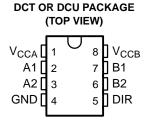
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# SN74AVCH2T45 DUAL-BIT DUAL-SUPPLY BUS TRANSCEIVER WITH CONFIGURABLE VOLTAGE TRANSLATION AND 3-STATE OUTPUTS

SCES582D-JULY 2004-REVISED AUGUST 2005

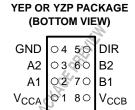
#### **FEATURES**

- Available in the Texas Instruments NanoStar<sup>™</sup> and NanoFree<sup>™</sup> Packages
- Control Inputs V<sub>IH</sub>/V<sub>IL</sub> Levels Are Referenced to V<sub>CCA</sub> Voltage
- Fully Configurable Dual-Rail Design Allows Each Port to Operate Over the Full 1.2-V to 3.6-V Power-Supply Range
- I/Os Are 4.6-V Tolerant
- I<sub>off</sub> Supports Partial-Power-Down Mode Operation
- Bus Hold on Data Inputs Eliminates the Need for External Pullup/Pulldown Resistors



#### Max Data Rates

- 500 Mbps (1.8-V to 3.3-V Translation)
- 320 Mbps (<1.8-V to 3.3-V Translation)
- 320 Mbps (Translate to 2.5 V or 1.8 V)
- 180 Mbps (Translate to 1.5 V)
- 240 Mbps (Translate to 1.2 V)
- Latch-Up Performance Exceeds 100 mA Per JESD 78. Class II
- ESD Protection Exceeds JESD 22
  - 2000-V Human-Body Model (A114-A)
  - 200-V Machine Model (A115-A)
  - 1000-V Charged-Device Model (C101)



### DESCRIPTION/ORDERING INFORMATION

This dual-bit noninverting bus transceiver uses two separate configurable power-supply rails. The SN74AVCH2T45 is optimized to operate with  $V_{CCA}/V_{CCB}$  set at 1.4 V to 3.6 V. It is operational with  $V_{CCA}/V_{CCB}$  as low as 1.2 V. The A port is designed to track  $V_{CCA}$ .  $V_{CCA}$  accepts any supply voltage from 1.2 V to 3.6 V. The B port is designed to track  $V_{CCB}$ .  $V_{CCB}$  accepts any supply voltage from 1.2 V to 3.6 V. This allows for universal low-voltage bidirectional translation between any of the 1.2-V, 1.5-V, 1.8-V, 2.5-V, and 3.3-V voltage nodes.

The SN74AVCH2T45 is designed for asynchronous communication between data buses. The device transmits data from the A bus to the B bus or from the B bus to the A bus, depending on the logic level at the direction-control (DIR) input.

#### ORDERING INFORMATION

T <sub>A</sub>	PACKAGE <sup>(1)</sup>		ORDERABLE PART NUMBER	TOP-SIDE MARKING(2)
	NanoStar™ – WCSP (DSBGA) 0.23-mm Large Bump – YEP	Tone and real	SN74AVCH2T45YEPR <sup>(3)</sup>	
-40°C to 85°C	NanoFree <sup>™</sup> – WCSP (DSBGA) 0.23-mm Large Bump – YZP (Pb-free)	Tape and reel	SN74AVCH2T45YZPR <sup>(3)</sup>	
	SSOP - DCT	Tape and reel	SN74AVCH2T45DCTR	ET2
	VSSOP - DCU	Tape and reel	SN74AVCH2T45DCUR	ET2_

- (1) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.
- (2) DCT: The actual top-side marking has three additional characters that designate the year, month, and assembly/test site. DCU: The actual top-side marking has one additional character that designates the assembly/test site. YEP/YZP: The actual top-side marking has three preceding characters to denote year, month, and sequence code, and one following character to designate the assembly/test site. Pin 1 identifier indicates solder-bump composition (1 = SnPb, = Pb-free).
- (3) Package preview



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

NanoStar, NanoFree are trademarks of Texas Instruments.



### **DESCRIPTION/ORDERING INFORMATION (CONTINUED)**

The SN74AVCH2T45 is designed so that the DIR input is powered by V<sub>CCA</sub>.

This device is fully specified for partial-power-down applications using  $I_{\text{off}}$ . The  $I_{\text{off}}$  circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down.

The  $V_{CC}$  isolation feature ensures that if either  $V_{CC}$  input is at GND, then both outputs are in the high-impedance state. The bus-hold circuitry on the powered-up side always stays active.

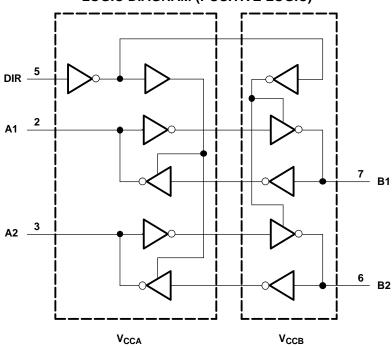
Active bus-hold circuitry holds unused or undriven inputs at a valid logic state. Use of pullup or pulldown resistors with the bus-hold circuitry is not recommended.

NanoStar<sup>™</sup> and NanoFree<sup>™</sup> package technology is a major breakthrough in IC packaging concepts, using the die as the package.

