or independent comparator, REGN LDO is enabled for an accurate reference.

### 8.3.2 Power-Up From DC Source

When an input source plugs in, the charger checks the input source voltage to turn on LDO and all the bias circuits. It sets the input current limit before the converter starts.

The power-up sequence from DC source is as follows:

1. 50 ms after VBUS above  $V_{VBUS\_CONVEN}$ , enable 6 V LDO and CHRГ\_OK goes HIGH
2. Input voltage and current limit setup
3. Battery CELL configuration
4. 150 ms after VBUS above  $V_{VBUS\_CONVEN}$ , converter powers up.

#### 8.3.2.1 CHRГ\_OK Indicator

CHRГ\_OK is an active HIGH open drain indicator. It indicates the charger is in normal operation when the following conditions are valid:

- VBUS is above  $V_{VBUS\_CONVEN}$
- VBUS is below  $V_{ACOV}$
- No MOSFET/inductor fault

#### 8.3.2.2 Input Voltage and Current Limit Setup

After CHRГ\_OK goes HIGH, the charger sets default input current limit in  $REG0x0F/0E()$  to 3.30 A. The actual input current limit is the lower setting of  $REG0x0F/0E()$  and ILIM\_HIZ pin.

Charger initiates a VBUS voltage measurement without load (VBUS at noLoad). The default VINDPM threshold is VBUS at noLoad – 1.28 V.

After input current and voltage limits are set, the charger device is ready to power up. The host can always update input current and voltage limit based on input source type.

#### 8.3.2.3 Battery Cell Configuration

CELL\_BATPRESZ pin is biased with resistors from REGN to CELL\_BATPRESZ to GND. After VDDA LDO is activated, the device detects the battery configuration through CELL\_BATPRESZ pin bias voltage. Refer to [Electrical Characteristics](#) for CELL setting thresholds.

**Table 1. Battery Cell Configuration**

CELL COUNT	PIN VOLTAGE w.r.t. VDDA	BATTERY VOLTAGE (REG0x05/04)	SYSOVP
4S	75%	16.800V	No SYSOVP (Refer to <a href="#">System Overvoltage Protection (SYSOVP)</a> section)
3S	55%	12.592V	18.5V
2S	40%	8.400V	12V
1S	25%	4.192V	5V

#### 8.3.2.4 Device Hi-Z State

The charger enters Hi-Z mode when ILIM\_HIZ pin voltage is below 0.4 V or  $REG0x35[7]$  is set to 1. During Hi-Z mode, the input source is present, and the charger is in the low quiescent current mode with REGN LDO enabled.

### 8.3.3 USB On-The-Go (OTG)

The device supports USB OTG operation to deliver power from the battery to other portable devices through USB port. The OTG mode output voltage is set in REG0x07/06(). The OTG mode output current is set in REG0x09/08(). The OTG operation can be enabled if the conditions are valid:

- Valid battery voltage is set REG0x05/04()
- OTG output voltage is set in REG0x07/06() and output current is set in REG0x09/08()
- EN\_OTG pin is HIGH and REG0x35[4] = 1
- VBUS is below  $V_{VBUS\_UVLO}$
- 10 ms after the above conditions are valid, converter starts and VBUS ramps up to target voltage. CHRГ\_OK pin goes HIGH if REG0x01[3] = 1.

### 8.3.4 Converter Operation

The charger employs a synchronous buck-boost converter that allows charging from a standard 5-V or a high-voltage power source. The charger operates in buck, buck-boost and boost mode. The buck-boost can operate uninterruptedly and continuously across the three operation modes.

**Table 2. MOSFET Operation**

MODE	BUCK	BUCK-BOOST	BOOST
Q1	Switching	Switching	ON
Q2	Switching	Switching	OFF
Q3	OFF	Switching	Switching
Q4	ON	Switching	Switching

#### 8.3.4.1 Inductor Setting through IADPT Pin

The charger reads the inductor value through the IADPT pin.

**Table 3. Inductor Setting on IADPT Pin**

INDUCTOR IN USE	RESISTOR ON IADPT PIN
1 $\mu$ H	93 k $\Omega$
2.2 $\mu$ H	137 k $\Omega$
3.3 $\mu$ H	169 k $\Omega$

#### 8.3.4.2 Continuous Conduction Mode (CCM)

With sufficient charge current, the inductor current does not cross 0, which is defined as CCM. The controller starts a new cycle with ramp coming up from 200 mV. As long as error amplifier output voltage is above the ramp voltage, the high-side MOSFET (HSFET) stays on. When the ramp voltage exceeds error amplifier output voltage, HSFET turns off and lowside MOSFET (LSFET) turns on. At the end of the cycle, ramp gets reset and LSFET turns off, ready for the next cycle. There is always break-before-make logic during transition to prevent cross-conduction and shoot-through. During the dead time when both MOSFETs are off, the body-diode of the low-side power MOSFET conducts the inductor current.

During CCM, the inductor current always flows and creates a fixed two-pole system. Having the LSFET turn-on keeps the power dissipation low and allows safe charging at high currents.

#### 8.3.4.3 Pulse Frequency Modulation (PFM)

In order to improve converter light-load efficiency, the bq25703A switches to PFM control at light load when inductor current is less than 500 mA. The effective switching frequency will decrease accordingly when system load decreases. The minimum frequency can be limit to 25 kHz (ChargeOption0() bit[10]=1). To have higher light load efficiency, set EN\_OOA bit low (Chargeoption0() bit[10] = 0).

### 8.3.5 Current and Power Monitor

#### 8.3.5.1 High-Accuracy Current Sense Amplifier (IADPT and IBAT)

As an industry standard, a high-accuracy current sense amplifier (CSA) is used to monitor the input current during forward charging, or output current during OTG (IADPT) and the charge/discharge current (IBAT). IADPT voltage is 20× or 40× the differential voltage across ACP and ACN. IBAT voltage is 8×/16× (during charging), or 8×/16× (during discharging) of the differential across SRP and SRN. After input voltage or battery voltage is above UVLO, IADPT output becomes valid. To lower the voltage on current monitoring, a resistor divider from CSA output to GND can be used and accuracy over temperature can still be achieved.

- $V_{(IADPT)} = 20 \text{ or } 40 \times (V_{(ACP)} - V_{(ACN)})$  during forward mode, or  $20 \text{ or } 40 \times (V_{(ACN)} - V_{(ACP)})$  during reverse OTG mode.
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRP)} - V_{(SRN)})$  during forward mode.
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRN)} - V_{(SRP)})$  during forward mode, or reverse OTG mode.

A maximum 100-pF capacitor is recommended to connect on the output for decoupling high-frequency noise. An additional RC filter is optional, if additional filtering is desired. Note that adding filtering also adds additional response delay. The CSA output voltage is clamped at 3.3 V.

#### 8.3.5.2 High-Accuracy Power Sense Amplifier (PSYS)

The charger monitors total system power. During forward mode, the input adapter powers system. During reverse OTG mode, the battery powers the system and VBUS output. The ratio of PSYS current and total power  $K_{PSYS}$  can be programmed in REG0x31[1] with default 1  $\mu$ A/W. The input and charge sense resistors (RAC and RSR) are programmed in REG0x31[3:2]. PSYS voltage can be calculated with Equation 1 where IIN>0 when adapter is in forward charging, and IBAT>0 when the battery is in discharge when the battery is in discharge.

$$V_{PSYS} = R_{PSYS} \times K_{PSYS} (V_{ACP} \times I_{IN} + V_{BAT} \times I_{BAT}) \quad (1)$$

For proper PSYS functionality, RAC and RSR values are limited to 10 m $\Omega$  and 20 m $\Omega$ .

### 8.3.6 Input Source Dynamic Power Manage

Refer to [Input Current and Input Voltage Registers for Dynamic Power Management](#).

#### 8.3.7 Two-Level Adapter Current Limit (Peak Power Mode)

Usually adapter can supply current higher than DC rating for a few milliseconds to tens of milliseconds. The charger employs two-level input current limit, or peak power mode, to fully utilize the overloading capability and minimize battery discharge during CPU turbo mode. Peak power mode is enabled in REG0x33[5]. The DC current limit, or  $I_{LIM1}$ , is the same as adapter DC current, set in REG0x0F/0E(). The overloading current, or  $I_{LIM2}$ , is set in REG0x37[7:3], as in percentage of  $I_{LIM1}$ .

When the charger detects input current surge and battery discharge due to load transient, it applies  $I_{LIM2}$  for  $T_{OVLD}$  in REG0x33[7:6], first, and then  $I_{LIM1}$  for up to  $T_{MAX} - T_{OVLD}$  time.  $T_{MAX}$  is programmed in REG0x33[1:0]. After  $T_{MAX}$ , if the load is still high, another peak power cycle starts. Charging is disabled during  $T_{MAX}$ ; once  $T_{MAX}$  expires, charging continues.



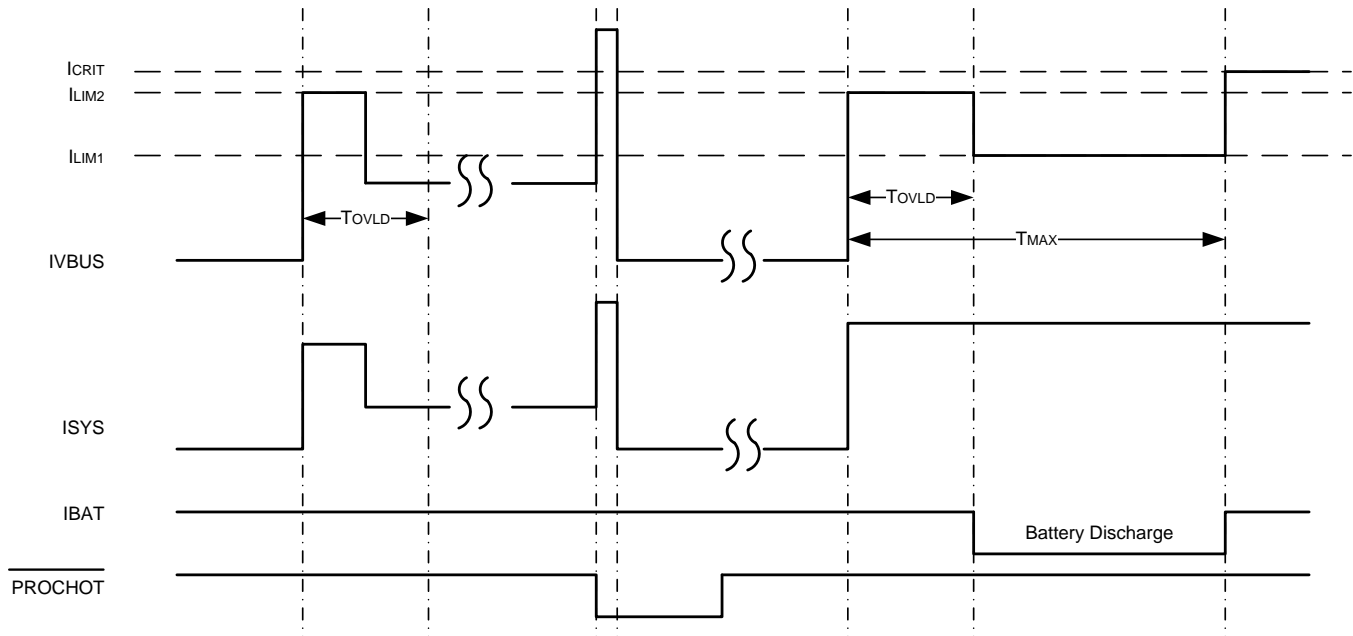


Figure 12. Two-Level Adapter Current Limit Timing Diagram

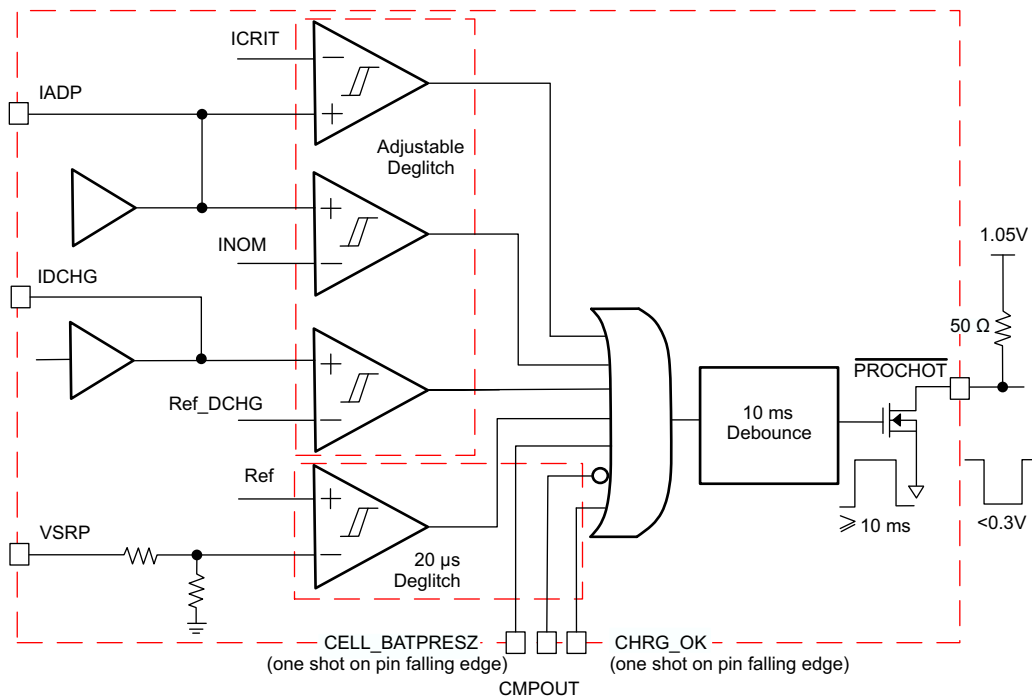
### 8.3.8 Processor Hot Indication

When CPU is running turbo mode, the system peak power may exceed available power from adapter and battery together. The adapter current and battery discharge peak current, or system voltage drop is indications that system power are too high. The charger processor hot function monitors these events, and  $\overline{\text{PROCHOT}}$  pulse is asserted. Once CPU receives  $\overline{\text{PROCHOT}}$  pulse from charger, it slows down to reduce system power. The processor hot function monitors these events, and  $\overline{\text{PROCHOT}}$  pulse is asserted.

The  $\overline{\text{PROCHOT}}$  triggering events include:

- ICRIT: adapter peak current, as 110% of  $I_{\text{LIM2}}$
- INOM: adapter average current (110% of input current limit)
- IDCHG: battery discharge current
- VSYS: system voltage on VSYS
- Adapter Removal: upon adapter removal (CHRG\_OK pin HIGH to LOW)
- Battery Removal: upon battery removal (CELL\_BATPRESZ pin goes LOW)
- CMPOUT: Independent comparator output (CMPOUT pin HIGH to LOW)

The threshold of ICRIT, IDCHG or VSYS, and the deglitch time of ICRIT, INOM, IDCHG or CMPOUT are programmable through I2C. Each triggering event can be individually enabled in REG0x38[6:0]. When any event in  $\overline{\text{PROCHOT}}$  profile is triggered,  $\overline{\text{PROCHOT}}$  is asserted low for minimum 10 ms programmable in 0x36[4:3]. At the end of the 10 ms, if the  $\overline{\text{PROCHOT}}$  event is still active, the pulse gets extended.