## FUNCTION TABLE (EACH TRANSCEIVER)

INPUT	OPERATION
DIR	OPERATION
L	B data to A bus
Н	A data to B bus

### **LOGIC DIAGRAM (POSITIVE LOGIC)**





SCES582D-JULY 2004-REVISED AUGUST 2005

## Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V <sub>CCA</sub> V <sub>CCB</sub>	Supply voltage range		-0.5	4.6	V
		I/O ports (A port)	-0.5	4.6	
$V_{I}$	Input voltage range (2)	I/O ports (B port)	-0.5	4.6	V
		Control inputs	-0.5	4.6	
W	Voltage range applied to any output	A port	-0.5	4.6	V
$V_O$	in the high-impedance or power-off state (2)	B port	-0.5	4.6	V
.,	V-11	A port	-0.5	V <sub>CCA</sub> + 0.5	1/
$V_{O}$	Voltage range applied to any output in the high or low state (2)(3)	B port	-0.5	$V_{CCB} + 0.5$	V
I <sub>IK</sub>	Input clamp current	V <sub>I</sub> < 0		-50	mA
l <sub>ok</sub>	Output clamp current	V <sub>O</sub> < 0		-50	mA
Io	Continuous output current			±50	mA
	Continuous current through V <sub>CCA</sub> , V <sub>CCB</sub> , or GND			±100	mA
		DCT package		220	
$\theta_{JA}$	Package thermal impedance (4)	DCU package		227	°C/W
		YEP/YZP package		102	
T <sub>stg</sub>	Storage temperature range		-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The input voltage and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

<sup>(3)</sup> The output positive-voltage rating may be exceeded up to 4.6 V maximum if the output current rating is observed.

<sup>(4)</sup> The package thermal impedance is calculated in accordance with JESD 51-7.



SCES582D-JULY 2004-REVISED AUGUST 2005

### Recommended Operating Conditions (1)(2)(3)(4)(5)

			V <sub>CCI</sub>	V <sub>cco</sub>	MIN	MAX	UNIT
$V_{CCA}$	Supply voltage				1.2	3.6	V
V <sub>CCB</sub>	Supply voltage				1.2	3.6	V
			1.2 V to 1.95 V		V <sub>CC</sub> × 0.65		
$V_{IH}$	High-level input voltage	Data inputs <sup>(4)</sup>	1.95 V to 2.7 V		1.6		V
	mpat voltage		2.7 V to 3.6 V		2		
			1.2 V to 1.95 V			$V_{CCI} \times 0.35$	
$V_{IL}$	Low-level input voltage	Data inputs <sup>(4)</sup>	1.95 V to 2.7 V			0.7	V
	mput voltago		2.7 V to 3.6 V			0.8	
			1.2 V to 1.95 V		$V_{\text{CCA}} \times 0.65$		
$V_{IH}$	High-level input voltage	DIR (referenced to V <sub>CCA</sub> ) <sup>(5)</sup>	1.95 V to 2.7 V		1.6		V
	mput voltago	(referenced to VCCA)	2.7 V to 3.6 V		2		
			1.2 V to 1.95 V			$V_{\text{CCA}} \times 0.35$	
$V_{IL}$	Low-level input voltage	DIR (referenced to V <sub>CCA</sub> ) <sup>(5)</sup>	1.95 V to 2.7 V			0.7	V
	mput voltago	(referenced to VCCA)	2.7 V to 3.6 V			0.8	
VI	Input voltage				0	3.6	V
Vo	Output voltage	Active state			0	V <sub>cco</sub>	V
v <sub>O</sub>	Output voltage	3-state			0	3.6	V
				1.2 V		-3	
				1.4 V to 1.6 V		-6	
$I_{OH}$	High-level output cur	rent		1.65 V to 1.95 V		-8	mA
				2.3 V to 2.7 V		-9	
				3 V to 3.6 V		-12	
				1.2 V		3	
				1.4 V to 1.6 V		6	
$I_{OL}$	Low-level output current			1.65 V to 1.95 V		8	mA
				2.3 V to 2.7 V		9	
				3 V to 3.6 V		12	
Δt/Δν	Input transition rise of	or fall rate				5	ns/V
$T_A$	Operating free-air ter	mperature			-40	85	°C

<sup>(1)</sup> V<sub>CCI</sub> is the V<sub>CC</sub> associated with the data input port.
(2) V<sub>CCO</sub> is the V<sub>CC</sub> associated with the output port.
(3) All unused data inputs of the device must be held at V<sub>CCI</sub> or GND to ensure proper device operation. Refer to the TI application report, *Implications of Slow or Floating CMOS Inputs*, literature number SCBA004.
(4) For V<sub>CCI</sub> values not specified in the data sheet, V<sub>IH</sub> min = V<sub>CCI</sub> × 0.7 V, V<sub>IL</sub> max = V<sub>CCI</sub> × 0.3 V.
(5) For V<sub>CCA</sub> values not specified in the data sheet, V<sub>IH</sub> min = V<sub>CCA</sub> × 0.7 V, V<sub>IL</sub> max = V<sub>CCA</sub> × 0.3 V.



SCES582D-JULY 2004-REVISED AUGUST 2005

## Electrical Characteristics (1)(2)

over recommended operating free-air temperature range (unless otherwise noted)

DADAMETED	TEST COMP	ITIONS	V	V	7	Γ <sub>A</sub> = 25°C		–40°C to 85	5°C	UNIT	
PARAMETER	TEST COND	IIIONS	V <sub>CCA</sub>	V <sub>CCB</sub>	MIN	TYP	MAX	MIN	MAX	UNII	
	$I_{OH} = -100 \mu A$		1.2 V to 3.6 V	1.2 V to 3.6 V				V <sub>CCO</sub> - 0.2 V			
	$I_{OH} = -3 \text{ mA}$		1.2 V	1.2 V		0.95					
M	$I_{OH} = -6 \text{ mA}$	$V_{I} = V_{IH}$	1.4 V	1.4 V				1.05		V	
V <sub>OH</sub>	$I_{OH} = -8 \text{ mA}$	$v_I = v_{IH}$	1.65 V	1.65 V				1.2		V	
	$I_{OH} = -9 \text{ mA}$		2.3 V	2.3 V				1.75			
	$I_{OH} = -12 \text{ mA}$		3 V	3 V				2.3			
	I <sub>OL</sub> = 100 μA		1.2 V to 3.6 V	1.2 V to 3.6 V					0.2		
	I <sub>OL</sub> = 3 mA		1.2 V	1.2 V		0.15					
I.V.	$I_{OL} = 6 \text{ mA}$	$V_I = V_{IL}$	1.4 V	1.4 V					0.35	V	
V <sub>OL</sub>	$I_{OL} = 8 \text{ mA}$	$V_{\parallel} = V_{\parallel}$	1.65 V	1.65 V					0.45	V	
	I <sub>OL</sub> = 9 mA		2.3 V	2.3 V					0.55		
	I <sub>OL</sub> = 12 mA		3 V	3 V					0.7		
I <sub>I</sub> DIR input	V <sub>I</sub> = V <sub>CCA</sub> or GN	1D	1.2 V to 3.6 V	1.2 V to 3.6 V		±0.025	±0.25		±1	μΑ	
	V <sub>I</sub> = 0.42 V		1.2 V	1.2 V		25					
	$V_1 = 0.49 \ V$		1.4 V	1.4 V				15			
I <sub>BHL</sub> <sup>(3)</sup>	$V_{I} = 0.58 \text{ V}$		1.65 V	1.65 V				25		μΑ	
	$V_1 = 0.7 \ V$		2.3 V	2.3 V				45			
	V <sub>I</sub> = 0.8 V		3.3 V	3.3 V				100			
	$V_1 = 0.78 \ V$		1.2 V	1.2 V		-25					
	$V_I = 0.91 \ V$		1.4 V	1.4 V				-15			
I <sub>BHH</sub> (4)	V <sub>I</sub> = 1.07 V		1.65 V	1.65 V				-25		μΑ	
	V <sub>I</sub> = 1.6 V		2.3 V	2.3 V				-45			
	V <sub>I</sub> = 2 V		3.3 V	3.3 V				-100			
			1.2 V	1.2 V		50					
			1.6 V	1.6 V				125			
I <sub>BHLO</sub> <sup>(5)</sup>	$V_I = 0$ to $V_{CC}$		1.95 V	1.95 V				200		μΑ	
			2.7 V	2.7 V				300			
			3.6 V	3.6 V				500			
			1.2 V	1.2 V		-50					
			1.6 V	1.6 V				-125			
I <sub>BHHO</sub> <sup>(6)</sup>	$V_I = 0$ to $V_{CC}$		1.95 V	1.95 V				-200		μΑ	
		2.7 V	2.7 V				-300				
			3.6 V	3.6 V			-	-500			

 $V_{CCO}$  is the  $V_{CC}$  associated with the output port.  $V_{CCI}$  is the  $V_{CC}$  associated with the input port. The bus-hold circuit can sink at least the minimum low sustaining current at  $V_{IL}$  max.  $I_{BHL}$  should be measured after lowering  $V_{IN}$  to GND and then raising it to  $V_{\text{IL}}\ \text{max}.$ 

The bus-hold circuit can source at least the minimum high sustaining current at  $V_{IH}$  min.  $I_{BHH}$  should be measured after raising  $V_{IN}$  to  $V_{CC}$  and then lowering it to  $V_{IH}$  min. An external driver must source at least  $I_{BHLO}$  to switch this node from low to high.

An external driver must sink at least I<sub>BHHO</sub> to switch this node from high to low.

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SCES582D-JULY 2004-REVISED AUGUST 2005

### Electrical Characteristics (1)(2)

over recommended operating free-air temperature range (unless otherwise noted) (continued)

DA	RAMETER	TEST CONDITI	ONE	V	V	$T_A = 25^{\circ}$	Č.	–40°C to	85°C	UNIT
PA	KAWEIEK	TEST CONDITI	UNS	V <sub>CCA</sub>	V <sub>CCB</sub>	MIN TYP	MAX	MIN	MAX	UNII
	A port	V or V 0 to 2 6 V		0 V	0 to 3.6 V	±0.1	±1		±5	^
I <sub>off</sub>	B port	$V_I$ or $V_O = 0$ to 3.6 V		0 to 3.6 V	0 V	±0.1	±1		±5	μΑ
loz	A or B port	$V_O = V_{CCO}$ or GND		1.2 V to 3.6 V	1.2 V to 3.6 V	±0.5	±2.5		±5	μΑ
				1.2 V to 3.6 V	1.2 V to 3.6 V				10	
$I_{CCA}$		$V_I = V_{CCI}$ or GND,	$I_O = 0$	0 V	3.6 V				-2	μΑ
				3.6 V	0 V				10	
				1.2 V to 3.6 V	1.2 V to 3.6 V				10	
I <sub>CCB</sub>		$V_I = V_{CCI}$ or GND,	$I_O = 0$	0 V	3.6 V				10	μΑ
				3.6 V	0 V				-2	
I <sub>CCA</sub> +	- I <sub>CCB</sub>	$V_I = V_{CCI}$ or GND,	I <sub>O</sub> = 0	1.2 V to 3.6 V	1.2 V to 3.6 V				20	μΑ
C <sub>i</sub>	Control inputs	V <sub>I</sub> = 3.3 V or GND		3.3 V	3.3 V	2.5				pF
C <sub>io</sub>	A or B port	$V_O = 3.3 \text{ V or GND}$		3.3 V	3.3 V	6				pF

 $<sup>\</sup>begin{array}{ll} \hbox{(1)} & V_{CCO} \text{ is the } V_{CC} \text{ associated with the output port.} \\ \hbox{(2)} & V_{CCI} \text{ is the } V_{CC} \text{ associated with the input port.} \\ \end{array}$ 