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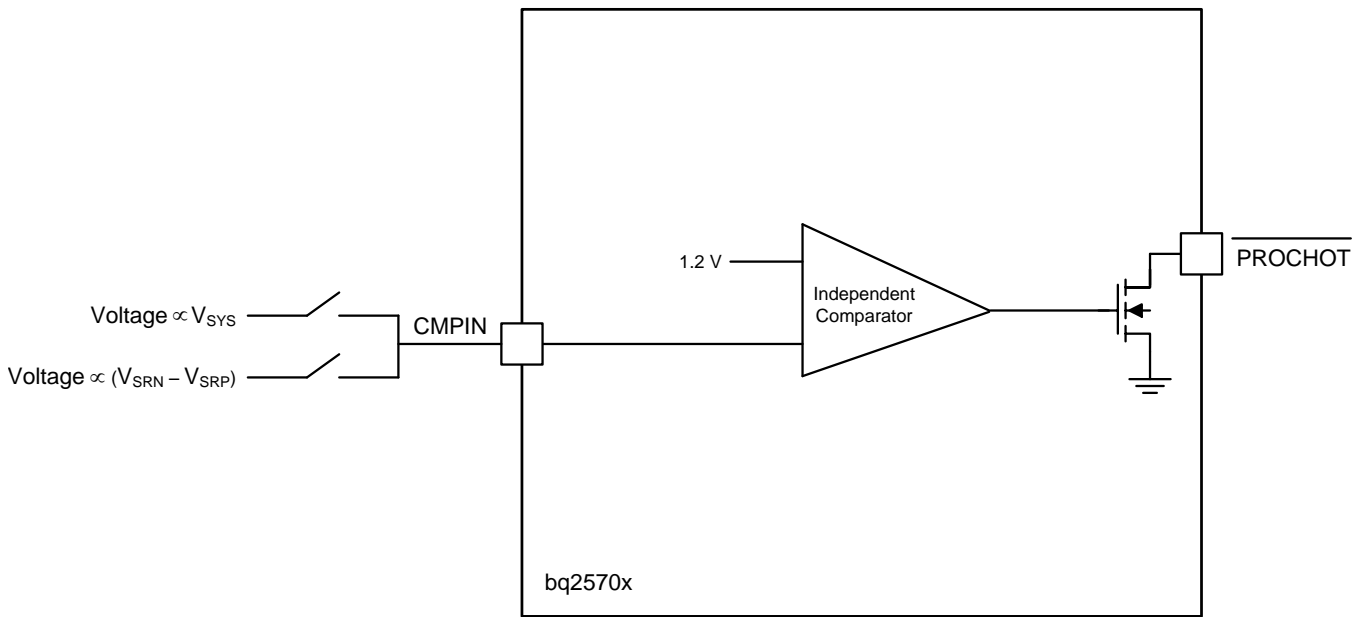
**Figure 13. PROCHOT Profile**

### 8.3.8.1 PROCHOT During Low Power Mode

During low power mode ( $REG0x01[7] = 1$ ), the charger offers a low quiescent current ( $\sim 150 \mu A$ ). Low power PROCHOT function uses the independent comparator to monitor battery discharge current and system voltage, and assert PROCHOT to CPU.

Below lists the register setting to enable PROCHOT during low power mode.

- $REG0x01[7] = 1$
- $REG0x38[5:0] = 000000$
- $REG0x30[6:4] = 100$
- Independent comparator threshold is always 1.2 V
- When  $REG0x31[6] = 1$ , charger monitors discharge current. Connect CMPIN to voltage proportional to IBAT pin. PROCHOT triggers from HIGH to LOW when CMPIN voltage falls below 1.2 V.
- When  $REG0x31[5] = 1$ , charger monitors system voltage. Connect CMPIN to voltage proportional to system. PROCHOT triggers from HIGH to LOW when CMPIN voltage rises above 1.2 V.



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Figure 14.  $\overline{\text{PROCHOT}}$  Low Power Mode Implementation

### 8.3.8.2 $\overline{\text{PROCHOT}}$ Status

REG0x22[6:0] reports which event in the profile triggers  $\overline{\text{PROCHOT}}$  by setting the corresponding bit to 1. The status bit can be reset back to 0 after it is read by host, and current  $\overline{\text{PROCHOT}}$  event is no longer active.

Assume there are two  $\overline{\text{PROCHOT}}$  events, event A and event B. Event A triggers  $\overline{\text{PROCHOT}}$  first, but event B is also active. Both status bits will be HIGH. At the end of the 10 ms  $\overline{\text{PROCHOT}}$  pulse, if  $\overline{\text{PROCHOT}}$  is still active (either by A or B), the  $\overline{\text{PROCHOT}}$  pulse is extended.

### 8.3.9 Device Protection

#### 8.3.9.1 Watchdog Timer

The charger includes watchdog timer to terminate charging if the charger does not receive a write MaxChargeVoltage() or write ChargeCurrent() command within 175 s (adjustable via REG0x01[6:5]). When watchdog timeout occurs, all register values are kept unchanged except ChargeCurrent() resets to zero. Battery charging is suspended. Write MaxChargeVoltage() or write ChargeCurrent() commands must be re-sent to reset watchdog timer and resume charging. Writing REG0x01[6:5] = 00 to disable watchdog timer also resumes charging.

#### 8.3.9.2 Input Overvoltage Protection (ACOV)

The charger has fixed ACOV voltage. When VBUS pin voltage is higher than ACOV, it is considered as adapter over voltage. CHRГ\_OK will be pulled low, and converter will be disabled. As system falls below battery voltage, BATFET will be turned on. When VBUS pin voltage falls below ACOV, it is considered as adapter voltage returns back to normal voltage. CHRГ\_OK is pulled high by external pull up resistor. The converter resumes if enable conditions are valid.

#### 8.3.9.3 Input Overcurrent Protection (ACOC)

If the input current exceeds the 1.25x or 2x (REG0x32[2]) of  $I_{\text{LIM2\_VTH}}$  (REG0x37[7:3]) set point, converter stops switching. After 300 ms, converter starts switching again.

#### 8.3.9.4 System Overvoltage Protection (SYSOVP)

When the converter starts up, the bq25700 reads CELL pin configuration and sets MaxChargeVoltage() and SYSOVP threshold (1s – 5 V, 2s – 12 V, 3s – 18.5 V). Before REGx05/04() is written by the host, the battery configuration will change with CELL pin voltage. When SYSOVP happens, the device latches off the converter. REG20[4] is set as 1. The user can clear latch-off by either writing 0 to the SYSOVP bit or removing and plugging in the adapter again. After latch-off is cleared, the converter starts again.

#### 8.3.9.5 Battery Overvoltage Protection (BATOVP)

Battery over-voltage may happen when battery is removed during charging or the user plugs in a wrong battery. The BATOVP threshold is 104% (1 s) or 102% (2 s to 4 s) of regulation voltage set in REG0x05/04().

#### 8.3.9.6 Battery Short

If BAT voltage falls below SYSMIN during charging, the maximum current is limited to 384 mA.

#### 8.3.9.7 Thermal Shutdown (TSHUT)

The WQFN package has low thermal impedance, which provides good thermal conduction from the silicon to the ambient, to keep junction temperatures low. As added level of protection, the charger converter turns off for self-protection whenever the junction temperature exceeds the 155°C. The charger stays off until the junction temperature falls below 135°C. During thermal shut down, the LDO current limit is reduced to 16 mA and REGN LDO stays off. When the temperature falls below 135°C, charge can be resumed with soft start.

### 8.4 Device Functional Modes

#### 8.4.1 Forward Mode

When input source is connected to VBUS, bq25703A is in forward mode to regulate system and charge battery.

##### 8.4.1.1 System Voltage Regulation with Narrow VDC Architecture

The bq25703A employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by MinSystemVoltage(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode).

As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

See [System Voltage Regulation](#) for details on system voltage regulation and register programming.

##### 8.4.1.2 Battery Charging

The bq25703A charges 1-4 cell battery in constant current (CC), and constant voltage (CV) mode. Based on CELL\_BATPREZ pin setting, the charger sets default battery voltage 4.2V/cell to ChargeVoltage(), or REG0x05/04(). According to battery capacity, the host programs appropriate charge current to ChargeCurrent(), or 0x03/02(). When battery is full or battery is not in good condition to charge, host terminates charge by setting 0x00[0] to 1, or setting ChargeCurrent() to zero.

See [Feature Description](#) for details on register programming.

#### 8.4.2 USB On-The-Go

The bq25703A supports USB OTG functionality to deliver power from the battery to other portable devices through USB port (reverse mode). The OTG output voltage is compliant with USB PD specification, including 5 V, 9 V, 15 V, and 20 V (REG0x07/06()). The output current regulation is compliant with USB type C specification, including 500 mA, 1.5 A, 3 A and 5 A (REG0x09/08()).

Similar to forward operation, the device switches from PWM operation to PFM operation at light load to improve efficiency.

## 8.5 Programming

The charger supports battery-charger commands that use either Write-Word or Read-Word protocols, as summarized in . The SMBUS address is 12h (0001001\_X), where X is the read/write bit. The ManufacturerID and DeviceID registers are assigned identify the charger device. The ManufacturerID register command always returns 40h.

### 8.5.1 I<sup>2</sup>C Serial Interface

The bq25703A uses I<sup>2</sup>C compatible interface for flexible charging parameter programming and instantaneous device status reporting. I<sup>2</sup>C is a bi-directional 2-wire serial interface. Only two bus lines are required: a serial data line (SDA) and a serial clock line (SCL). Devices can be considered as masters or slaves when performing data transfers. A master is the device which initiates a data transfer on the bus and generates the clock signals to permit that transfer. At that time, any device addressed is considered a slave.

The device operates as a slave device with address D6h, receiving control inputs from the master device like micro controller or a digital signal processor through REG00-REG0F. The I<sup>2</sup>C interface supports both standard mode (up to 100 kbits), and fast mode (up to 400 kbits). connecting to the positive supply voltage via a current source or pull-up resistor. When the bus is free, both lines are HIGH. The SDA and SCL pins are open drain.

#### 8.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock. The HIGH or LOW state of the data line can only change when the clock signal on the SCL line is LOW. One clock pulse is generated for each data bit transferred.

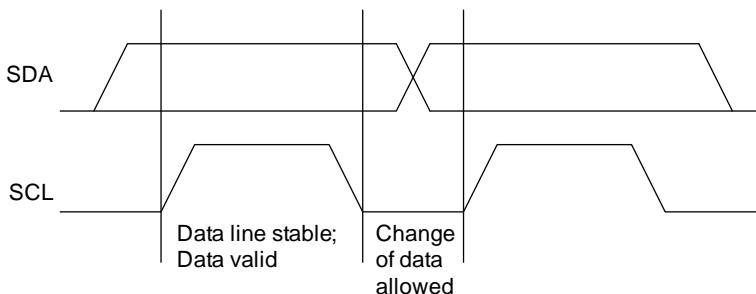


Figure 15. Bit Transfer on the I<sup>2</sup>C Bus

#### 8.5.1.2 START and STOP Conditions

All transactions begin with a START (S) and can be terminated by a STOP (P). A HIGH to LOW transition on the SDA line while SCL is HIGH defines a START condition. A LOW to HIGH transition on the SDA line when the SCL is HIGH defines a STOP condition.

START and STOP conditions are always generated by the master. The bus is considered busy after the START condition, and free after the STOP condition.

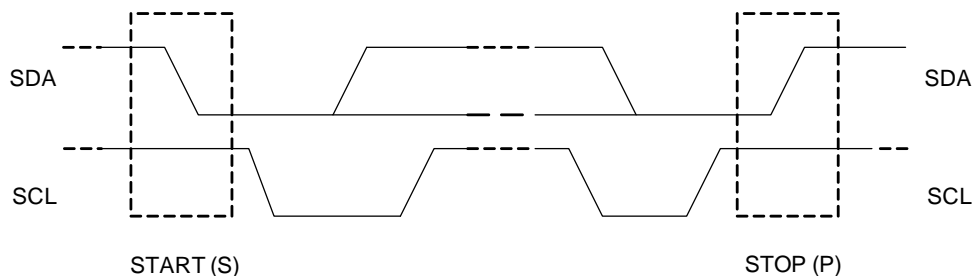
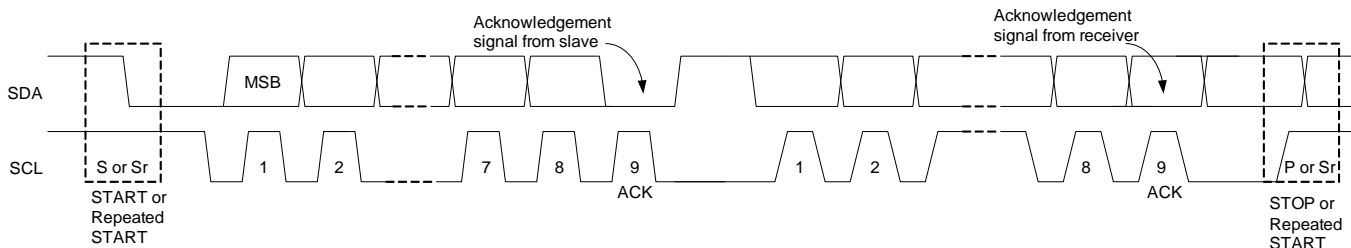


Figure 16. START and STOP Conditions

## Programming (continued)

### 8.5.1.3 Byte Format

Every byte on the SDA line must be 8 bits long. The number of bytes to be transmitted per transfer is unrestricted. Each byte has to be followed by an Acknowledge bit. Data is transferred with the Most Significant Bit (MSB) first. If a slave cannot receive or transmit another complete byte of data until it has performed some other function, it can hold the clock line SCL low to force the master into a wait state (clock stretching). Data transfer then continues when the slave is ready for another byte of data and release the clock line SCL.



**Figure 17. Data Transfer on the I<sup>2</sup>C Bus**

### 8.5.1.4 Acknowledge (ACK) and Not Acknowledge (NACK)

The acknowledge takes place after every byte. The acknowledge bit allows the receiver to signal the transmitter that the byte was successfully received and another byte may be sent. All clock pulses, including the acknowledge 9th clock pulse, are generated by the master.

The transmitter releases the SDA line during the acknowledge clock pulse so the receiver can pull the SDA line LOW and it remains stable LOW during the HIGH period of this clock pulse.

When SDA remains HIGH during the 9th clock pulse, this is the Not Acknowledge signal. The master can then generate either a STOP to abort the transfer or a repeated START to start a new transfer.

## Programming (continued)

### 8.5.1.5 Slave Address and Data Direction Bit

After the START, a slave address is sent. This address is 7 bits long followed by the eighth bit as a data direction bit (bit R/W). A zero indicates a transmission (WRITE) and a one indicates a request for data (READ).

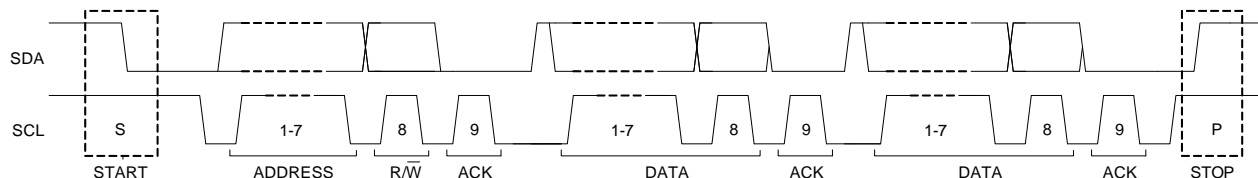


Figure 18. Complete Data Transfer

### 8.5.1.6 Single Read and Write

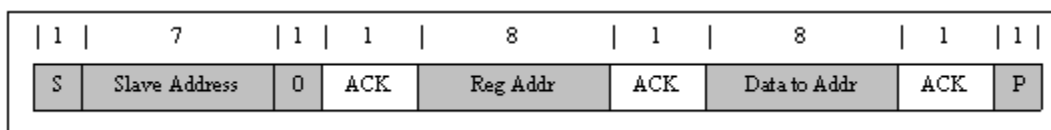


Figure 19. Single Write

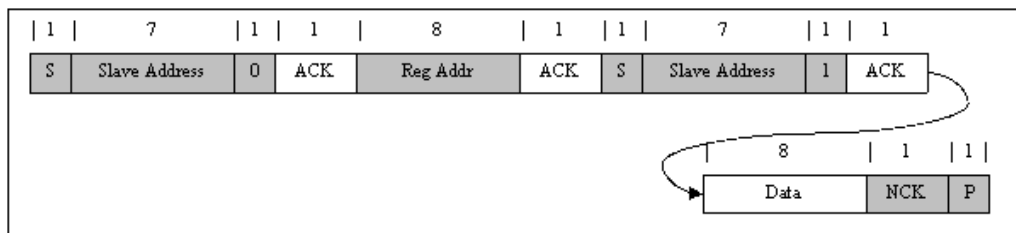


Figure 20. Single Read

If the register address is not defined, the charger IC send back NACK and go back to the idle state.

### 8.5.1.7 Multi-Read and Multi-Write

The charger device supports multi-read and multi-write.