### **Switching Characteristics**

over recommended operating free-air temperature range,  $V_{CCA} = 1.2 \text{ V}$  (see Figure 11)

PARAMETER	FROM	то	V <sub>CCB</sub> = 1.2 V	V <sub>CCB</sub> = 1.5 V	V <sub>CCB</sub> = 1.8 V	V <sub>CCB</sub> = 2.5 V	V <sub>CCB</sub> = 3.3 V	UNIT	
PARAMETER	(INPUT)	(OUTPUT)	TYP	TYP	TYP	TYP	TYP	UNII	
t <sub>PLH</sub>	А	В	3.1	2.6	2.4	2.2	2.2	20	
t <sub>PHL</sub>	A	Б	3.1	2.6	2.4	2.2	2.2	ns	
t <sub>PLH</sub>	В	Α	3.4	3.1	3	2.9	2.9	20	
t <sub>PHL</sub>	Ь	A	3.4	3.1	3	2.9	2.9	ns	
t <sub>PHZ</sub>	DIR	Α	5.2	5.2	5.1	5	4.8	20	
$t_{PLZ}$	DIK	JIR A	5.2	5.2	5.1	5	4.8	ns	
t <sub>PHZ</sub>	DIR	В	5	4	3.8	2.8	3.2	20	
t <sub>PLZ</sub>	DIK	В	5	4	3.8	2.8	3.2	ns	
t <sub>PZH</sub> <sup>(1)</sup>	DIR	Α	8.4	7.1	6.8	5.7	6.1	20	
t <sub>PZL</sub> <sup>(1)</sup>	DIK	A	8.4	7.1	6.8	5.7	6.1	ns	
t <sub>PZH</sub> <sup>(1)</sup>	DIB	DIR B	D D	8.3	7.8	7.5	7.2	7	20
t <sub>PZL</sub> <sup>(1)</sup>	אוט		8.3	7.8	7.5	7.2	7	ns	

<sup>(1)</sup> The enable time is a calculated value derived using the formula shown in the enable times section.

SCES582D-JULY 2004-REVISED AUGUST 2005

### **Switching Characteristics**

over recommended operating free-air temperature range,  $V_{\text{CCA}}$  = 1.5 V  $\pm$  0.1 V (see Figure 11)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	V <sub>CCB</sub> = 1.2 V	V <sub>CCB</sub> = ± 0.1	1.5 V I V	V <sub>CCB</sub> = ± 0.1		V <sub>CCB</sub> = ± 0.2		V <sub>CCB</sub> = ± 0.		UNIT																		
	(INFOT)	(0011 01)	TYP	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX																			
t <sub>PLH</sub>	Α	В	2.8	0.7	5.4	0.5	4.6	0.4	3.7	0.3	3.5	20																		
t <sub>PHL</sub>	A	Б	2.8	0.7	5.4	0.5	4.6	0.4	3.7	0.3	3.5	ns																		
t <sub>PLH</sub>	В	А	2.7	0.8	5.4	0.7	5.2	0.6	4.9	0.5	4.7	20																		
t <sub>PHL</sub>	В	В	A	2.7	0.8	5.4	0.7	5.2	0.6	4.9	0.5	4.7	ns																	
t <sub>PHZ</sub>	DIR	^	3.9	1.3	8.5	1.3	7.1	1.1	5.5	1.4	4.6																			
t <sub>PLZ</sub>	DIK	A A	3.9	1.3	8.5	1.3	7.1	1.1	5.5	1.4	4.6	ns																		
t <sub>PHZ</sub>	DIR	В	4.7	1.1	7	1.4	6.9	1.2	6.9	1.7	7.1	20																		
t <sub>PLZ</sub>	DIK	В	4.7	1.1	7	1.4	6.9	1.2	6.9	1.7	7.1	ns																		
t <sub>PZH</sub> <sup>(1)</sup>	DIR	DIB	NIP	DIP	DIP	^	7.4		12.4		12.1		11.8		11.8	20														
t <sub>PZL</sub> <sup>(1)</sup>		Α	7.4		12.4		12.1		11.8		11.8	ns																		
t <sub>PZH</sub> <sup>(1)</sup>	DIR	В	Б	DID D	6.7		13.9		11.6		9.1		7.8	20																
t <sub>PZL</sub> <sup>(1)</sup>		DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	В	6.7		13.9		11.6		9.1		7.8

<sup>(1)</sup> The enable time is a calculated value derived using the formula shown in the *enable times* section.

### **Switching Characteristics**

over recommended operating free-air temperature range,  $V_{\text{CCA}}$  = 1.8 V  $\pm$  0.15 V (see Figure 11)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	V <sub>CCB</sub> = 1.2 V	V <sub>CCB</sub> = ± 0.1		V <sub>CCB</sub> = ± 0.7	: 1.8 V I5 V	V <sub>CCB</sub> = ± 0.2		V <sub>CCB</sub> = ± 0.3		UNIT												
	(INPUT)	(OUTFUT)	TYP	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX													
t <sub>PLH</sub>	А	В	2.7	0.5	5.2	0.4	4.3	0.2	3.4	0.2	3.1	20												
t <sub>PHL</sub>	A	Б	2.7	0.5	5.2	0.4	4.3	0.2	3.4	0.2	3.1	ns												
t <sub>PLH</sub>	В	Α	2.4	0.7	4.7	0.5	4.4	0.5	4	0.4	3.8	20												
t <sub>PHL</sub>	В	ь	D	A	2.4	0.7	4.7	0.5	4.4	0.5	4	0.4	3.8	ns										
t <sub>PHZ</sub>	DIR	DIR	Α	3.7	1.3	8.1	0.7	6.9	1.4	5.3	1.1	4.5	20											
t <sub>PLZ</sub>		A	3.7	1.3	8.1	0.7	6.9	1.4	5.3	1.1	4.5	ns												
t <sub>PHZ</sub>	DIR	В	4.4	1.3	5.8	1.3	5.9	0.8	5.7	1.5	5.9													
t <sub>PLZ</sub>	DIK	Б	4.4	1.3	5.8	1.3	5.9	0.8	5.7	1.5	5.9	ns												
t <sub>PZH</sub> <sup>(1)</sup>	DIR	DIP	DIP	DID	DID	DID	DID	6.8		10.4		10.3		9.7		9.7								
t <sub>PZL</sub> <sup>(1)</sup>		Α	6.8		10.4		10.3		9.7		9.7	ns												
t <sub>PZH</sub> <sup>(1)</sup>	DIR	В	6.4		13.3		11.2		8.6		7.4	20												
t <sub>PZL</sub> <sup>(1)</sup>		DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	D	6.4		13.3		11.2		8.6		7.4

<sup>(1)</sup> The enable time is a calculated value derived using the formula shown in the enable times section.

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SCES582D-JULY 2004-REVISED AUGUST 2005

### **Switching Characteristics**

over recommended operating free-air temperature range,  $V_{CCA}$  = 2.5 V  $\pm$  0.2 V (see Figure 11)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	V <sub>CCB</sub> = 1.2 V	V <sub>CCB</sub> = ± 0.1		V <sub>CCB</sub> = ± 0.1		V <sub>CCB</sub> = ± 0.2		V <sub>CCB</sub> = 3.3 V ± 0.3 V		UNIT																		
	(INPUI)	(001701)	TYP	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX																			
t <sub>PLH</sub>	А	В	2.6	0.4	4.9	0.2	4	0.2	3	0.2	2.6	ns																		
t <sub>PHL</sub>	A	В	2.6	0.4	4.9	0.2	4	0.2	3	0.2	2.6	110																		
t <sub>PLH</sub>	В	А	2.1	0.6	3.8	0.5	3.4	0.4	3	0.3	2.8	ns																		
t <sub>PHL</sub>	D		A	2.1	0.6	3.8	0.5	3.4	0.4	3	0.3	2.8	110																	
t <sub>PHZ</sub>	DIR	А	2.4	0.7	7.9	0.8	6.4	0.8	5	0.5	4.3	20																		
t <sub>PLZ</sub>	DIK	A	2.4	0.7	7.9	0.8	6.4	0.8	5	0.5	4.3	ns																		
t <sub>PHZ</sub>	DIR	В	3.8	1	4.3	0.6	4.3	0.5	4.2	1.1	4.1	ns																		
$t_{PLZ}$	DIK	В	3.8	1	4.3	0.6	4.3	0.5	4.2	1.1	4.1	110																		
t <sub>PZH</sub> <sup>(1)</sup>	DIP	^	5.9		7.9		7.7		7.2		6.9	ns																		
t <sub>PZL</sub> <sup>(1)</sup>	DIR	A	5.9		7.9		7.7		7.2		6.9	115																		
t <sub>PZH</sub> <sup>(1)</sup>	DIR	D	5		12.8		10.4		7.9		6.8	20																		
t <sub>PZL</sub> <sup>(1)</sup>		DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	DIR	IR B	5		12.8		10.4		7.9		6.8

<sup>(1)</sup> The enable time is a calculated value derived using the formula shown in the *enable times* section.

### **Switching Characteristics**

over recommended operating free-air temperature range,  $V_{CCA}$  = 3.3 V  $\pm$  0.3 V (see Figure 11)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	V <sub>CCB</sub> = 1.2 V	V <sub>CCB</sub> = 1.5 V ± 0.1 V		V <sub>CCB</sub> = ± 0.1	1.8 V 5 V	V <sub>CCB</sub> = ± 0.2		V <sub>CCB</sub> = 3.3 V ± 0.3 V		UNIT		
	(INFOT)	(001701)	TYP	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX			
t <sub>PLH</sub>	Α	В	2.5	0.3	4.7	0.2	3.8	0.2	2.8	0.2	2.4	ns		
t <sub>PHL</sub>	A	Ь	2.5	0.3	4.7	0.2	3.8	0.2	2.8	0.2	2.4	115		
t <sub>PLH</sub>	В	А	2.1	0.6	3.6	0.4	3.1	0.3	2.6	0.3	2.4	20		
t <sub>PHL</sub>	В	A	2.1	0.6	3.6	0.4	3.1	0.3	2.6	0.3	2.4	ns		
t <sub>PHZ</sub>	DIR	Α	2.9	1.1	8	1	6.5	1.3	4.7	1.2	4	ns		
t <sub>PLZ</sub>	DIK	A	2.9	1.1	8	1	6.5	1.3	4.7	1.2	4	115		
t <sub>PHZ</sub>	DIR	В	3.4	0.5	6.6	0.3	5.6	0.3	4.6	1.1	3.5	20		
t <sub>PLZ</sub>	DIK	Ь	3.4	0.5	6.6	0.3	5.6	0.3	4.6	1.1	3.5	ns		
t <sub>PZH</sub> <sup>(1)</sup>	DIB	۸	5.5		6.9		6.6		6.2		5.9	20		
t <sub>PZL</sub> <sup>(1)</sup>	DIR	Α	5.5		6.9		6.6		6.2		5.9	ns		
t <sub>PZH</sub> <sup>(1)</sup>	DID	В	5.4		12.7		10.3		7.4		6.3	no		
t <sub>PZL</sub> <sup>(1)</sup>	DIR	DIR	В	DIR B	5.4		12.7		10.3		7.4		6.3	ns

<sup>(1)</sup> The enable time is a calculated value derived using the formula shown in the enable times section.