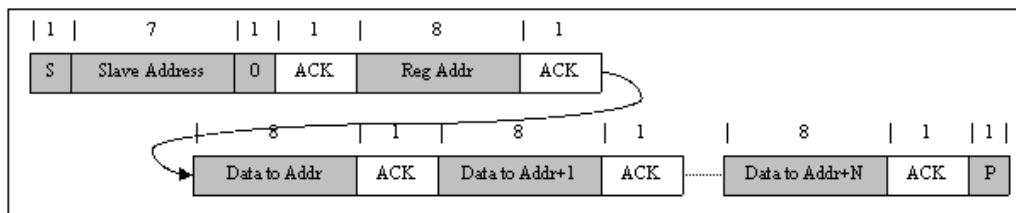
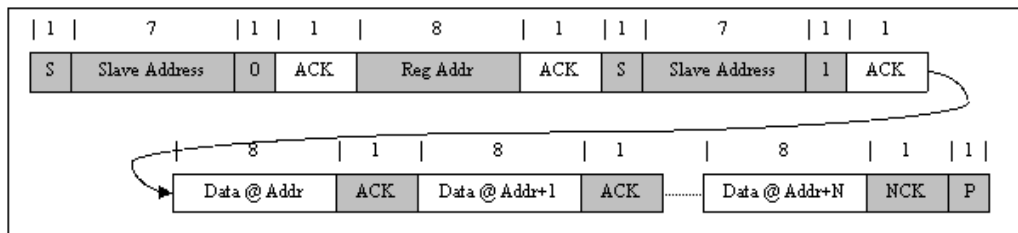


Figure 21. Multi Write

## Programming (continued)



**Figure 22. Multi Read**

### 8.5.1.8 Write 2-Byte I2C Commands

A few I2C commands combine two 8-bit registers together to form a complete value. These commands include:

- ChargeCurrent()
- MaxChargeVoltage()
- IIN\_DPM()
- OTGVoltage()
- InputVoltage()

Host has to write LSB command followed by MSB command. No other command can be inserted in between these two writes. The charger waits for the complete write to the two registers to decide whether to accept or ignore the new value.

After the completion of LSB and MSB bytes, the two bytes will be updated at the same time. If host writes MSB byte first, the command will be ignored. If the time between write of LSB and MSB bytes exceeds watchdog timer, both the LSB and MSB commands will be ignored.

## 8.6 Register Map

**Table 4. Charger Command Summary**

I2C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
01/00	ChargeOption0()	R/W	Charge Option 0	<a href="#">Go</a>
03/02	ChargeCurrent()	R/W	7-bit charge current setting LSB 64 mA, Range 8128 mA	<a href="#">Go</a>
05/04	MaxChargeVoltage()	R/W	11-bit charge voltage setting LSB 16 mV, Default: 1S-4192mV, 2S-8400mV, 3S-12592mV, 4S-16800mV	<a href="#">Go</a>
31/30	ChargeOption1()	R/W	Charge Option 1	<a href="#">Go</a>
33/32	ChargeOption2()	R/W	Charge Option 2	<a href="#">Go</a>
35/34	ChargeOption3()	R/W	Charge Option 3	<a href="#">Go</a>
37/36	ProchotOption0()	R/W	$\overline{\text{PROCHOT}}$ Option 0	<a href="#">Go</a>
39/38	ProchotOption1()	R/W	$\overline{\text{PROCHOT}}$ Option 1	<a href="#">Go</a>
3B/3A	ADCOption()	R/W	ADC Option	<a href="#">Go</a>
21/20	ChargerStatus()	R	Charger Status	<a href="#">Go</a>
23/22	ProchotStatus()	R	Prochot Status	<a href="#">Go</a>
25/24	IIN_DPM()	R	7-bit input current limit in use LSB: 50 mA, Range: 50 mA - 6400 mA	<a href="#">Go</a>
27/26	ADCVBUS/PSYS()	R	8-bit digital output of input voltage, 8-bit digital output of system power PSYS: Full range: 3.06 V, LSB: 12 mV VBUS: Full range: 3.2 V - 19.52 V, LSB 64 mV	<a href="#">Go</a>



**Register Map (continued)**
**Table 4. Charger Command Summary (continued)**

I2C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
29/28	ADCIBAT()	R	8-bit digital output of battery charge current, 8-bit digital output of battery discharge current ICHG: Full range 8.128 A, LSB 64 mA IDCHG: Full range: 32.512 A, LSB: 256 mA	<a href="#">Go</a>
2B/2A	ADCIINCPIN()	R	8-bit digital output of input current, 8-bit digital output of CMPIN voltage POR State - IIN: Full range: 12.75 A, LSB 50 mA CMPIN: Full range 3.06 V, LSB: 12 mV	<a href="#">Go</a>
2D/2C	ADCVSYSVBAT()	R	8-bit digital output of system voltage, 8-bit digital output of battery voltage VSY: Full range: 2.88 V - 19.2 V, LSB: 64 mV VBAT: Full range : 2.88 V - 19.2 V, LSB 64 mV	<a href="#">Go</a>
07/06	OTGVoltage()	R/W	8-bit OTG voltage setting LSB 64 mV, Range: 4480 – 20800 mV	<a href="#">Go</a>
09/08	OTGCurrent()	R/W	7-bit OTG output current setting LSB 50 mA, Range: 0 A – 6350 mA	<a href="#">Go</a>
0B/0A	InputVoltage()	R/W	8-bit input voltage setting LSB 64 mV, Range: 3200 mV – 19520 mV	<a href="#">Go</a>
0D/0C	MinSystemVoltage()	R/W	6-Bit minimum system voltage setting LSB: 256 mV, Range: 1024 mV - 16182 mV Default: 1S-3.584V, 2S-6.144V, 3S-9.216V, 4S-12.288V	<a href="#">Go</a>
0F/0E	IIN_HOST()	R/W	6-bit Input current limit set by host LSB: 50-mA, Range: 0 mA - 6350 mA	<a href="#">Go</a>
2E	ManufacturerID()	R	Manufacturer ID - 0x0040H	<a href="#">Go</a>
2F	DeviceAddress()	R	Device Address ID	<a href="#">Go</a>

### 8.6.1 Setting Charge and PROCHOT Options

#### 8.6.1.1 ChargeOption0 Register (I2C address = 01/00h) [reset = E20Eh]

Figure 23. ChargeOption0 Register (I2C address = 01h/00h) [reset = E20Eh]

15	14	13	12	11	10	9	8
EN_LWPWR	WDTMR_ADJ		IDPM_AUTO_DISABLE	OTG_ON_CHRGOK	EN_OOA	PWM_FREQ	Reserved
R/W	R/W		R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Reserved	EN_LEARN	IADPT_GAIN	IBAT_GAIN	EN_LDO	EN_IDPM	CHRG_INHIBIT	
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 5. ChargeOption0 Register (I2C address = 01h) Field Descriptions

I2C 01h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_LWPWR	R/W	1b	<p>Low Power Mode Enable</p> <p>0b: Disable Low Power Mode. Device in performance mode with battery only. The PROCHOT, current/power monitor buffer and comparator follow register setting.</p> <p>1b: Enable Low Power Mode. Device in low power mode with battery only for lowest quiescent current. PROCHOT, discharge current monitor buffer, power monitor buffer and independent comparator are disabled. ADC is not available in Low Power Mode. Independent comparator can be enabled by setting either REG0X31()[6] or [5] to 1. &lt;default at POR&gt;</p>
6-5	WDTMR_ADJ	R/W	11b	<p>WATCHDOG Timer Adjust</p> <p>Set maximum delay between consecutive I2C write of charge voltage or charge current command.</p> <p>If device does not receive a write on the REG0x05/04() or the REG0x03/02() within the watchdog time period, the charger will be suspended by setting the REG0x03/02() to 0 mA.</p> <p>After expiration, the timer will resume upon the write of REG0x03/02(), REG0x05/04() or REG0x01[6:5]. The charger will resume if the values are valid.</p> <p>00b: Disable Watchdog Timer            01b: Enabled, 5 sec            10b: Enabled, 88 sec            11b: Enable Watchdog Timer, 175 sec &lt;default at POR&gt;</p>
4	IDPM_AUTO_DISABLE	R/W	0b	<p>IDPM Auto Disable</p> <p>When CELL_BATPRESZ pin is LOW, the charger automatically disables the IDPM function by setting EN_IDPM (REG0x00[1]) to 0. The host can enable IDPM function later by writing EN_IDPM bit (REG0x00[1]) to 1.</p> <p>0b: Disable this function. IDPM is not disabled when CELL_BATPRESZ goes LOW. &lt;default at POR&gt;            1b: Enable this function. IDPM is disabled when CELL_BATPRESZ goes LOW.</p>
3	OTG_ON_CHRGOK	R/W	0b	<p>Add OTG to CHRG_OK</p> <p>Drive CHRG_OK to HIGH when the device is in OTG mode.</p> <p>0b: Disable &lt;default at POR&gt;            1b: Enable</p>
2	EN_OOA	R/W	0b	<p>Out-of-Audio Enable</p> <p>0b: No limit of PFM burst frequency &lt;default at POR&gt;            1b: Set minimum PFM burst frequency to above 25 kHz to avoid audio noise</p>

**Table 5. ChargeOption0 Register (I2C address = 01h) Field Descriptions (continued)**

I2C 01h	FIELD	TYPE	RESET	DESCRIPTION
1	PWM_FREQ	R/W	1b	Switching Frequency Two converter switching frequencies. One for small inductor and the other for big inductor. Recommend 800 kHz with 2.2 $\mu$ H or 3.3 $\mu$ H, and 1.2 MHz with 1 $\mu$ H or 1.5 $\mu$ H. Host has to set the right PWM frequency after device POR. 0b: 1200 kHz 1b: 800 kHz
0	Reserved	R/W	0b	Reserved

**Table 6. ChargeOption0 Register (I2C address = 00h) Field Descriptions**

I2C 00h	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Reserved
5	EN_LEARN	R/W	0b	LEARN function allows the battery to discharge while the adapter is present. It calibrates the battery gas gauge over a complete discharge/charge cycle. When the battery voltage is below battery depletion threshold, the system switches back to adapter input by the host. When CELL_BATPRESZ pin is LOW, the device exits LEARN mode and this bit is set back to 0. 0b: Disable LEARN Mode <default at POR> 1b: Enable LEARN Mode
4	IADPT_GAIN	R/W	0b	IADPT Amplifier Ratio The ratio of voltage on IADPT and voltage across ACP and ACN. 0b: 20x <default at POR> 1b: 40x
3	IBAT_GAIN	R/W	1b	IBAT Amplifier Ratio 0b: 8x 1b: 16x <default at POR>
2	EN_LDO	R/W	1b	LDO Mode Enable When battery voltage is below minimum system voltage (REG0x0D/0C()), the charger is in pre-charge with LDO mode enabled. 0b: Disable LDO mode, BATFET fully ON. Precharge current is set by battery pack LDO. The system is regulated by the MaxChargeVoltage register. 1b: Enable LDO mode, Precharge current is set by the ChargeCurrent register and clamped below 384 mA (2 cell – 4 cell) or 2A (1 cell). The system is regulated by the MinSystemVoltage register. <default at POR>
1	EN_IDPM	R/W	1b	IDPM Enable Host writes this bit to enable IDPM regulation loop. When the IDPM is disabled by the charger (refer to IDPM_AUTO_DISABLE), this bit goes LOW. 0b: IDPM disabled 1b: IDPM enabled <default at POR>
0	CHRG_INHIBIT	R/W	0b	Charge Inhibit When this bit is 0, battery charging will start with valid values in the MaxChargeVoltage register and the ChargeCurrent register. 0b: Enable Charge <default at POR> 1b: Inhibit Charge

**8.6.1.2 ChargeOption1 Register (I2C address = 31h/30h) [reset = 211h]**
**Figure 24. ChargeOption1 Register (I2C address = 31h/30h) [reset = 211h]**

15	14	13	12	11	10	9	8
EN_IBAT	EN_PROCHOT_LPWR		EN_PSYS	RSNS_RAC	RSNS_RSR	PSYS_RATIO	Reserved
R/W	R/W		R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
CMP_REF	CMP_POL	CMP_DEG		FORCE_LATCHOFF	Reserved	EN_SHIP_DCHG	AUTO_WAKEUP_EN
R/W	R/W	R/W		R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 7. ChargeOption1 Register (I2C address = 31h) Field Descriptions**

I2C 31h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_IBAT	R/W	0b	IBAT Enable Enable the IBAT output buffer. In low power mode (REG0x01[7] = 1), IBAT buffer is always disabled regardless of this bit value. 0b Turn off IBAT buffer to minimize Iq <default at POR> 1b: Turn on IBAT buffer
6-5	EN_PROCHOT_LPWR	R/W	00b	Enable $\overline{\text{PROCHOT}}$ during battery only low power mode With battery only, enable IDCHG or VSYS in $\overline{\text{PROCHOT}}$ with low power consumption. Do not enable this function with adapter present. Refer to <a href="#">PROCHOT During Low Power Mode</a> for more details. 00b: Disable low power $\overline{\text{PROCHOT}}$ <default at POR> 01b: Enable IDCHG low power $\overline{\text{PROCHOT}}$ 10b: Enable VSYS low power $\overline{\text{PROCHOT}}$ 11b: Reserved
4	EN_PSYS	R/W	0b	PSYS Enable Enable PSYS sensing circuit and output buffer (whole PSYS circuit). In low power mode (REG0x01[7] = 1), PSYS sensing and buffer are always disabled regardless of this bit value. 0b: Turn off PSYS buffer to minimize Iq <default at POR> 1b: Turn on PSYS buffer
3	RSNS_RAC	R/W	0b	Input sense resistor RAC 0b: 10 mΩ <default at POR> 1b: 20 mΩ
2	RSNS_RSR	R/W	0b	Charge sense resistor RSR 0b: 10 mΩ <default at POR> 1b: 20 mΩ
1	PSYS_RATIO	R/W	1b	PSYS Gain Ratio of PSYS output current vs total input and battery power with 10-mΩ sense resistor. 0b: 0.25 μA/W 1b: 1 μA/W <default at POR>
0	Reserved	R/W	0b	Reserved

**Table 8. ChargeOption1 Register (I2C address = 30h) Field Descriptions**

I2C 30h	FIELD	TYPE	RESET	DESCRIPTION
7	CMP_REF	R/W	0b	Independent Comparator Reference Independent comparator internal reference. 0b: 2.4 V <default at POR> 1b: 1.3 V

**Table 8. ChargeOption1 Register (I2C address = 30h) Field Descriptions (continued)**

I2C 30h	FIELD	TYPE	RESET	DESCRIPTION
6	CMP_POL	R/W	0b	<p>Independent Comparator Polarity</p> <p>Independent comparator output polarity</p> <p>0b: When CMPIN is above internal threshold, CMPOUT is LOW (internal hysteresis) &lt;default at POR&gt;</p> <p>1b: When CMPIN is below internal threshold, CMPOUT is LOW (external hysteresis)</p>
5-4	CMP_DEG	R/W	01b	<p>Independent Comparator Deglitch Time</p> <p>Independent comparator deglitch time, only applied to the falling edge of CMPOUT (HIGH → LOW).</p> <p>00b: Independent comparator is disabled</p> <p>01b: Independent comparator is enabled with output deglitch time 1 μs &lt;default at POR&gt;</p> <p>10b: Independent comparator is enabled with output deglitch time of 2 ms</p> <p>11b: Independent comparator is enabled with output deglitch time of 5 sec</p>
3	FORCE_LATCHOFF	R/W	0b	<p>Force Power Path Off</p> <p>When comparator triggers, charger turns off Q1 and Q4 (same as disable converter) so that the system is disconnected from the input source. At the same time, CHRГ_OK signal goes to LOW to notify the system.</p> <p>0b: Disable this function &lt;default at POR&gt;</p> <p>1b: Enable this function</p>
2	Reserved	R/W	0b	Reserved
1	EN_SHIP_DCHG	R/W	0b	<p>Discharge SRN for Shipping Mode</p> <p>When this bit is 1, discharge SRN pin down below 3.8 V in 140 ms. When 140 ms is over, this bit is reset to 0.</p> <p>0b: Disable shipping mode &lt;default at POR&gt;</p> <p>1b: Enable shipping mode</p>
0	AUTO_WAKEUP_EN	R/W	1b	<p>Auto Wakeup Enable</p> <p>When this bit is HIGH, if the battery is below minimum system voltage (REG0x0D/0C()), the device will automatically enable 128 mA charging current for 30 mins. When the battery is charged up above minimum system voltage, charge will terminate and the bit is reset to LOW.</p> <p>0b: Disable</p> <p>1b: Enable &lt;default at POR&gt;</p>

**8.6.1.3 ChargeOption2 Register (I2C address = 33h/32h) [reset = 2B7]**
**Figure 25. ChargeOption2 Register (I2C address = 33h/32h) [reset = 2B7]**