SCES582D-JULY 2004-REVISED AUGUST 2005

### **Operating Characteristics**

 $T_A = 25^{\circ}C$ 

P	ARAMETER	TEST CONDITIONS	V <sub>CCA</sub> = V <sub>CCB</sub> = 1.2 V	V <sub>CCA</sub> = V <sub>CCB</sub> = 1.5 V	V <sub>CCA</sub> = V <sub>CCB</sub> = 1.8 V	V <sub>CCA</sub> = V <sub>CCB</sub> = 2.5 V	V <sub>CCA</sub> = V <sub>CCB</sub> = 3.3 V	UNIT
		CONDINONO	TYP	TYP	TYP	TYP	TYP	
C (1)	A-port input, B-port output	$C_L = 0,$	3	3	3	3	4	pF
B-port input, A-port output	$f = 10 \text{ MHz},$ $t_r = t_f = 1 \text{ ns}$	13	13	14	15	15	рг	
C (1)	A-port input, B-port output	$C_L = 0,$ f = 10 MHz,	13	13	14	15	15	pF
C <sub>pdB</sub> <sup>(1)</sup>	B-port input, A-port output	$t_r = t_f = 1 \text{ ns}$	3	3	3	3	4	рΓ

(1) Power dissipation capacitance per transceiver

### **POWER-UP CONSIDERATIONS**

A proper power-up sequence always should be followed to avoid excessive supply current, bus contention, oscillations, or other anomalies. To guard against such power-up problems, take the following precautions:

- 1. Connect ground before any supply voltage is applied.
- 2. Power up V<sub>CCA</sub>.
- 3.  $V_{CCB}$  can be ramped up along with or after  $V_{CCA}$ .

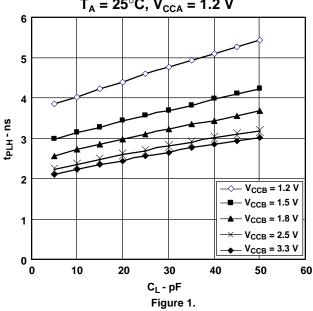
Table 1. Typical Total Static Power Consumption (I<sub>CCA</sub> + I<sub>CCB</sub>)

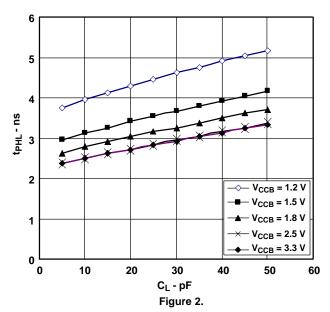
V <sub>CCB</sub>	V <sub>CCA</sub>							
	0 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	UNIT	
0 V	0	<0.5	<0.5	<0.5	<0.5	<0.5		
1.2 V	<0.5	<1	<1	<1	<1	1		
1.5 V	<0.5	<1	<1	<1	<1	1	^	
1.8 V	<0.5	<1	<1	<1	<1	<1	μΑ	
2.5 V	<0.5	1	<1	<1	<1	<1		
3.3 V	<0.5	1	<1	<1	<1	<1		