15	14	13	12	11	10	9	8
PKPWR_TOVLD_DEG		EN_PKPWR_IDPM	EN_PKPWR_VSYS	PKPWR_OVLD_STAT	PKPWR_RELAX_STAT	PKPWR_TMAX[1:0]	
R/W		R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0
EN_EXTILIM	EN_ICHG_IDCHG	Q2_OCP	ACX_OCP	EN_ACOC	ACOC_VTH	EN_BATOC	BATOC_VTH
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 9. ChargeOption2 Register (I2C address = 33h) Field Descriptions**

I2C 33h	FIELD	TYPE	RESET	DESCRIPTION
7-6	PKPWR_TOVLD_DEG	R/W	00b	Input Overload time in Peak Power Mode 00b: 1 ms <default at POR> 01b: 2 ms 10b: 10 ms 11b: 20 ms
5	EN_PKPWR_IDPM	R/W	0b	Enable Peak Power Mode triggered by input current overshoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapter removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by input current overshoot <default at POR> 1b: Enable peak power mode triggered by input current overshoot.
4	EN_PKPWR_VSYS	R/W	0b	Enable Peak Power Mode triggered by system voltage under-shoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapter removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by system voltage under-shoot <default at POR> 1b: Enable peak power mode triggered by system voltage under-shoot.
3	PKPWR_OVLD_STAT	R/W	0b	Indicator that the device is in overloading cycle. Write 0 to get out of overloading cycle. 0b: Not in peak power mode. <default at POR> 1b: In peak power mode.
2	PKPWR_RELAX_STAT	R/W	0b	Indicator that the device is in relaxation cycle. Write 0 to get out of relaxation cycle. 0b: Not in relaxation cycle. <default at POR> 1b: In relaxation mode.
1-0	PKPWR_TMAX[1:0]	R/W	10b	Peak power mode overload and relax cycle time. When REG0x33[7:6] is programmed longer than REG0x33[1:0], there is no relax time. 00b: 5 ms 01b: 10 ms 10b: 20 ms <default at POR> 11b: 40 ms

**Table 10. ChargeOption2 Register (I2C address = 32h) Field Descriptions**

I2C 32h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_EXTILIM	R/W	1b	Enable ILIM_HIZ pin to set input current limit 0b: Input current limit is set by REG0x0F/0E. 1b: Input current limit is set by the lower value of ILIM_HIZ pin and REG0x0F/0E. <default at POR>
6	EN_ICHG_IDCHG	R/W	0b	0b: IBAT pin as discharge current. <default at POR> 1b: IBAT pin as charge current.
5	Q2_OCP	R/W	1b	Q2 OCP threshold by sensing Q2 VDS 0b: 210 mV 1b: 150 mV <default at POR>
4	ACX_OCP	R/W	1b	Input current OCP threshold by sensing ACP-ACN. 0b: 280 mV 1b: 150 mV <default at POR>
3	EN_ACOC	R/W	0b	ACOC Enable Input overcurrent (ACOC) protection by sensing the voltage across ACP and ACN. Upon ACOC (after 100- $\mu$ s blank-out time), converter is disabled. 0b: Disable ACOC <default at POR> 1b: ACOC threshold 125% or 200% ICRIT
2	ACOC_VTH	R/W	1b	ACOC Limit Set MOSFET OCP threshold as percentage of IDPM with current sensed from R <sub>AC</sub> . 0b: 125% of ICRIT 1b: 210% of ICRIT <default at POR>
1	EN_BATOC	R/W	1b	BATOC Enable Battery discharge overcurrent (BATOC) protection by sensing the voltage across SRN and SRP. Upon BATOC, converter is disabled. 0b: Disable BATOC 1b: BATOC threshold 125% or 200% $\overline{\text{PROCHOT}}$ IDCHG <default at POR>
0	BATOC_VTH	R/W	1b	Set battery discharge overcurrent threshold as percentage of $\overline{\text{PROCHOT}}$ battery discharge current limit. 0b: 125% of $\overline{\text{PROCHOT}}$ IDCHG 1b: 200% of $\overline{\text{PROCHOT}}$ IDCHG <default at POR>

**8.6.1.4 ChargeOption3 Register (I2C address = 35h/34h) [reset = 0h]**
**Figure 26. ChargeOption3 Register (I2C address = 35h/34h) [reset = 0h]**

15	14	13	12	11	10	9	8
EN_HIZ	RESET_REG	RESET_VINDPM	EN_OTG	EN_ICO_MODE	Reserved		
R/W	R/W	R/W	R/W	R/W	R/W		
7	6	5	4	3	2	1	0
Reserved						BATFETOFF_HIZ	PSYS_OTG_IDCHG
R/W						R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 11. ChargeOption3 Register (I2C address = 35h) Field Descriptions**

I2C 35h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_HIZ	R/W	0b	Device Hi-Z Mode Enable When the charger is in Hi-Z mode, the device draws minimal quiescent current. With VBUS above UVLO. REGN LDO stays on, and system powers from battery. 0b: Device not in Hi-Z mode <default at POR> 1b: Device in Hi-Z mode
6	RESET_REG	R/W	0b	Reset Registers All the registers go back to the default setting except the VINDPM register. 0b: Idle <default at POR> 1b: Reset all the registers to default values. After reset, this bit goes back to 0.
5	RESET_VINDPM	R/W	0b	Reset VINDPM Threshold 0b: Idle 1b: Converter is disabled to measure VINDPM threshold. After VINDPM measurement is done, this bit goes back to 0 and converter starts.
4	EN_OTG	R/W	0b	OTG Mode Enable Enable device in OTG mode when EN_OTG pin is HIGH. 0b: Disable OTG <default at POR> 1b: Enable OTG mode to supply VBUS from battery.
3	EN_ICO_MODE	R/W	0b	Enable ICO Algorithm 0b: Disable ICO algorithm. <default at POR> 1b: Enable ICO algorithm.
2-0	Reserved	R/W	0b	Reserved

**Table 12. ChargeOption3 Register (I2C address = 34h) Field Descriptions**

I2C 34h	FIELD	TYPE	RESET	DESCRIPTION
7-2	Reserved	R/W	0b	Reserved
1	BATFETOFF_HIZ	R/W	0b	Control BATFET during HIZ mode. 0b: BATFET on during Hi-Z 1b: BATFET off during Hi-Z
0	PSYS_OTG_IDCHG	R/W	0b	PSYS function during OTG mode. 0b: PSYS as battery discharge power minus OTG output power 1b: PSYS as battery discharge power only



**8.6.1.5 ProchotOption0 Register (I2C address = 37h/36h) [reset = 04A54h]**
**Figure 27. ProchotOption0 Register (I2C address = 37h/36h) [reset = 04A54h]**

15-11			10-9		8	
ILIM2_VTH			ICRIT_DEG		Reserved	
R/W			R/W		R/W	
7-6	5	4-3		2	1	0
VSYS_VTH	EN_PROCHOT_EXT	PROCHOT_WIDTH		PROCHOT_CLEAR	INOM_DEG	Reserved
R/W	R/W	R/W		R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 13. ProchotOption0 Register (I2C address = 37h) Field Descriptions**

I2C 37h	FIELD	TYPE	RESET	DESCRIPTION
7-3	ILIM2_VTH	R/W	01001b	$I_{LIM2}$ Threshold 5 bits, percentage of IDPM in 0x0F/0EH. Measure current between ACP and ACN. Trigger when the current is above this threshold: 00001b - 11001b: 110% - 230%, step 5% 11010b - 11110b: 250% - 450%, step 50% 11111b: Out of Range (Ignored) Default 150%, or 01001
2-1	ICRIT_DEG	R/W	01b	ICRIT Deglitch time ICRIT is set to be 110% of $I_{LIM2}$ . Typical ICRIT deglitch time to trigger $\overline{PROCHOT}$ . 00b: 15 $\mu$ s 01b: 100 $\mu$ s <default at POR> 10b: 400 $\mu$ s (max 500 us) 11b: 800 $\mu$ s (max 1 ms)
0	Reserved	R/W	0b	Reserved

**Table 14. ProchotOption0 Register (I2C address = 36h) Field Descriptions**

I2C 36h	FIELD	TYPE	RESET	DESCRIPTION
7-6	VSYS_VTH	R/W	01b	VSYS Threshold Measure on VSYS with fixed 20- $\mu$ s deglitch time. Trigger when SYS pin voltage is below the threshold. 00b: 5.75 V (2-4 s) or 2.85 V (1 s) 01b: 6 V (2-4 s) or 3.1 V (1 s) <default at POR> 10b: 6.25 V (2-4 s) or 3.35 V (1 s) 11b: 6.5 V (2-4 s) or 3.6 V (1 s)
5	EN_PROCHOT_EXT	R/W	0b	When pulse extension is enabled, keep the $\overline{PROCHOT}$ pin voltage LOW until host writes 0x36[2] = 0. 0b: Disable pulse extension <default at POR> 1b: Enable pulse extension
4-3	PROCHOT_WIDTH	R/W	10b	$\overline{PROCHOT}$ Pulse Width $\overline{PROCHOT}$ Pulse Extension Enable Minimum $\overline{PROCHOT}$ pulse width when REG0x36[5] = 0 00b: 100 $\mu$ s 01b: 1 ms 10b: 10 ms <default at POR> 11b: 5 ms

**Table 14. ProchotOption0 Register (I2C address = 36h) Field Descriptions (continued)**

I2C 36h	FIELD	TYPE	RESET	DESCRIPTION
2	PROCHOT_CLEAR	R/W	1b	<p><math>\overline{\text{PROCHOT}}</math> Pulse Clear</p> <p>Clear <math>\overline{\text{PROCHOT}}</math> pulse when 0x36[5] = 1.</p> <p>0b: Clear <math>\overline{\text{PROCHOT}}</math> pulse and drive <math>\overline{\text{PROCHOT}}</math> pin HIGH.</p> <p>1b: Idle &lt;default at POR&gt;</p>
1	INOM_DEG	R/W	0b	<p>INOM Deglitch Time</p> <p>INOM is always 10% above IDPM in 0x0F/0EH. Measure current between ACP and ACN.</p> <p>Trigger when the current is above this threshold.</p> <p>0b: 1 ms (must be max) &lt;default at POR&gt;</p> <p>1b: 50 ms (max 60 ms)</p>
0	Reserved	R/W	0b	Reserved

**8.6.1.6 ProchotOption1 Register (I2C address = 39h/38h) [reset = 8120h]**
**Figure 28. ProchotOption1 Register (I2C address = 39h/38h) [reset = 8120h]**

15-10					9-8		
IDCHG_VTH					IDCHG_DEG		
R/W					R/W		
7	6	5	4	3	2	1	0
Reserved	PROCHOT_PROFILE_IC	PP_ICRIT	PP_INOM	PP_IDCHG	PP_VSYS	PP_BATPRES	PP_ACOK
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 15. ProchotOption1 Register (I2C address = 39h) Field Descriptions**

I2C 39h	FIELD	TYPE	RESET	DESCRIPTION
7-2	IDCHG_VTH	R/W	000000b	IDCHG Threshold 6 bit, range, range 0 A to 32256 mA, step 512 mA. Measure current between SRN and SRP. Trigger when the discharge current is above the threshold. If the value is programmed to 0 mA, $\overline{\text{PROCHOT}}$ is always triggered. Default: 16384 mA or 100000
1-0	IDCHG_DEG	R/W	01b	IDCHG Deglitch Time 00b: 1.6 ms 01b: 100 $\mu$ s <default at POR> 10b: 6 ms 11b: 12 ms

**Table 16. ProchotOption1 Register (I2C address = 38h) Field Descriptions**

I2C 38h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Reserved
6	PROCHOT_PROFILE_COMP	R/W	0b	$\overline{\text{PROCHOT}}$ Profile When all the REG0x34[6:0] bits are 0, $\overline{\text{PROCHOT}}$ function is disabled. Bit6 Independent comparator 0b: disable <default at POR> 1b: enable
5	PROCHOT_PROFILE_ICRIT	R/W	1b	0b: disable 1b: enable <default at POR>
4	PROCHOT_PROFILE_INOM	R/W	0b	0b: disable <default at POR> 1b: enable
3	PROCHOT_PROFILE_IDCHG	R/W	0b	0b: disable <default at POR> 1b: enable
2	PROCHOT_PROFILE_VSYS	R/W	0b	0b: disable <default at POR> 1b: enable
1	PROCHOT_PROFILE_BATPRES	R/W	0b	0b: disable <default at POR> 1b: enable (one-shot falling edge triggered) If BATPRES is enabled in $\overline{\text{PROCHOT}}$ after the battery is removed, it will immediately send out one-shot $\overline{\text{PROCHOT}}$ pulse.

**Table 16. ProchotOption1 Register (I2C address = 38h) Field Descriptions (continued)**

I2C 38h	FIELD	TYPE	RESET	DESCRIPTION
0	PROCHOT _PROFILE_ACOK	R/W	0b	0b: disable <default at POR> 1b: enable ChargeOption0[15] = 0 to assert $\overline{\text{PROCHOT}}$ pulse after adapter removal. If PROCHOT_PROFILE_ACOK is enabled in $\overline{\text{PROCHOT}}$ after the adapter is removed, it will be pulled low.

**8.6.1.7 ADCOption Register (I2C address = 3B/3Ah) [reset = 2000h]**
**Figure 29. ADCOption Register (I2C address = 3B/3Ah) [reset = 2000h]**

15		14		13		12-8									
ADC_CONV		ADC_START		ADC_FULLSCALE		Reserved									
R/W		R/W		R/W		R/W									
7		6		5		4		3		2		1		0	
EN_ADC_CMPIN		EN_ADC_VBUS		EN_ADC_PSYS		EN_ADC_IIN		EN_ADC_IDCHG		EN_ADC_ICHG		EN_ADC_VSYS		EN_ADC_VBAT	
R/W		R/W		R/W		R/W		R/W		R/W		R/W		R/W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

The ADC registers are read in the following order: VBAT, VSYS, ICHG, IDCHG, IIN, PSYS, VBUS, CMPIN. ADC is disabled in low power mode. When enabling ADC, the device exit low power mode at battery only.

**Table 17. ADCOption Register (I2C address = 3Bh) Field Descriptions**

I2C 3Bh	FIELD	TYPE	RESET	DESCRIPTION
7	ADC_CONV	R/W	0b	Typical ADC conversion time is 10 ms. 0b: One-shot update. Do one set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() after ADC_START = 1. 1b: Continuous update. Do a set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() every 1 sec.
6	ADC_START	R/W	0b	0b: No ADC conversion 1b: Start ADC conversion. After the one-shot update is complete, this bit automatically resets to zero
5	ADC_FULLSCALE	R/W	1b	ADC input voltage range. When input voltage is below 5 V, or battery is 1S, full scale 2.04 V is recommended. 0b: 2.04 V 1b: 3.06 V <default at POR>
4-0	Reserved	R/W	00000b	Reserved

**Table 18. ADCOption Register (I2C address = 3Ah) Field Descriptions**

I2C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
7	EN_ADC_CMPIN	R/W	0b	0b: Disable <default at POR> 1b: Enable
6	EN_ADC_VBUS	R/W	0b	0b: Disable <default at POR> 1b: Enable
5	EN_ADC_PSYS	R/W	0b	0b: Disable <default at POR> 1b: Enable
4	EN_ADC_IIN	R/W	0b	0b: Disable <default at POR> 1b: Enable
3	EN_ADC_IDCHG	R/W	0b	0b: Disable <default at POR> 1b: Enable
2	EN_ADC_ICHG	R/W	0b	0b: Disable <default at POR> 1b: Enable
1	EN_ADC_VSYS	R/W	0b	0b: Disable <default at POR> 1b: Enable

**Table 18. ADCOption Register (I2C address = 3Ah) Field Descriptions (continued)**

I2C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
0	EN_ADC_VBAT	R/W	0b	0b: Disable <default at POR> 1b: Enable

## 8.6.2 Charge and PROCHOT Status

### 8.6.2.1 ChargerStatus Register (I2C address = 21/20h) [reset = 0000h]

**Figure 30. ChargerStatus Register (I2C address = 21/20h) [reset = 0000h]**

15	14	13	12	11	10	9	8
AC_STAT	ICO_DONE	Reserved	IN_VINDPM	IN_IINDPM	IN_FCHRG	IN_PCHRG	IN_OTG
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Fault ACOV	Fault BATOC	Fault ACOC	YSOVP_STAT	Reserved	Fault Latchoff	Fault_OTG_OVP	Fault_OTG_OCP
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 19. ChargerStatus Register (I2C address = 21h) Field Descriptions**

I2C 21h	FIELD	TYPE	RESET	DESCRIPTION
7	AC_STAT	R	0b	Input source status, same as CHRG_OK bit 0b: Input not present 1b: Input is present
6	ICO_DONE	R	0b	After the ICO routine is successfully executed, the bit goes 1. 0b: ICO is not complete 1b: ICO is complete
5	Reserved	R	0b	Reserved
4	IN_VINDPM	R	0b	0b: Charger is not in VINDPM during forward mode, or voltage regulation during OTG mode 1b: Charger is in VINDPM during forward mode, or voltage regulation during OTG mode
3	IN_IINDPM	R	0b	0b: Charger is not in IINDPM 1b: Charger is in IINDPM
2	IN_FCHRG	R	0b	0b: Charger is not in fast charge 1b: Charger is in fast charge
1	IN_PCHRG	R	0b	0b: Charger is not in pre-charge 1b: Charger is in pre-charge
0	IN_OTG	R	0b	0b: Charger is not in OTG 1b: Charge is in OTG

**Table 20. ChargerStatus Register (I2C address = 20h) Field Descriptions**

I2C 20h	FIELD	TYPE	RESET	DESCRIPTION
7	Fault ACOV	R	0b	The faults are latched until a read from host. 0b: No fault 1b: ACOV
6	Fault BATOC	R	0b	The faults are latched until a read from host. 0b: No fault 1b: BATOC
5	Fault ACOC	R	0b	The faults are latched until a read from host. 0b: No fault 1b: ACOC

**Table 20. ChargerStatus Register (I2C address = 20h) Field Descriptions (continued)**

I2C 20h	FIELD	TYPE	RESET	DESCRIPTION
4	SYSOVP_STAT	R	0b	SYSOVP Status and Clear When the SYSOVP occurs, this bit is HIGH. During the SYSOVP, the converter is disabled. After the SYSOVP is removed, the user must write a 0 to this bit or unplug the adapter to clear the SYSOVP condition to enable the converter again. 0b: Not in SYSOVP <default at POR> 1b: In SYSOVP. When SYSOVP is removed, write 0 to clear the SYSOVP latch.
3	Reserved	R	0b	Reserved
2	Fault Latchoff	R	0b	The faults are latched until a read from host. 0b: No fault 1b: Latch off (REG0x30[3])
1	Fault_OTG_OVP	R	0b	The faults are latched until a read from host. 0b: No fault 1b: OTG OVP
0	Fault_OTG_UCP	R	0b	The faults are latched until a read from host. 0b: No fault 1b: OTG OCP



**8.6.2.2 ProchotStatus Register (I2C address = 23/22h) [reset = 0h]**
**Figure 31. ProchotStatus Register (I2C address = 23/22h) [reset = 0h]**

15-8							
Reserved							
R							
7	6	5	4	3	2	1	0
Reserved	STAT_COMP	STAT_ICRIT	STAT_INOM	STAT_IDCHG	STAT_VSYS	STAT_Battery_ Removal	STAT_Adapter_ Removal
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 21. ProchotStatus Register (I2C address = 23h) Field Descriptions**

I2C 23h	FIELD	TYPE	RESET	DESCRIPTION
–	Reserved	R	0b	Reserved

**Table 22. ProchotStatus Register (I2C address = 22h) Field Descriptions**

I2C 22h	FIELD	TYPE	RESET	DESCRIPTION
–	Reserved	R	0b	Reserved
6	STAT_COMP	R	0b	0b: Not triggered 1b: Triggered
5	STAT_ICRIT	R	0b	0b: Not triggered 1b: Triggered
4	STAT_INOM	R	0b	0b: Not triggered 1b: Triggered
3	STAT_IDCHG	R	0b	0b: Not triggered 1b: Triggered
2	STAT_VSYS	R	0b	0b: Not triggered 1b: Triggered
1	STAT_Battery_Removal	R	0b	0b: Not triggered 1b: Triggered
0	STAT_Adapter_Removal	R	0b	0b: Not triggered 1b: Triggered

### 8.6.3 ChargeCurrent Register (I2C address = 03/02h) [reset = 0h]

To set the charge current, write a 16-bit ChargeCurrent() command (REG0x03/02()) using the data format listed in Table 23 and Table 24.

With 10-mΩ sense resistor, the charger provides charge current range of 64 mA to 8.128 A, with a 64-mA step resolution. Upon POR, ChargeCurrent() is 0 A. Any conditions for CHRГ\_OK low except ACOV will reset ChargeCurrent() to zero. CELL\_BATPRESZ going LOW (battery removal) will reset the ChargeCurrent() register to 0 A.

Charge current is not reset in ACOC, TSHUT, power path latch off (REG0x30[1]), and SYSOVP.

A 0.1-μF capacitor between SRP and SRN for differential mode filtering is recommended; an optional 0.1-μF capacitor between SRN and ground, and an optional 0.1-μF capacitor between SRP and ground for common mode filtering. Meanwhile, the capacitance on SRP should not be higher than 0.1 μF in order to properly sense the voltage across SRP and SRN for cycle-by-cycle current detection.

The SRP and SRN pins are used to sense voltage drop across RSR with default value of 10 mΩ. However, resistors of other values can also be used. For a larger sense resistor, a larger sense voltage is given, and a higher regulation accuracy; but, at the expense of higher conduction loss. If current sensing resistor value is too high, it may trigger an over current protection threshold because the current ripple voltage is too high. In such a case, either a higher inductance value or a lower current sensing resistor value should be used to limit the current ripple voltage level. A current sensing resistor value no more than 20 mΩ is suggested.

**Figure 32. ChargeCurrent Register With 10-mΩ Sense Resistor (I2C address = 03/02h) [reset = 0h]**

15		14		13		12		11		10		9		8	
Reserved				Charge Current, bit 6		Charge Current, bit 5		Charge Current, bit 4		Charge Current, bit 3		Charge Current, bit 2			
R/W				R/W		R/W		R/W		R/W		R/W		R/W	
7		6		5		4		3		2		1		0	
Charge Current, bit 1		Charge Current, bit 0		Reserved						Reserved					
R/W		R/W		R/W						R/W					

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 23. Charge Current Register (14h) With 10-mΩ Sense Resistor (I2C address = 03h) Field Descriptions**

I2C 03h	FIELD	TYPE	RESET	DESCRIPTION
7-5	Reserved	R/W	000b	Not used. 1 = invalid write.
4	Charge Current, bit 6	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 4096 mA of charger current.
3	Charge Current, bit 5	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 2048 mA of charger current.
2	Charge Current, bit 4	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 1024 mA of charger current.
1	Charge Current, bit 3	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 512 mA of charger current.
0	Charge Current, bit 2	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 256 mA of charger current.

**Table 24. Charge Current Register (14h) With 10-mΩ Sense Resistor (I2C address = 02h) Field Descriptions**

I2C 02h	FIELD	TYPE	RESET	DESCRIPTION
7	Charge Current, bit 1	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 128 mA of charger current.

**Table 24. Charge Current Register (14h) With 10-mΩ Sense Resistor (I2C address = 02h) Field Descriptions (continued)**

I2C 02h	FIELD	TYPE	RESET	DESCRIPTION
6	Charge Current, bit 0	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 64 mA of charger current.
5-0	Reserved	R/W	000000b	Not used. Value Ignored.

### 8.6.3.1 Battery Pre-Charge Current Clamp

During pre-charge, BATFET works in linear mode or LDO mode (default REG0x00[2] = 1). For 2-4 cell battery, the system is regulated at minimum system voltage in REG0x0D/0C() and the pre-charge current is clamped at 384 mA. For 1 cell battery, the pre-charge to fast charge threshold is 3 V, and the pre-charge current is clamped at 384 mA. However, the BATFET stays in LDO mode operation till battery voltage is above minimum system voltage (~3.6 V). During battery voltage from 3 V to 3.6 V, the fast charge current is clamped at 2 A.

### 8.6.4 MaxChargeVoltage Register (I2C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]

To set the output charge voltage, write a 16-bit ChargeVoltage register command (REG0x05/04()) using the data format listed in [Table 25](#) and [Table 26](#). The charger provides charge voltage range from 1.024 V to 19.200 V, with 16-mV step resolution. Any write below 1.024 V or above 19.200 V is ignored. Upon POR or when charge is disabled, the system is regulated at the MaxChargeVoltage register.

Upon POR, REG0x05/04() is by default set as 4192 mV for 1 s, 8400 mV for 2 s, 12592 mV for 3 s or 16800 mV for 4 s. After CHRГ\_OK, if host writes REG0x03/02() before REG0x05/04(), the charge will start after the write to REG0x03/02(). If the battery is different from 4.2 V/cell, the host has to write to REG0x05/04() before REG0x03/02() for correct battery voltage setting. Writing REG0x05/04() to 0 will set REG0x05/04() to default value on CELL\_BATPRESZ pin, and force REG0x03/02() to zero to disable charge.

The SRN pin is used to sense the battery voltage for voltage regulation and should be connected as close to the battery as possible, and directly place a decoupling capacitor (0.1  $\mu$ F recommended) as close to the device as possible to decouple high frequency noise.

**Figure 33. MaxChargeVoltage Register (I2C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]**

15	14	13	12	11	10	9	8
Reserved	Max Charge Voltage, bit 10	Max Charge Voltage, bit 9	Max Charge Voltage, bit 8	Max Charge Voltage, bit 7	Max Charge Voltage, bit 6	Max Charge Voltage, bit 5	Max Charge Voltage, bit 4
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Max Charge Voltage, bit 3	Max Charge Voltage, bit 2	Max Charge Voltage, bit 1	Max Charge Voltage, bit 0	Reserved			
R/W	R/W	R/W	R/W	R/W			

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 25. MaxChargeVoltage Register (I2C address = 05h) Field Descriptions**

I2C 05h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Max Charge Voltage, bit 10	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 16384 mV of charger voltage.
5	Max Charge Voltage, bit 9	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 8192 mV of charger voltage
4	Max Charge Voltage, bit 8	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 4096 mV of charger voltage.
3	Max Charge Voltage, bit 7	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 2048 mV of charger voltage.
2	Max Charge Voltage, bit 6	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 1024 mV of charger voltage.
1	Max Charge Voltage, bit 5	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 512 mV of charger voltage.
0	Max Charge Voltage, bit 4	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 256 mV of charger voltage.

**Table 26. MaxChargeVoltage Register (I2C address = 04h) Field Descriptions**

I2C 04h	FIELD	TYPE	RESET	DESCRIPTION
7	Max Charge Voltage, bit 3	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 128 mV of charger voltage.

**Table 26. MaxChargeVoltage Register (I2C address = 04h) Field Descriptions (continued)**

I2C 04h	FIELD	TYPE	RESET	DESCRIPTION
6	Max Charge Voltage, bit 2	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 64 mV of charger voltage.
5	Max Charge Voltage, bit 1	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 32 mV of charger voltage.
4	Max Charge Voltage, bit 0	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 16 mV of charger voltage.
3-0	Reserved	R/W	0000b	Not used. Value Ignored.

### 8.6.5 MinSystemVoltage Register (I2C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]

To set the minimum system voltage, write a 16-bit MinSystemVoltage register command (REG0x0D/0C()) using the data format listed in [Table 27](#) and [Table 28](#). The charger provides minimum system voltage range from 1.024 V to 16.128 V, with 256-mV step resolution. Any write below 1.024 V or above 16.128 V is ignored. Upon POR, the MinSystemVoltage register is 3.584 V for 1 S, 6.144 V for 2 S and 9.216 V for 3 S, and 12.288 V for 4 S.

**Figure 34. MinSystemVoltage Register (I2C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]**

15	14	13	12	11	10	9	8
Reserved		Min System Voltage, bit 5	Min System Voltage, bit 4	Min System Voltage, bit 3	Min System Voltage, bit 2	Min System Voltage, bit 1	Min System Voltage, bit 0
R/W		R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Reserved							
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 27. MinSystemVoltage Register (I2C address = 0Dh) Field Descriptions**

I2C 0Dh	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Min System Voltage, bit 5	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 8192 mV of system voltage.
4	Min System Voltage, bit 4	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 4096mV of system voltage.
3	Min System Voltage, bit 3	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 2048 mV of system voltage.
2	Min System Voltage, bit 2	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 1024 mV of system voltage.
1	Min System Voltage, bit 1	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 512 mV of system voltage.
0	Min System Voltage, bit 0	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 256 mV of system voltage.

**Table 28. MinSystemVoltage Register (I2C address = 0Ch) Field Descriptions**

I2C 0Ch	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R/W	0000000 0b	Not used. Value Ignored.

#### 8.6.5.1 System Voltage Regulation

The device employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by REG0x0D/0C(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage with BATFET.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode), and the system is regulated above the minimum system voltage setting. As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

When BATFET is removed, the system node VSYS is shorted to SRP. Before the converter starts operation, LDO mode needs to be disabled. The following sequence is required to configure charger without BATFET.

1. Before adapter plugs in, put the charger into HIZ mode. (either pull pin 6 ILIM\_HIZ to ground, or set

- REG0x35[7] to 1)
2. Set 0x00[2] to 0 to disable LDO mode.
  3. Set 0x30[0] to 0 to disable auto-wakeup mode.
  4. Check if battery voltage is properly programmed (REG0x05/04)
  5. Set pre-charge/charge current (REG0x03/02)
  6. Put the device out of HIZ mode. (Release ILIM\_HIZ from ground and set REG0x35[7]=0).

In order to prevent any accidental SW mistakes, the host sets low input current limit (a few hundred milliamps) when device is out of HIZ.

## 8.6.6 Input Current and Input Voltage Registers for Dynamic Power Management

The charger supports Dynamic Power Management (DPM). Normally, the input power source provides power for the system load or to charge the battery. When the input current exceeds the input current setting, or the input voltage falls below the input voltage setting, the charger decreases the charge current to provide priority to the system load. As the system current rises, the available charge current drops accordingly toward zero. If the system load keeps increasing after the charge current drops down to zero, the system voltage starts to drop. As the system voltage drops below the battery voltage, the battery will discharge to supply the heavy system load.

### 8.6.6.1 Input Current Registers

To set the maximum input current limit, write a 16-bit IIN\_HOST register command (REG0x0F/0E()) using the data format listed in [Table 29](#) and [Table 30](#). When using a 10-mΩ sense resistor, the charger provides an input-current limit range of 50 mA to 6400 mA, with 50-mA resolution. The default current limit is 3.3 A. Due to the USB current setting requirement, the register setting specifies the maximum current instead of the typical current. Upon adapter removal, the input current limit is reset to the default value of 3.3 A. The register offset is 50 mA. With code 0, the input current limit is 50 mA.

The ACP and ACN pins are used to sense  $R_{AC}$  with the default value of 10 mΩ. However, resistors of other values can also be used. For a larger sense resistor, a larger sense voltage is given and a higher regulation accuracy, but at the expense of higher conduction loss.

Instead of using the internal DPM loop, the user can build up an external input current regulation loop and have the feedback signal on the ILIM\_HIZ pin.

$$V_{ILIM\_HIZ} = 1V + 40 \times (V_{ACP} - V_{ACN}) = 1 + 40 \times I_{DPM} \times R_{AC} \quad (2)$$

In order to disable ILIM\_HIZ pin, the host can write to 0x32[7] to disable ILIM\_HIZ pin, or pull ILIM\_HIZ pin above 4.0 V.

**8.6.6.1.1 IIN\_HOST Register With 10-mΩ Sense Resistor (I2C address = 0F/0Eh) [reset = 4000h]**
**Figure 35. IIN\_HOST Register With 10-mΩ Sense Resistor (I2C address = 0F/0Eh) [reset = 4100h]**

15	14	13	12	11	10	9	8
Reserved	Input Current set by host, bit 6	Input Current set by host, bit 5	Input Current set by host, bit 4	Input Current set by host, bit 3	Input Current set by host, bit 2	Input Current set by host, bit 1	Input Current set by host, bit 0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Reserved							
R							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 29. IIN\_HOST Register With 10-mΩ Sense Resistor (I2C address = 0Fh) Field Descriptions**

I2C 0Fh	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Input Current set by host, bit 6	R/W	1b	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current set by host, bit 5	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current set by host, bit 4	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 800 mA of input current.
3	Input Current set by host, bit 3	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current set by host, bit 2	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current set by host, bit 1	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current set by host, bit 0	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current.

**Table 30. IIN\_HOST Register With 10-mΩ Sense Resistor (I2C address = 0Eh) Field Descriptions**

I2C 0Eh	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R	0000000 0b	Not used. Value Ignored.