### **TYPICAL CHARACTERISTICS**

# TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE $T_{\text{A}}$ = 25°C, $V_{\text{CCA}}$ = 1.2 V

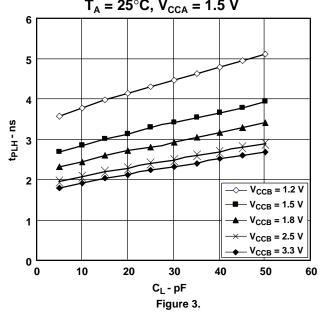


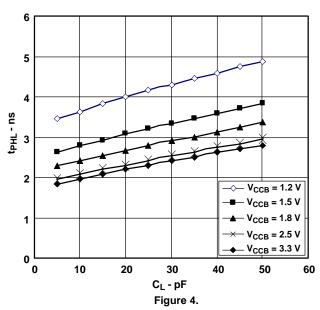




### **TYPICAL CHARACTERISTICS**

## TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE $T_{\rm A}$ = 25°C, $V_{\rm CCA}$ = 1.5 V

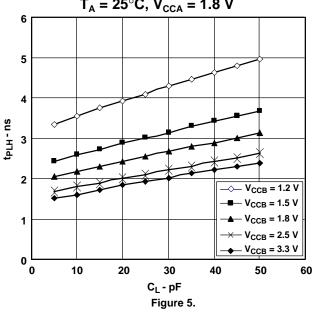


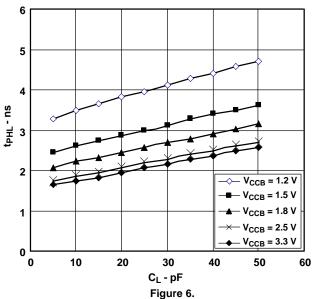




### **TYPICAL CHARACTERISTICS**

# TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE $T_{\rm A}$ = 25°C, $V_{\rm CCA}$ = 1.8 V

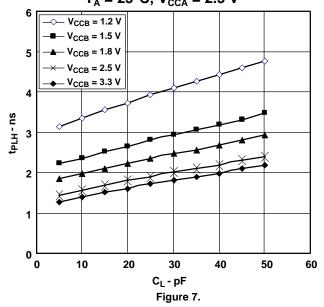


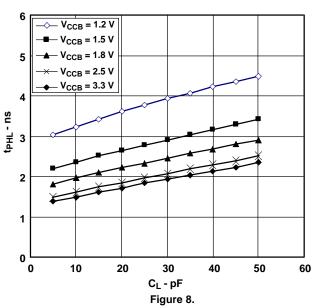




### **TYPICAL CHARACTERISTICS**

# TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE $T_{\text{A}}$ = 25°C, $V_{\text{CCA}}$ = 2.5 V

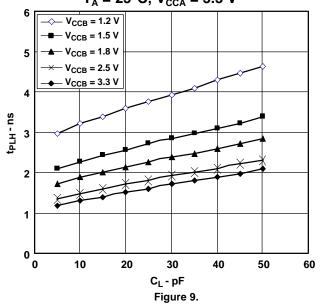


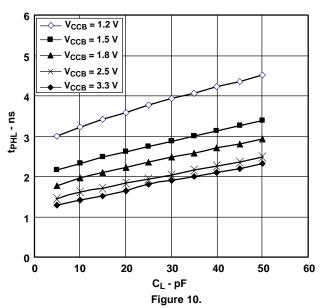




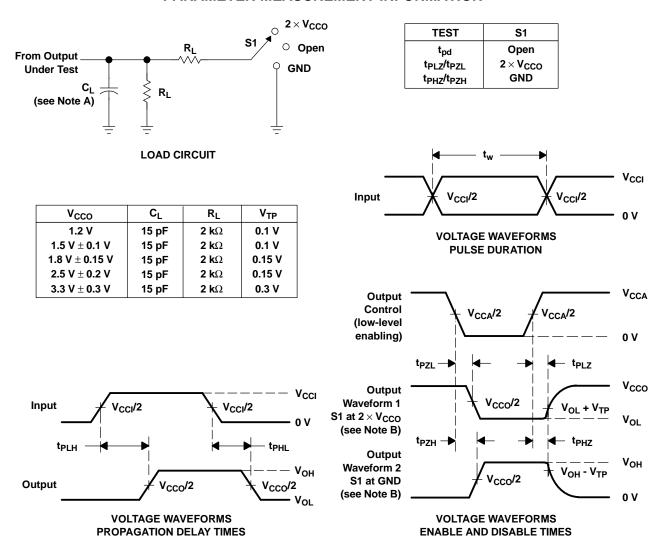
### **TYPICAL CHARACTERISTICS**

# TYPICAL PROPAGATION DELAY (A to B) vs LOAD CAPACITANCE $T_{\text{A}}$ = 25°C, $V_{\text{CCA}}$ = 3.3 V





### PARAMETER MEASUREMENT INFORMATION



NOTES: A. C<sub>L</sub> includes probe and jig capacitance.

- B. Waveform 1 is for an output with internal conditions such that the output is low, except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high, except when disabled by the output control.
- C. All input pulses are supplied by generators having the following characteristics:  $PRR \le 10 \text{ MHz}$ ,  $Z_0 = 50 \Omega$ ,  $dv/dt \ge 1 \text{ V/ns}$ .
- D. The outputs are measured one at a time, with one transition per measurement.
- E.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .
- F.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .
- G. t<sub>PLH</sub> and t<sub>PHL</sub> are the same as t<sub>pd</sub>.
- H.  $V_{CCI}$  is the  $V_{CC}$  associated with the input port.
- I.  $V_{CCO}$  is the  $V_{CC}$  associated with the output port.

Figure 11. Load Circuit and Voltage Waveforms



### **APPLICATION INFORMATION**

Figure 12 is an example of the SN74AVCH2T45 circuit used in a bidirectional logic level-shifting application.

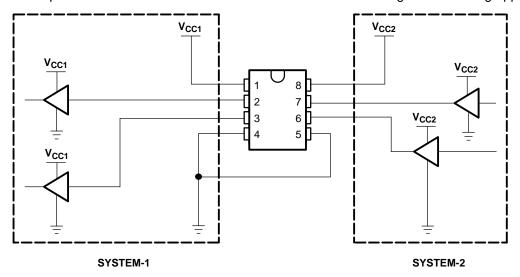


Figure 12. Bidirectional Logic Level-Shifting Application

	_		<b>.</b>		
PIN NAME		FUNCTION	DESCRIPTION		
1	V <sub>CCA</sub>	V <sub>CC1</sub>	SYSTEM-1 supply voltage (1.2 V to 3.6 V)		
2	A1	OUT1	Output level depends on V <sub>CC1</sub> voltage.		
3	A2	OUT2	Output level depends on V <sub>CC1</sub> voltage.		
4	GND	GND	Device GND		
5	DIR	DIR	GND (low level) determines B-port to A-port direction.		
6	B2	IN2	Input threshold value depends on V <sub>CC2</sub> voltage.		
7	B1	IN1	Input threshold value depends on V <sub>CC2</sub> voltage.		
8	V <sub>CCB</sub>	V <sub>CC2</sub>	SYSTEM-2 supply voltage (1.2 V to 3.6 V)		

### **APPLICATION INFORMATION**

Figure 13 shows the SN74AVCH2T45 used in a bidirectional logic level-shifting application. Since the SN74AVCH2T45 does not have an output-enable (OE) pin, system designers should take precautions to avoid bus contention between SYSTEM-1 and SYSTEM-2 when changing directions.

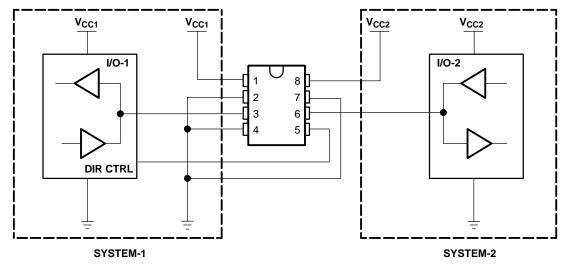


Figure 13. Bidirectional Logic Level-Shifting Application

Following is a sequence that shows data transmission from SYSTEM-1 to SYSTEM-2 and then from SYSTEM-2 to SYSTEM-1.