**8.6.6.1.2 IIN\_DPM Register With 10-mΩ Sense Resistor (I2C address = 25/24h) [reset = 0h]**

IIN\_DPM register reflects the actual input current limit programmed in the register, either from host or from ICO.

After ICO, the current limit used by DPM regulation may differ from the IIN\_HOST register settings. The actual DPM limit is reported in REG0x25/24(). The register offset is 50 mA. With code 0, the input current limit read-back is 50 mA.

**Figure 36. IIN\_DPM Register With 10-mΩ Sense Resistor (I2C address = 25/24h) [reset = 0h]**

15	14	13	12	11	10	9	8
Reserved	Input Current in DPM, bit 6	Input Current in DPM, bit 5	Input Current in DPM, bit 4	Input Current in DPM, bit 3	Input Current in DPM, bit 2	Input Current in DPM, bit 1	Input Current in DPM, bit 0
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Reserved							
R							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 31. IIN\_DPM Register With 10-mΩ Sense Resistor (I2C address = 25h) Field Descriptions**

I2C 25h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R	0b	Not used. 1 = invalid write.
6	Input Current in DPM, bit 6	R	0b	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current in DPM, bit 5	R	0b	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current in DPM, bit 4	R	0b	0 = Adds 0 mA of input current. 1 = Adds 800mA of input current
3	Input Current in DPM, bit 3	R	0b	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current in DPM, bit 2	R	0b	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current in DPM, bit 1	R	0b	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current in DPM, bit 0	R	0b	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current.

**Table 32. IIN\_DPM Register With 10-mΩ Sense Resistor (I2C address = 24h) Field Descriptions**

I2C 24h	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R	00000000b	Not used. Value Ignored.

**8.6.6.1.3 InputVoltage Register (I2C address = 0B/0Ah) [reset = VBUS-1.28V]**

To set the input voltage limit, write a 16-bit InputVoltage register command (REG0x0B/0A()) using the data format listed in [Table 33](#) and [Table 34](#).

If the input voltage drops more than the InputVoltage register allows, the device enters DPM and reduces the charge current. The default offset voltage is 1.28 V below the no-load VBUS voltage. The DC offset is 3.2 V (0000000).

**Figure 37. InputVoltage Register (I2C address = 0B/0Ah) [reset = VBUS-1.28V]**

15		14		13		12		11		10		9		8	
Reserved		Input Voltage, bit 7		Input Voltage, bit 6		Input Voltage, bit 5		Input Voltage, bit 4		Input Voltage, bit 3		Input Voltage, bit 2		Input Voltage, bit 1	
R/W		R/W		R/W		R/W		R/W		R/W		R/W		R/W	
7		6		5		4		3		2		1		0	
Input Voltage, bit 1		Input Voltage, bit 0		Reserved		Reserved		Reserved		Reserved		Reserved		Reserved	
R/W		R/W		R/W		R/W		R/W		R/W		R/W		R/W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 33. InputVoltage Register (I2C address = 0Bh) Field Descriptions**

I2C 0Bh	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Input Voltage, bit 7	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 8192 mV of input voltage.
4	Input Voltage, bit 6	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 4096mV of input voltage.
3	Input Voltage, bit 5	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 2048 mV of input voltage.
2	Input Voltage, bit 4	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 1024 mV of input voltage.
1	Input Voltage, bit 3	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 512 mV of input voltage.
0	Input Voltage, bit 2	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 256 mV of input voltage.

**Table 34. InputVoltage Register (I2C address = 0Ah) Field Descriptions**

I2C 0Ah	FIELD	TYPE	RESET	DESCRIPTION
7	Input Voltage, bit 1	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 128 mV of input voltage.
6	Input Voltage, bit 0	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 64 mV of input voltage
5-0	Reserved	R/W	000000b	Not used. Value Ignored.

### 8.6.7 OTGVoltage Register (I2C address = 07/06h) [reset = 0h]

To set the OTG output voltage limit, write to REG0x07/06() using the data format listed in [Table 35](#) and [Table 36](#). The DC offset is 4.48 V (0000000).

**Figure 38. OTGVoltage Register (I2C address = 07/06h) [reset = 0h]**

15		14		13		12		11		10		9		8	
Reserved		Reserved		OTG Voltage, bit 7		OTG Voltage, bit 6		OTG Voltage, bit 5		OTG Voltage, bit 4		OTG Voltage, bit 3		OTG Voltage, bit 2	
R/W		R/W		R/W		R/W		R/W		R/W		R/W		R/W	
7		6		5		4		3		2		1		0	
OTG Voltage, bit 1		OTG Voltage, bit 0		Reserved		Reserved		Reserved		Reserved		Reserved		Reserved	
R/W		R/W		R/W		R/W		R/W		R/W		R/W		R/W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 35. OTGVoltage Register (I2C address = 07h) Field Descriptions**

I2C 07h	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	OTG Voltage, bit 7	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 8192 mV of OTG voltage.
4	OTG Voltage, bit 6	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 4096 mV of OTG voltage.
3	OTG Voltage, bit 5	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 2048 mV of OTG voltage.
2	OTG Voltage, bit 4	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 1024 mV of OTG voltage.
1	OTG Voltage, bit 3	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 512 mV of OTG voltage.
0	OTG Voltage, bit 2	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 256 mV of OTG voltage.

**Table 36. OTGVoltage Register (I2C address = 06h) Field Descriptions**

I2C 06h	FIELD	TYPE	RESET	DESCRIPTION
7	OTG Voltage, bit 1	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 128 mV of OTG voltage.
6	OTG Voltage, bit 0	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 64 mV of OTG voltage.
5-0	Reserved	R/W	000000b	Not used. Value Ignored.

**8.6.8 OTGCurrent Register (I2C address = 09/08h) [reset = 0h]**

To set the OTG output current limit, write to REG0x09/08() using the data format listed in [Table 37](#) and [Table 38](#).

**Figure 39. OTGCurrent Register (I2C address = 09/08h) [reset = 0h]**

15	14	13	12	11	10	9	8
Reserved	OTG Current set by host, bit 6	OTG Current set by host, bit 5	OTG Current set by host, bit 4	OTG Current set by host, bit 3	OTG Current set by host, bit 2	OTG Current set by host, bit 1	OTG Current set by host, bit 0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Reserved							
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 37. OTGCurrent Register (I2C address = 09h) Field Descriptions**

I2C 09h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	OTG Current set by host, bit 6	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 3200 mA of OTG current.
5	OTG Current set by host, bit 5	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 1600mA of OTG current.
4	OTG Current set by host, bit 4	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 800 mA of OTG current.
3	OTG Current set by host, bit 3	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 400 mA of OTG current.
2	OTG Current set by host, bit 2	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 200 mA of OTG current.
1	OTG Current set by host, bit 1	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 100 mA of OTG current.
0	OTG Current set by host, bit 0	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 50 mA of OTG current.

**Table 38. OTGCurrent Register (I2C address = 08h) Field Descriptions**

I2C 08h	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R/W	00000000b	Not used. Value Ignored.

### 8.6.9 ADCVBUS/PSYS Register (I2C address = 27h)

- PSYS: Full range: 3.06 V, LSB: 12 mV
- VBUS: Full range: 3200 mV to 19520 mV, LSB: 64 mV

**Figure 40. ADCVBUS/PSYS Register (I2C address = 27h)**

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 39. ADCVBUS/PSYS Register Field Descriptions**

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of Input Voltage
7-0		R		8-bit Digital Output of System Power

**8.6.10 ADCIBAT Register (I2C address = 29h)**

- ICHG: Full range: 8.128 A, LSB 64: mA
- IDCHG: Full range: 32.512 A, LSB: 256 mA

**Figure 41. ADCIBAT Register (I2C address = 29h)**

15	14	13	12	11	10	9	8
Reserved	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Reserved	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 40. ADCIBAT Register Field Descriptions**

BIT	FIELD	TYPE	RESET	DESCRIPTION
15	Reserved	R		Not used. Value ignored.
14-8		R		7-bit Digital Output of Battery Charge Current
7	Reserved	R		Not used. Value ignored.
6-0		R		7-bit Digital Output of Battery Discharge Current

**8.6.11 ADCIINCMPIN Register (I2C address = 2Bh)**

- IIN: Full range: 12.75 A, LSB: 50 mA
- CMPIN: Full range: 3.06 V, LSB: 12 mV

**Figure 42. ADCIINCMPIN Register (I2C address = 2Bh)**

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 41. ADCIINCMPIN Register Field Descriptions**

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of Input Current
7-0		R		8-bit Digital Output of CMPIN voltage

**8.6.12 ADCVSYVBAT Register (I2C address = 2Dh) (reset = )**

- VSYS: Full range: 2.88 V to 19.2 V, LSB: 64 mV
- VBAT: Full range: 2.88 V to 19.2 V, LSB: 64 mV

**Figure 43. ADCVSYVBAT Register (I2C address = 2Dh) (reset = )**

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 42. ADCVSYVBAT Register Field Descriptions**

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of System Voltage
7-0		R		8-bit Digital Output of Battery Voltage



### 8.6.13 ID Registers

#### 8.6.13.1 ManufactureID Register (I2C address = 2Eh) [reset = 0040h]

**Figure 44. ManufactureID Register (I2C address = 2Eh) [reset = 0040h]**

15-0
MANUFACTURE_ID
R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 43. ManufactureID Register Field Descriptions**

I2C 2Eh	FIELD	TYPE	RESET	DESCRIPTION (READ ONLY)
7-0	MANUFACTURE_ID	R		40h

#### 8.6.13.2 Device ID (DeviceAddress) Register (I2C address = 2Fh) [reset = 0h]

**Figure 45. Device ID (DeviceAddress) Register (I2C address = 2Fh) [reset = 0h]**

15-8
Reserved
R
7-0
DEVICE_ID
R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

**Table 44. Device ID (DeviceAddress) Register Field Descriptions**

I2C 2Fh	FIELD	TYPE	RESET	DESCRIPTION (READ ONLY)
15-8	Reserved	R	0b	Reserved
7-0	DEVICE_ID	R	0b	I2C:78h

## 9 Application and Implementation

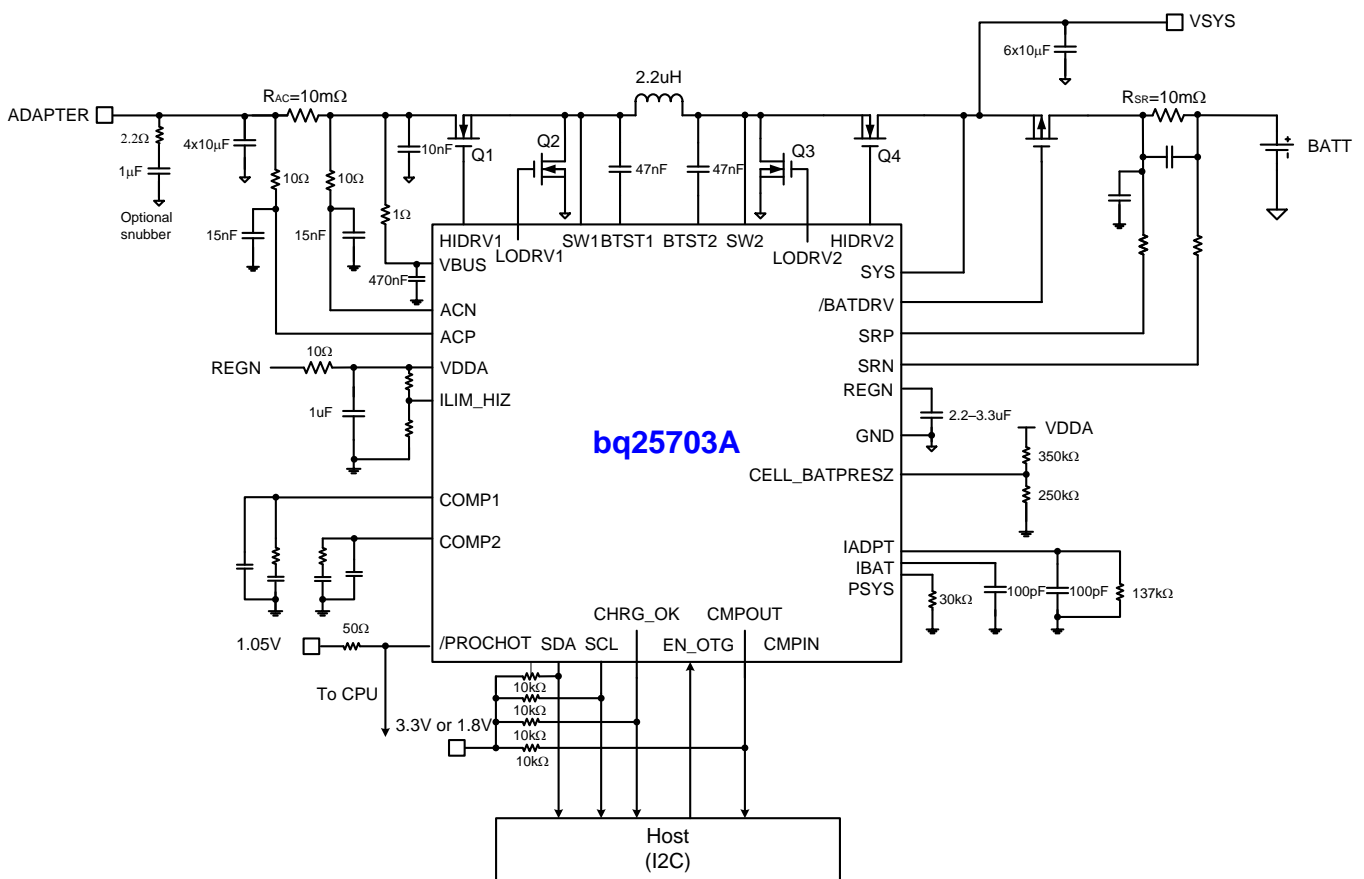
### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The bq2570xEVM-732 evaluation module (EVM) is a complete charger module for evaluating the bq25703A. The application curves were taken using the bq2570xEVM-732. Refer to the EVM user's guide (SLUUBG6) for EVM information.

### 9.2 Typical Application



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Figure 46. Application Diagram

#### 9.2.1 Design Requirements

DESIGN PARAMETER	EXAMPLE VALUE
Input Voltage <sup>(1)</sup>	3.5 V < Adapter Voltage < 24 V
Input Current Limit <sup>(1)</sup>	3.2 A for 65 W adapter
Battery Charge Voltage <sup>(2)</sup>	8400 mV for 2s battery

(1) Refer to adapter specification for settings for Input Voltage and Input Current Limit.

(2) Refer to battery specification for settings.

## Typical Application (continued)

DESIGN PARAMETER	EXAMPLE VALUE
Battery Charge Current <sup>(2)</sup>	3072 mA for 2s battery
Minimum System Voltage <sup>(2)</sup>	614 mV for 2s battery

### 9.2.2 Detailed Design Procedure

The parameters are configurable using the evaluation software. The simplified application circuit (see [Figure 46](#), as the application diagram) shows the minimum component requirements. Inductor, capacitor, and MOSFET selection are explained in the rest of this section. Refer to the EVM user's guide ([SLUUBG6](#)) for the complete application schematic.

#### 9.2.2.1 Input Snubber and Filter for Voltage Spike Damping

During adapter hot plug-in, the parasitic inductance and input capacitor from the adapter cable form a second order system. The voltage spike at VBUS pin maybe beyond IC maximum voltage rating and damage IC. The input filter must be carefully designed and tested to prevent over voltage event on VBUS pin.

There are several methods to damp or limit the over voltage spike during adapter hot plug-in. An electrolytic capacitor with high ESR as an input capacitor can damp the over voltage spike well below the IC maximum pin voltage rating. A high current capability TVS Zener diode can also limit the over voltage level to an IC safe level. However these two solutions may not have low cost or small size.

A cost effective and small size solution is shown in [Figure 47](#). The R1 and C1 are composed of a damping RC network to damp the hot plug-in oscillation. As a result the over voltage spike is limited to a safe level. D1 is used for reverse voltage protection for VBUS pin. C2 is VBUS pin decoupling capacitor and it should be placed as close as possible to VBUS pin. C2 value should be less than C1 value so R1 can dominate the equivalent ESR value to get enough damping effect. R2 is used to limit inrush current of D1 to prevent D1 getting damage when adapter hot plug-in. R2 and C2 should have 10  $\mu$ s time constant to limit the dv/dt on VBUS pin to reduce inrush current when adapter hot plug in. R1 has high inrush current. R1 package must be sized enough to handle inrush current power loss according to resistor manufacturer's data sheet. The filter components' value always need to be verified with real application and minor adjustments may need to fit in the real application circuit.

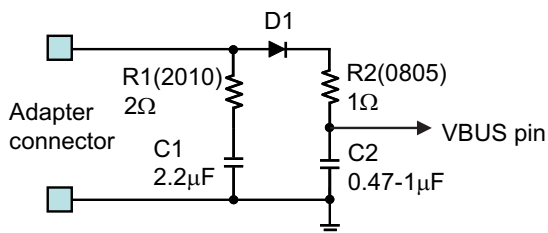
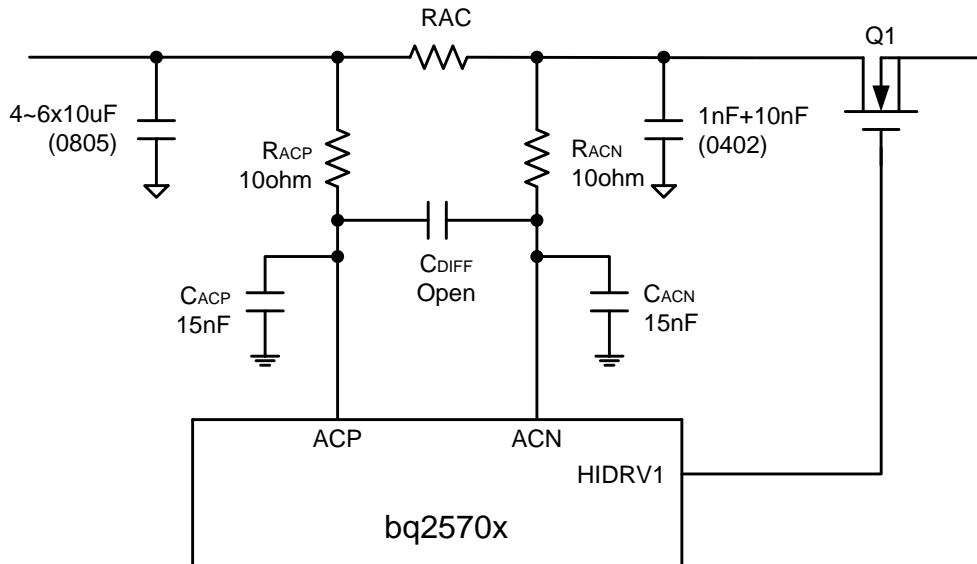


Figure 47. Input Filter

#### 9.2.2.2 ACP-ACN Input Filter

The bq25703A has average current mode control. The input current sensing through ACP/ACN is critical to recover inductor current ripple. Parasitic inductance on board will generate high frequency ringing on ACP-ACN which overwhelms converter sensed inductor current information, so it is difficult to manage parasitic inductance created based on different PCB layout. Bigger parasitic inductance will generate bigger sense current ringing which will cause the average current control loop to go into oscillation.

For real system board condition, we suggest to use below circuit design to get best result and filter noise induced from different PCB parasitic factor. With time constant of filter from 47 nsec to 200 nsec, the filtering on ringing is effective and in the meantime, the delay of on the sensed signal is small and therefore poses no concern for average current mode control.



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**Figure 48. ACN-ACP Input Filter**

### 9.2.2.3 Inductor Selection

The bq25703A has two selectable fixed switching frequency. Higher switching frequency allows the use of smaller inductor and capacitor values. Inductor saturation current should be higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPLE}$ ):

$$I_{SAT} \geq I_{CHG} + (1/2) I_{RIPPLE} \quad (3)$$

The inductor ripple current in buck operation depends on input voltage ( $V_{IN}$ ), duty cycle ( $D_{BUCK} = V_{OUT}/V_{IN}$ ), switching frequency ( $f_s$ ) and inductance ( $L$ ):

$$I_{RIPPLE\_BUCK} = \frac{V_{IN} \times D \times (1 - D)}{f_s \times L} \quad (4)$$

During boost operation, the duty cycle is:

$$D_{BOOST} = 1 - (V_{IN}/V_{BAT})$$

and the ripple current is:

$$I_{RIPPLE\_BOOST} = (V_{IN} \times D_{BOOST}) / (f_s \times L)$$

The maximum inductor ripple current happens with  $D = 0.5$  or close to 0.5. For example, the battery charging voltage range is from 9 V to 12.6 V for 3-cell battery pack. For 20-V adapter voltage, 10-V battery voltage gives the maximum inductor ripple current. Another example is 4-cell battery, the battery voltage range is from 12 V to 16.8 V, and 12-V battery voltage gives the maximum inductor ripple current.

Usually inductor ripple is designed in the range of (20 – 40%) maximum charging current as a trade-off between inductor size and efficiency for a practical design.

### 9.2.2.4 Input Capacitor

Input capacitor should have enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current when duty cycle is 0.5 in buck mode. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current occurs where the duty cycle is closest to 50% and can be estimated by Equation 5:

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1 - D)} \quad (5)$$

Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed to the drain of the high side MOSFET and source of the low side MOSFET as close as possible. Voltage rating of the capacitor must be higher than normal input voltage level. 25 V rating or higher capacitor is preferred for 19 V - 20 V input voltage. Minimum 4 - 6 pcs of 10- $\mu$ F 0805 size capacitor is suggested for 45 - 65 W adapter design.

Ceramic capacitors show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the input capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high input voltages and small capacitor packages. See the manufacturer's datasheet about the performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required value at the operating point.

### 9.2.2.5 Output Capacitor

Output capacitor also should have enough ripple current rating to absorb output switching ripple current. In buck mode the output capacitor RMS current is given:

To get good loop stability, the resonant frequency of the output inductor and output capacitor should be designed between 10 kHz and 20 kHz. The preferred ceramic capacitor is 25-V X7R or X5R for output capacitor. Minimum 6 pcs of 10- $\mu$ F 0805 size capacitor is suggested to be placed by the inductor. Place the capacitors after Q4 drain. Place minimum 10  $\mu$ F after the charge current sense resistor for best stability.

Ceramic capacitors show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the output capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high output voltages and small capacitor packages. See the manufacturer's data sheet about the performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required value at the operating point.

### 9.2.2.6 Power MOSFETs Selection

Four external N-channel MOSFETs are used for a synchronous switching battery charger. The gate drivers are internally integrated into the IC with 6 V of gate drive voltage. 30 V or higher voltage rating MOSFETs are preferred for 19 V - 20 V input voltage.

Figure-of-merit (FOM) is usually used for selecting proper MOSFET based on a tradeoff between the conduction loss and switching loss. For the top side MOSFET, FOM is defined as the product of a MOSFET's on-resistance,  $R_{DS(ON)}$ , and the gate-to-drain charge,  $Q_{GD}$ . For the bottom side MOSFET, FOM is defined as the product of the MOSFET's on-resistance,  $R_{DS(ON)}$ , and the total gate charge,  $Q_G$ .

$$FOM_{top} = R_{DS(on)} \times Q_{GD}; FOM_{bottom} = R_{DS(on)} \times Q_G \quad (6)$$

The lower the FOM value, the lower the total power loss. Usually lower  $R_{DS(ON)}$  has higher cost with the same package size.

The top-side MOSFET loss includes conduction loss and switching loss. It is a function of duty cycle ( $D=V_{OUT}/V_{IN}$ ), charging current ( $I_{CHG}$ ), MOSFET's on-resistance ( $R_{DS(ON)}$ ), input voltage ( $V_{IN}$ ), switching frequency ( $f_s$ ), turn on time ( $t_{on}$ ) and turn off time ( $t_{off}$ ):

$$P_{top} = D \times I_{CHG}^2 \times R_{DS(on)} + \frac{1}{2} \times V_{IN} \times I_{CHG} \times (t_{on} + t_{off}) \times f_s \quad (7)$$

The first item represents the conduction loss. Usually MOSFET  $R_{DS(ON)}$  increases by 50% with 100°C junction temperature rise. The second term represents the switching loss. The MOSFET turn-on and turn-off times are given by:

$$t_{on} = \frac{Q_{SW}}{I_{on}}, t_{off} = \frac{Q_{SW}}{I_{off}} \quad (8)$$

where  $Q_{SW}$  is the switching charge,  $I_{on}$  is the turn-on gate driving current and  $I_{off}$  is the turn-off gate driving current. If the switching charge is not given in MOSFET datasheet, it can be estimated by gate-to-drain charge ( $Q_{GD}$ ) and gate-to-source charge ( $Q_{GS}$ ):

$$Q_{SW} = Q_{GD} + \frac{1}{2} \times Q_{GS} \quad (9)$$

Gate driving current can be estimated by REGN voltage ( $V_{REGN}$ ), MOSFET plateau voltage ( $V_{plt}$ ), total turn-on gate resistance ( $R_{on}$ ) and turn-off gate resistance ( $R_{off}$ ) of the gate driver:

$$I_{on} = \frac{V_{REGN} - V_{plf}}{R_{on}}, \quad I_{off} = \frac{V_{plf}}{R_{off}} \quad (10)$$

The conduction loss of the bottom-side MOSFET is calculated with the following equation when it operates in synchronous continuous conduction mode:

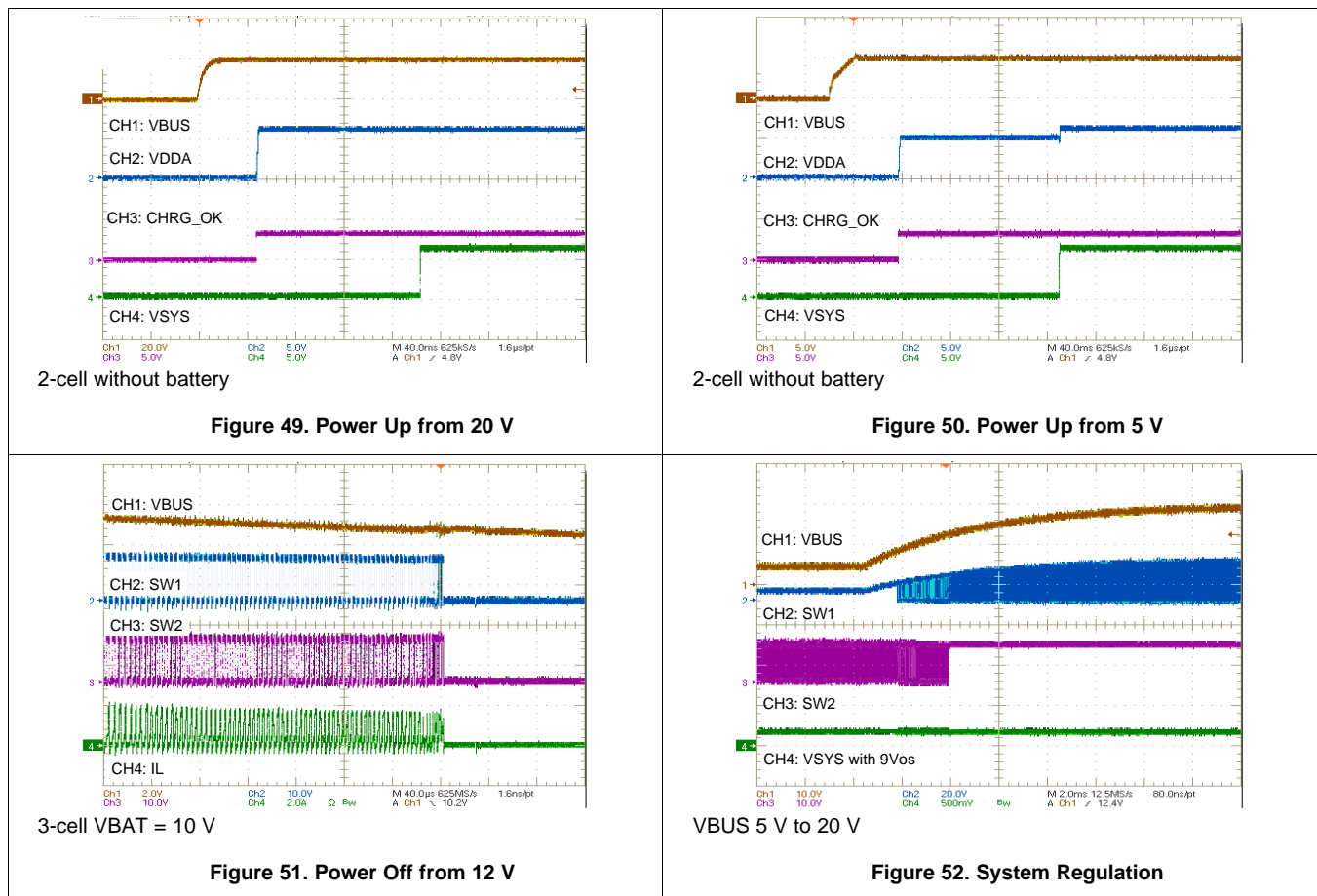
$$P_{bottom} = (1 - D) \times I_{CHG}^2 \times R_{DS(on)} \quad (11)$$

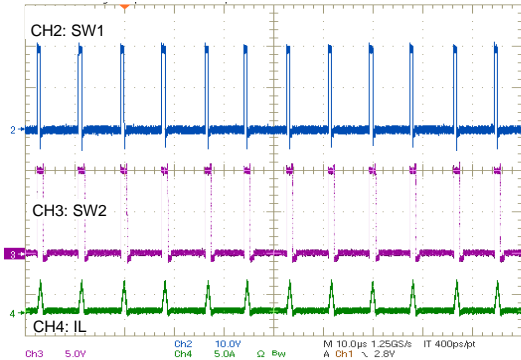
When charger operates in non-synchronous mode, the bottom-side MOSFET is off. As a result all the freewheeling current goes through the body-diode of the bottom-side MOSFET. The body diode power loss depends on its forward voltage drop ( $V_F$ ), non-synchronous mode charging current ( $I_{NONSYNC}$ ), and duty cycle ( $D$ ).

$$P_D = V_F \times I_{NONSYNC} \times (1 - D) \quad (12)$$

The maximum charging current in non-synchronous mode can be up to 0.25 A for a 10-mΩ charging current sensing resistor or 0.5 A if battery voltage is below 2.5 V. The minimum duty cycle happens at lowest battery voltage. Choose the bottom-side MOSFET with either an internal Schottky or body diode capable of carrying the maximum non-synchronous mode charging current.