STATE	DIR CTRL	I/O-1	I/O-2	DESCRIPTION
1	Н	Out	In	SYSTEM-1 data to SYSTEM-2
2	н	Hi-Z	Hi-Z	SYSTEM-2 is getting ready to send data to SYSTEM-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold.
3	L	Hi-Z	Hi-Z	DIR bit is flipped. I/O-1 and I/O-2 still are disabled. The bus-line state depends on bus hold.
4	L	Out	In	SYSTEM-2 data to SYSTEM-1

### **Enable Times**

Calculate the enable times for the SN74AVCH2T45 using the following formulas:

- $t_{PZH}$  (DIR to A) =  $t_{PLZ}$  (DIR to B) +  $t_{PLH}$  (B to A)
- $t_{PZL}$  (DIR to A) =  $t_{PHZ}$  (DIR to B) +  $t_{PHL}$  (B to A)
- $t_{PZH}$  (DIR to B) =  $t_{PLZ}$  (DIR to A) +  $t_{PLH}$  (A to B)
- $t_{PZI}$  (DIR to B) =  $t_{PHZ}$  (DIR to A) +  $t_{PHI}$  (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the SN74AVCH2T45 initially is transmitting from A to B, the DIR bit is switched; the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.





ti.com 7-Feb-2006

### PACKAGING INFORMATION

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
74AVCH2T45DCURE4	ACTIVE	US8	DCU	8	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
74AVCH2T45DCUTE4	ACTIVE	US8	DCU	8	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN74AVCH2T45DCTR	ACTIVE	SM8	DCT	8	3000	Pb-Free (RoHS)	CU NIPDAU	Level-1-260C-UNLIM
SN74AVCH2T45DCTT	ACTIVE	SM8	DCT	8	250	Pb-Free (RoHS)	CU NIPDAU	Level-1-260C-UNLIM
SN74AVCH2T45DCUR	ACTIVE	US8	DCU	8	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN74AVCH2T45DCUT	ACTIVE	US8	DCU	8	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN74AVCH2T45YEPR	PREVIEW	WCSP	YEP	8	3000	TBD	Call TI	Call TI
SN74AVCH2T45YZPR	ACTIVE	WCSP	YZP	8	3000	Pb-Free (RoHS)	SNAGCU	Level-1-260C-UNLIM

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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### DCT (R-PDSO-G8)

### PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion
- D. Falls within JEDEC MO-187 variation DA.

## DCU (R-PDSO-G8)

## PLASTIC SMALL-OUTLINE PACKAGE (DIE DOWN)



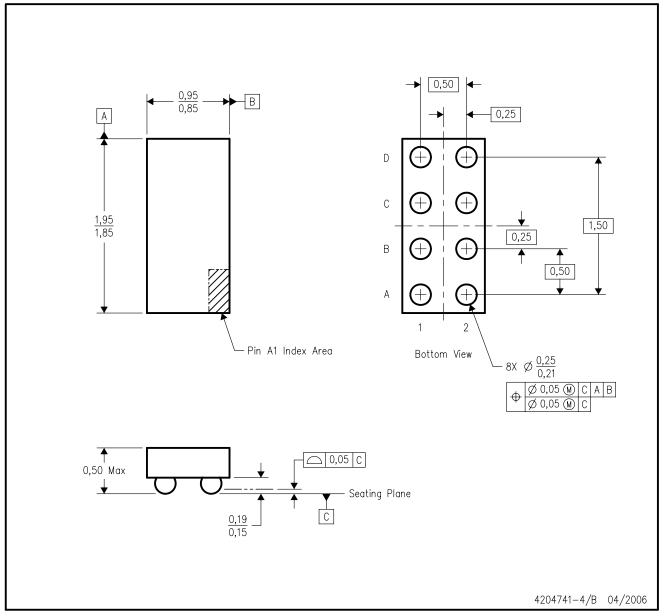
NOTES:

- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
  - D. Falls within JEDEC MO-187 variation CA.



## YZP (R-XBGA-N8)

### DIE-SIZE BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

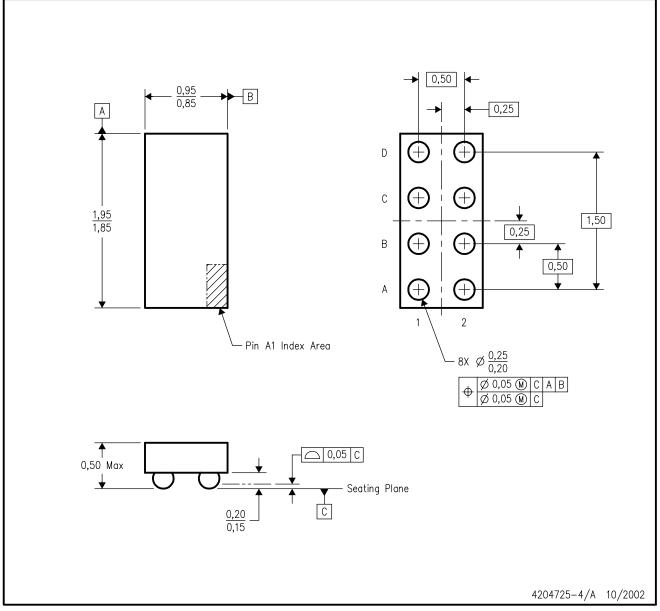
- B. This drawing is subject to change without notice.
- C. NanoFree  $^{\text{TM}}$  package configuration.
- D. This package is lead-free. Refer to the 8 YEP package (drawing 4204725) for tin-lead (SnPb).

NanoFree is a trademark of Texas Instruments.



## YEP (R-XBGA-N8)

### DIE-SIZE BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. NanoStar  $\mathbf{M}$  package configuration.
- D. This package is tin-lead (SnPb). Refer to the 8 YZP package (drawing 4204741) for lead-free.

NanoStar is a trademark of Texas Instruments.



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