### 9.2.3 Application Curves





VBUS = 20 V, VSYS = 10 V, ISYS = 200 mA

Figure 53. PFM Operation

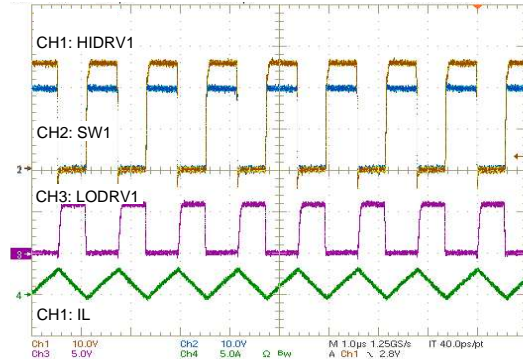
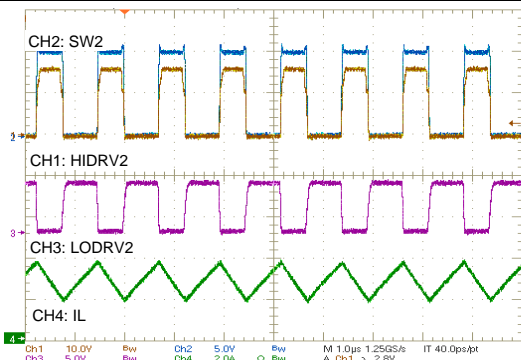
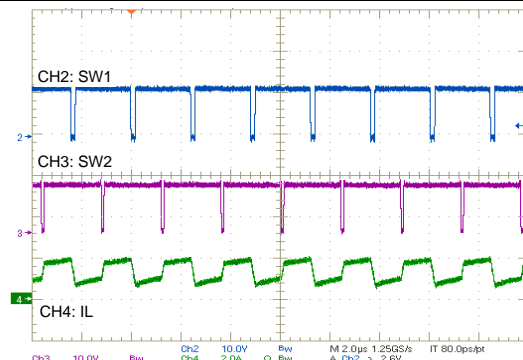


Figure 54. PWM Operation



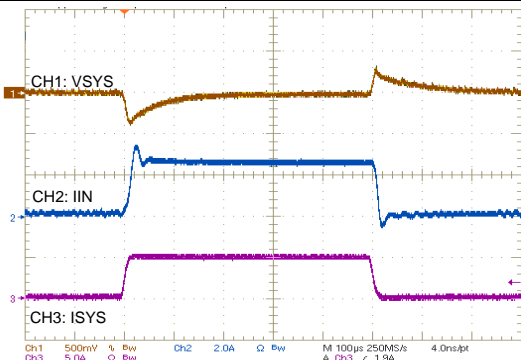
VBUS = 5 V, VBAT = 10 V

Figure 55. Switching During Boost Mode



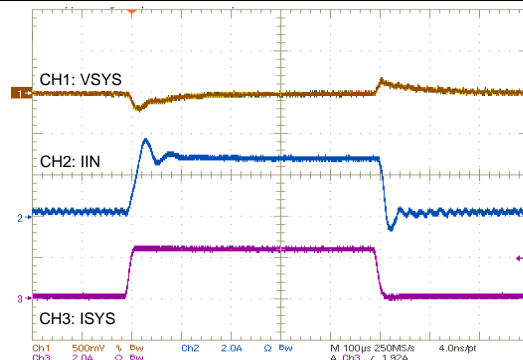
VBUS = 12 V, VBAT = 12 V

Figure 56. Switching During Buck Boost Mode



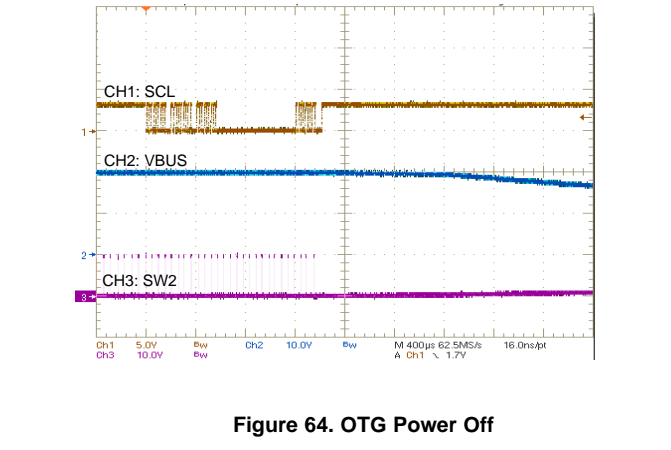
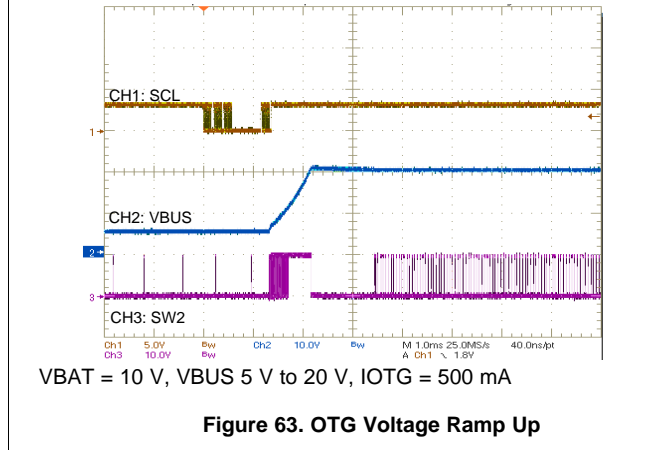
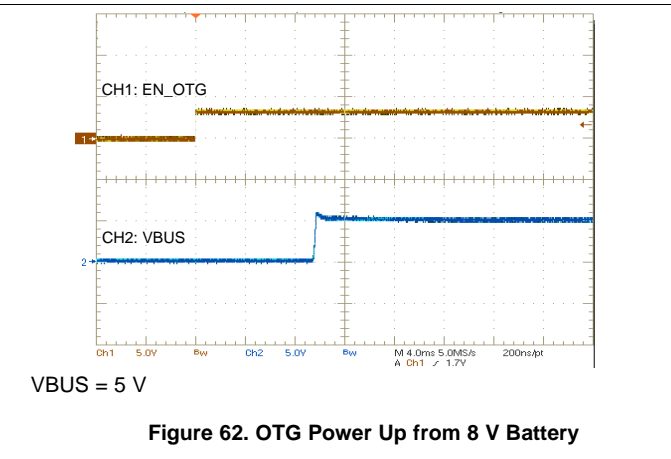
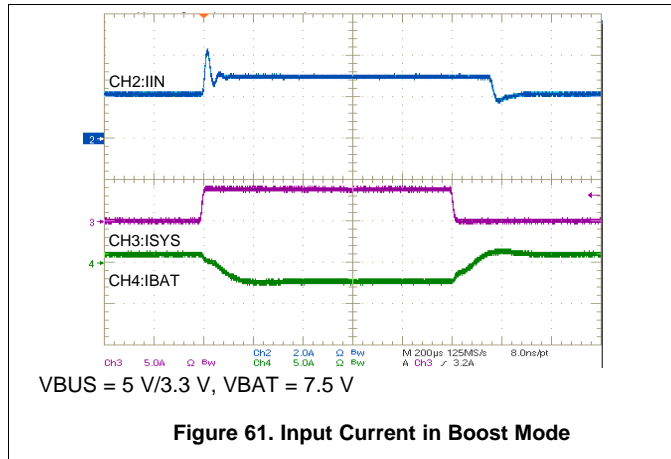
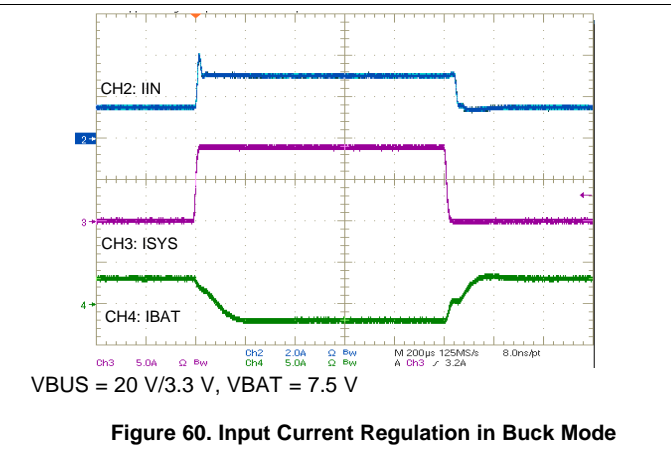
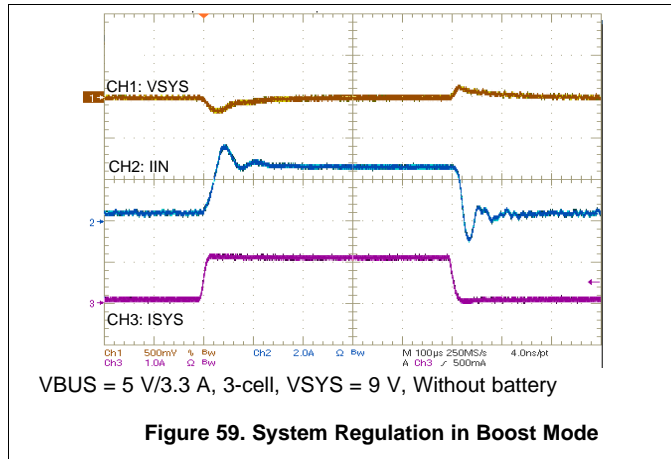
VBUS = 12 V/3.3 A, 3-cell, VSYS = 9 V, Without battery

Figure 57. System Regulation in Buck Mode

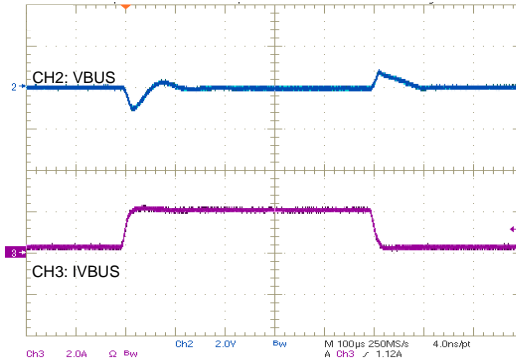


VBUS = 9 V/3.3 A, 3-cell, VSYS = 9 V, Without battery

Figure 58. System Regulation in Buck Boost Mode







VBAT = 10 V, VBUS = 20 V

Figure 65. OTG Load Transient

## 10 Power Supply Recommendations

The valid adapter range is from 3.5 V ( $V_{V_{BUS\_CONVEN}}$ ) to 24 V (ACOV) with at least 500-mA current rating. When CHRG\_OK goes HIGH, the system is powered from adapter through the charger. When adapter is removed, the system is connected to battery through BATFET. Typically the battery depletion threshold should be greater than the minimum system voltage so that the battery capacity can be fully utilized for maximum battery life.

## 11 Layout

### 11.1 Layout Guidelines

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high frequency current path loop (see [Layout Example](#) section) is important to prevent electrical and magnetic field radiation and high frequency resonant problems. Here is a PCB layout priority list for proper layout. Layout PCB according to this specific order is essential.

1. Place the input capacitor as close as possible to the supply of the switching MOSFET and ground connections. Use a short copper trace connection. These parts must be placed on the same layer of PCB using vias to make this connection.
2. The device must be placed close to the gate pins of the switching MOSFET. Keep the gate drive signal traces short for a clean MOSFET drive. The device can be placed on the other side of the PCB of switching MOSFETs.
3. Place an inductor input pin as close as possible to the output pin of the switching MOSFET. Minimize the copper area of this trace to lower electrical and magnetic field radiation but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
4. The charging current sensing resistor should be placed right next to the inductor output. Route the sense leads connected across the sensing resistor back to the device in same layer, close to each other (minimize loop area) and do not route the sense leads through a high-current path (see [Figure 67](#) for Kelvin connection for best current accuracy). Place a decoupling capacitor on these traces next to the device.
5. Place an output capacitor next to the sensing resistor output and ground.
6. Output capacitor ground connections must be tied to the same copper that connects to the input capacitor ground before connecting to system ground.
7. Use a single ground connection to tie the charger power ground to the charger analog ground. Just beneath the device, use analog ground copper pour but avoid power pins to reduce inductive and capacitive noise coupling.
8. Route analog ground separately from power ground. Connect analog ground and connect power ground separately. Connect analog ground and power ground together using power pad as the single ground connection point. Or using a 0-Ω resistor to tie analog ground to power ground (power pad should tie to analog ground in this case if possible).
9. Decoupling capacitors must be placed next to the device pins. Make trace connection as short as possible.
10. It is critical that the exposed power pad on the backside of the device package be soldered to the PCB ground.
11. The via size and number should be enough for a given current path. See the EVM design ([SLUUBG6](#)) for the recommended component placement with trace and via locations. For WQFN information, see [SLUA271](#).

### 11.2 Layout Example

#### 11.2.1 Layout Consideration of Current Path

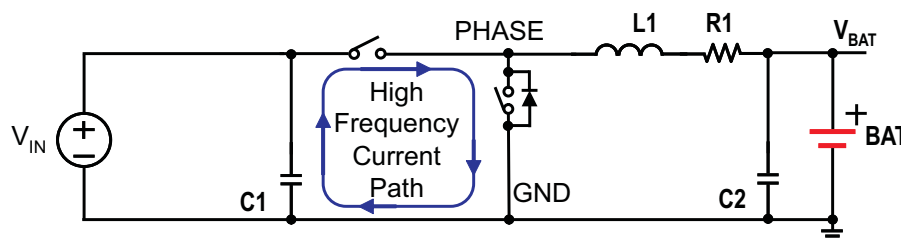
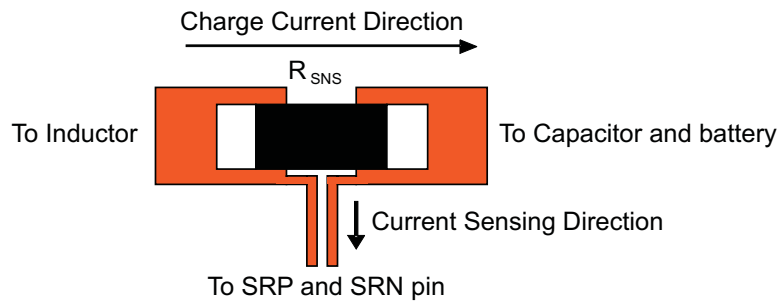


Figure 66. High Frequency Current Path

**Layout Example (continued)**

**11.2.2 Layout Consideration of Short Circuit Protection**



**Figure 67. Sensing Resistor PCB Layout**

## 12 Device and Documentation Support

### 12.1 Device Support

#### 12.1.1 Third-Party Products Disclaimer

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### 12.2 Documentation Support

#### 12.2.1 Related Documentation

For related documentation see the following:

- *Semiconductor and IC Package Thermal Metrics* Application Report [SPRA953](#)
- *bq2570x Evaluation Module* User's Guide [SLUUBG6](#)
- *QFN/SOP PCB Attachment* Application Report [SLUA271](#)

#### 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](http://ti.com). In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 12.4 Community Resources

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#### 12.5 Trademarks

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#### 12.6 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### 12.7 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
BQ25703ARSNR	PREVIEW	QFN	RSN	32	3000	TBD	Call TI	Call TI	-40 to 85		
BQ25703ARSNT	PREVIEW	QFN	RSN	32	250	TBD	Call TI	Call TI	-40 to 85		

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

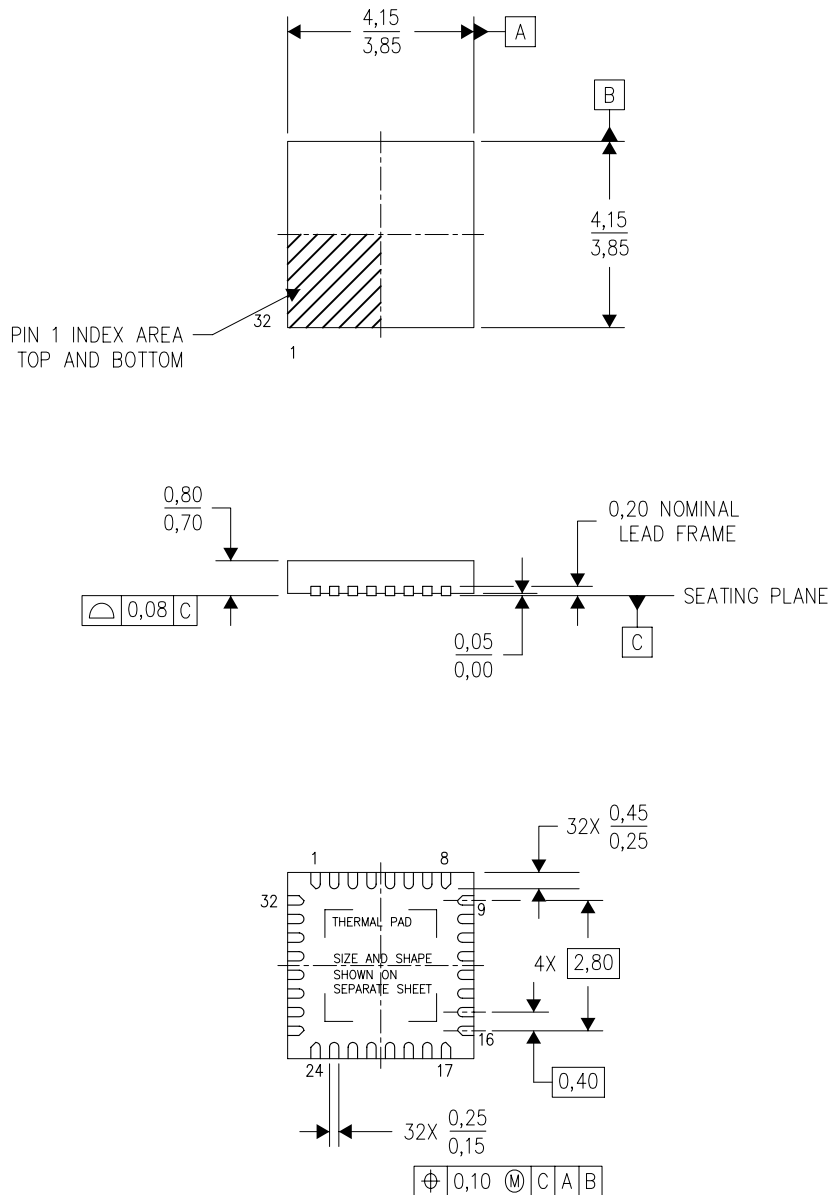
(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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RSN (S-PWQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD



4207561/C 08/11

- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - This drawing is subject to change without notice.
  - QFN (Quad Flatpack No-Lead) Package configuration.
  - The package thermal pad must be soldered to the board for thermal and mechanical performance.
  - See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



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